Program and Course Structure

Department of Electrical Electronics and Communication Engineering

B.Tech. Electrical and Electronics Engineering SET0404

2019



1. Standard Structure of the Program at University Level

1.1 Vision, Mission and Core Values of the University

Vision of the University

To serve the society by being a global University of higher learning in pursuit of academic excellence, innovation and nurturing entrepreneurship.

Mission of the University

- 1. Transformative educational experience
- 2. Enrichment by educational initiatives that encourage global outlook
- 3. Develop research, support disruptive innovations and accelerate entrepreneurship

Core Values

4. Seeking beyond boundaries

- Integrity
- Leadership
- Diversity
- Community



1.2 Vision and Mission of the School

Vision of the School

To become a globally acclaimed institution of higher learning in engineering and technology promoting excellence in research, innovation and entrepreneurship

Mission of the School

- 1. To impart quality education with strong industry & academic connectivity in the expanding fields of Engineering and Technology in a conductive and enriching learning environment.
- 2. To product technocrats equipped with technical & soft skills and experiential learning required to stay current with the modern tools in emerging technologies to fulfill professional responsibilities and uphold ethical values.
- 3. To inculcate a culture of interdisciplinary research, innovation and entrepreneurship to provide sustainable solutions to meet the growing challenges and societal needs.
- 4. To foster collaborative learning and to play adaptive leadership role in professional career and pursuit of higher education through effective mentoring and counseling.



1.2.1 Vision and Mission of the Department

Vision of the Department of Electrical and Electronics Engineering

To become an internationally acclaimed destination of academic excellence in the discipline of Electrical, Electronics, and Communication Engineering by promoting research, innovation, and entrepreneurship to serve society.

Mission of the Department Electrical and Electronics Engineering

M1-To provide comprehensive technical knowledge in Electrical, Electronics and Communication Engineering.

M2- To facilitate and foster the industry-academia collaboration to enhance technical skills and employability.

M3- To promote interdisciplinary and multi-disciplinary research, innovations and entrepreneurship to serve society.

M4- To develop core values, professional ethics and lifelong learning skills through interactive support systems.



1.3 Programme Educational Objectives (PEO)

1.3.1 Writing Programme Educational Objectives (PEO)

The Educational Objectives of UG Program in Electrical and Electronics Engineering are:

PEO1: The graduates will achieve a reputation as a source of providing innovative solutions for complex engineering problems.

PEO2: The graduates will demonstrate sound engineering knowledge and managerial decisions based on ethical and professional standards.

PEO3: The graduates will work on global technological and environmental issues as a successful entrepreneur.

PEO4: The graduates will pursue higher studies to become successful academicians and lead researchers.



1.3.2 Map PEOs with School Mission Statements:

| No. | PEO statement | School missions | | | |
|-----|-----------------------|-------------------|-------------------|-------------|-------------|
| | | Mission statement | Mission statement | Mission | Mission |
| | | 1 | 2 | statement 3 | statement 4 |
| 1 | The graduates will | 3 | 2 | 2 | 3 |
| | achieve a reputation | | | | |
| | as a source of | | | | |
| | providing innovative | | | | |
| | solutions for complex | | | | |
| | engineering problems. | | | | |
| 2 | PEO2: The graduates | 2 | 3 | 3 | 2 |
| | will demonstrate | | | | |
| | sound engineering | | | | |
| | knowledge and | | | | |
| | managerial decisions | | | | |
| | based on ethical and | | | | |
| | professional | | | | |
| | standards. | | | | |
| 3 | PEO3: The graduates | 2 | 3 | 2 | 3 |
| | will work on global | | | | |
| | technological and | | | | |
| | environmental issues | | | | |
| | as a successful | | | | |
| | entrepreneur. | | | | |
| 4 | PEO4: The graduates | 2 | 3 | 2 | 2 |
| | will pursue higher | | | | |
| | studies to become | | | | |
| | successful | | | | |
| | academicians and lead | | | | |
| | researchers. | | | | |



1.3.2.1 Map PEOs with Department Mission Statements:

| PEOs MISSION STATEMENTS | PEO1: The graduates will achieve a reputation as a source of providing innovative solutions for complex engineering problems. | PEO2: The graduates will demonstrate sound engineering knowledge and managerial decisions based on ethical and professional standards. | PEO3: The graduates will work on global technological and environmental issues as a successful entrepreneur. | PEO4: The graduates will pursue higher studies to become successful academicians and lead researchers. | |
|---|--|---|---|---|--------|
| M1- To provide comprehensive technical knowledge in Electrical, Electronics, and Communication Engineering | 3 | 3 | 3 | 3 | 12/12 |
| M2- To facilitate and foster the industry-academia collaboration to enhance technical skills and employability. | 3 | 3 | 3 | 3 | 12/12 |
| M3- To promote interdisciplinary and multi- disciplinary research, innovations, and entrepreneurship to serve society. | 3 | 2 | 3 | 3 | 11/12 |
| M4-To develop core values, professional ethics, and lifelong learning skills through interactive support systems | 2 | 3 | 2 | 3 | 10/12 |
| | 11/12 | 11/12 | 11/12 | 12/12 | 93.75% |



1. Slight (Low)2. Moderate (Medium)3. Substantial (High)1.3.3 Program Outcomes (PO's)

- PO1: **Engineering knowledge**: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
- PO2: **Problem analysis**: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- PO3: **Design/development of solutions**: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
- PO4: **Conduct investigations of complex problems**: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- PO5: **Modern tool usage**: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.
- PO6: **The engineer and society**: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
- PO7: **Environment and sustainability**: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
- PO8: **Ethics**: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- PO9: **Individual and team work**: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
- PO10: **Communication**: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.



- PO11: **Project management and finance**: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
- PO12: Life-long learning: Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

1.3.4 Program Specific Outcomes (PSO's)

PSO 1: An ability to apply hardware and software based embedded smart solutions for industrial automation and power system

PSO 2: Accentuate the application of cutting-edge technology on renewable energy systems and smart grid

PSO 3: To utilize the knowledge of power systems, automation, robotics and sustainable technology in multidisciplinary research

| Mapping | PEO1 | PEO2 | PEO3 | PEO4 |
|---------|------|------|------|------|
| PO1 | 2 | 2 | 1 | 1 |
| PO2 | 1 | 3 | 1 | 1 |
| PO3 | 3 | 3 | 2 | 2 |
| PO4 | 3 | 2 | 2 | 1 |
| PO5 | 2 | 3 | 1 | - |
| PO6 | 1 | 2 | 3 | 3 |
| PO7 | 2 | 1 | 1 | 3 |
| PO8 | 1 | 1 | 3 | 2 |
| PO9 | 2 | 1 | 3 | 1 |
| PO10 | 1 | 1 | 2 | 3 |
| PO11 | 2 | 2 | 3 | 1 |
| PO12 | 1 | 2 | 2 | - |
| PSO1 | 3 | 1 | 1 | 2 |

1.3.5 Mapping of Program Outcome Vs Program Educational Objectives

| | | | | SHARDA UNIVERSITY |
|------|---|---|---|----------------------|
| PSO2 | 2 | 1 | 1 | 1 |
| PSO3 | 2 | 1 | 1 | 2 |

1. Slight (Low)

2. Moderate (Medium) 3.

Substantial

(High)



1.3.6 The components of the curriculum

| Course Component | Curriculum Content (% of total number of credits of the program) | Total number of contact hours | Total number of credits | | |
|--------------------------|--|----------------------------------|-------------------------|--|--|
| Basic Sciences | 16.25 | 33 | 26 | | |
| Engineering Sciences | 8.125 | 20 | 13 | | |
| Humanities and Social | 11.25 | 29 | 18 | | |
| Program Core | 35 | 72 | 56 | | |
| Program Electives | 11.25 | 18 | 18 | | |
| Open Electives | 6.25 | 10 | 10 | | |
| Project(s) | 11.875 | 40 | 19 | | |
| 272 | | | | | |



Course Structure

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: I

| S. | Course Code | Course | Te | eaching | Load | | Pre-Requisite/Co | | | |
|---------|--------------------|--|----|---------|------|---------|------------------|--|--|--|
| No. | | | L | Т | Р | Credits | Requisite | | | |
| THEO | THEORY SUBJECTS | | | | | | | | | |
| 1. | CSE113 | Programming for Problem Solving | 3 | 0 | 0 | 3 | | | | |
| 2. | HMM126 | Human Values and Ethics | 2 | 0 | 0 | 2 | | | | |
| 3. | MTH141 | Mathematics I | 3 | 1 | 0 | 4 | | | | |
| 4. | PHY117 | Engineering Physics (Semiconductor Physics) | 3 | 1 | 0 | 3 | | | | |
| 5. | CHY111 | Engineering Chemistry | 2 | 1 | 0 | 3 | | | | |
| Practio | cal/Viva-Voce/Jury | | | | | | | | | |
| 6. | ARP101 | Comm. Eng-I | 0 | 0 | 2 | 2 | | | | |
| 7. | CSP113 | Programming for Problem Solving | 0 | 0 | 2 | 1 | | | | |
| 8. | MEP106 | Computer Aided Design & Drafting | 0 | 0 | 3 | 1.5 | | | | |
| 9. | ECP106 | Introduction to Engineering | 0 | 0 | 2 | 1 | | | | |
| 10. | PHY162 | Physics Lab II | 0 | 0 | 2 | 1 | | | | |
| 11. | CHY161 | Engineering Chemistry lab | 0 | 0 | 2 | 1 | | | | |
| | | 22.5 | | | | | | | | |

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: II

| S. | Paper ID | Course Code | Course | Teaching Load | | | | Pre-Requisite/Co |
|---------|--------------|-------------|--|---------------|----------|-------------------------|----------|------------------|
| No. | | | | L | Т | Р | Credits | Requisite |
| ГНЕО | RY SUBJEC | TS | | | | | | 1 |
| 1. | | CSE114 | Application based Programming in Python | 3 | 0 | 0 | 3 | |
| 2. | | MTH143 | Differential Equations, Spec.Transforms and complex variable | 3 | 1 | 0 | 4 | |
| 3. | | PHY118 | Advanced Physics (Electricity and Magnetism) | 2 | 1 | 0 | 3 | |
| 4. | | EEE112 | Principles of Electrical and Electronics Engineering | 3 | 0 | 0 | 3 | |
| 5. | | EVS112 | Environmental Science | 2 | 0 | 0 | 2 | |
| 6. | | ARP102 | Comm. Eng II | 1 | 0 | 2 | 2 | |
| Practio | cal/Viva-Voc | e/Jury | · | | | | · | |
| 7. | | CSP114 | Application based Programming in Python | 0 | 0 | 2 | 1 | |
| 8. | | MEP105 | Mechanical Workshop | 0 | 0 | 3 | 1.5 | |
| 9. | | ECP107 | Tinkering Lab Electrical | 0 | 0 | 2 | 1 | |
| 10. | | PHY161 | Physics Lab | 0 | 0 | 2 | 1 | |
| 11. | | EEP112 | Principles of Electrical and Electronics Engineering lab | 0 | 0 | 2 | 1 | |
| 12. | | | | | | | | |
| | 1 | 1 | TOTAL CREDITS | | | 1 | 22.5 | l |
| | | Note: Indu | strial Internship after completion of 2 nd Semester | and will | be evalu | ated in 3 rd | Semester | 1 |

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: III

| S. | Course | Course | Т | eaching | Load | | Pre-Requisite/Co | | | |
|---------|------------------|---|---|---------|------|---------|------------------|--|--|--|
| No. | Code | | L | Т | Р | Credits | Requisite | | | |
| THEO | THEORY SUBJECTS | | | | | | | | | |
| 1. | HMM305 | Management for Engineers | 3 | 0 | 0 | 3 | | | | |
| 2. | MTH145 | Mathematics III (Probability & Statistics) | 3 | 0 | 0 | 3 | | | | |
| 3. | ECE237 | Analog Circuits-I | 3 | 0 | 0 | 3 | | | | |
| 4. | EEE220 | Network Analysis & Synthesis | 3 | 0 | 0 | 3 | | | | |
| 5. | EEE221 | Electrical Machine-I | 3 | 0 | 0 | 3 | | | | |
| Practic | al/Viva-Voce/J | ury | | | | | | | | |
| 6. | ARP203 | Aptitude Reasoning and Business Communication Skills-Basic | 0 | 0 | 4 | 2 | | | | |
| 7. | MTP145 | Mathematics III (Using MATLAB/ Sci Lab) | 0 | 0 | 2 | 1 | | | | |
| 8. | ECP237 | Analog Electronics -1 Lab | 0 | 0 | 2 | 1 | | | | |
| 9. | EEP221 | Electrical Machine-I Lab | 0 | 0 | 2 | 1 | | | | |
| 10. | EEP251 | Project Based Learning (PBL) -1 | 0 | 0 | 2 | 1 | | | | |
| 11. | EEP294 | Summer Internship | 0 | 0 | 2 | 1 | | | | |
| | TOTAL CREDITS 22 | | | | | | | | | |

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: IV

| S. | Course | Course | Teach | ing Lo | ad | | Pre-Requisite/Co |
|------------|-------------|--|-------|--------|----------|---------|------------------|
| No. | Code | | L | Т | Р | Credits | Requisite |
| THEORY | SUBJECTS | <u> </u> | | | <u> </u> | | |
| 1. | EEE224 | Electrical Macines-II | 3 | 0 | 0 | 3 | |
| 2. | ECE240 | Digital System Design | 3 | 0 | 0 | 3 | |
| 3. | EEE225 | Electrical & Electronic Measurements | 3 | 0 | 0 | 3 | |
| 4. | ECE245 | Microprocessor and Microcontroller with Interfacing | 3 | 0 | 0 | 3 | |
| 5. | BTY 223 | Introduction to Biology for Engineers | 2 | 0 | 0 | 2 | |
| 6. | MOO211 | Wheeled Mobile Robots | 2 | 0 | 0 | 2 | |
| Practical/ | Viva-Voce/J | ury | | | | | |
| 7. | EEP226 | Project Based Learning (PBL) -2 | 0 | 0 | 2 | 1 | |
| 8. | EEP224 | Electrical Macines-II Lab | 0 | 0 | 2 | 1 | |
| 9. | ECP240 | Digital System Design Lab | 0 | 0 | 2 | 1 | |
| 10. | EEP225 | Electrical & Electronic Measurements Lab | 0 | 0 | 2 | 1 | |
| 11. | ECP245 | Microprocessor and Microcontroller with Interfacing Lab | 0 | 0 | 2 | 1 | |
| 12. | ARP204 | Aptitude Reasoning and Business Communication Skills-Intermediate | 0 | 0 | 4 | 2 | |
| | | | TOTAL | CREI | DITS | 23 | |

School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: V

| S. | Course Code | Course | Teaching Load | | | | Pre- | |
|-------|---------------------------------|--|---------------|--------|-------|---------|---------------------------|--|
| No. | | | L | Т | Р | Credits | Requisite/Co Requisite | |
| Theor | y Subjects | | 1 | 1 | 1 | 1 | | |
| 1. | EEE330 | Control Systems | 3 | 0 | 0 | 3 | | |
| 2. | EEE331 | Power System-I | 3 | 0 | 0 | 3 | | |
| 3. | EEE332 | Power Electronics | 3 | 0 | 0 | 3 | | |
| 4. | EEE452 | Wind and Solor Energy | 3 | 0 | 0 | 3 | | |
| 5. | ECE932/BTY320/ MEC333/MEC319 | IoT in smart application/Microbiology /Industry 4.0/Energy Conservation and Management | 3 | 0 | 0 | 3 | | |
| Pract | ical/Viva-Voce | | | | | | | |
| 6. | EEP321 | Control Systems Lab | 0 | 0 | 2 | 1 | | |
| 7. | EEP331 | Power System-I Lab | 0 | 0 | 2 | 1 | | |
| 8 | EEP332 | Power Electronics Lab | 0 | 0 | 2 | 1 | | |
| 9. | EEP337 | Technical Skill Enhancement Course-1 | 0 | 0 | 2 | 1 | | |
| 10. | EEP333 | Project Based Learning (PBL) -3 | 0 | 0 | 2 | 1 | | |
| 11. | ARP301 | Quantitative Aptitude Behavioral and Interpersonal Skills | 0 | 0 | 4 | 2 | | |
| 12. | EEP391 | Summer Internship | 0 | 0 | 2 | 1 | | |
| 13. | ECC301 | Community Connect | 0 | 0 | 4 | 2 | | |
| | | · | TOT | AL CRI | EDITS | 25 | | |



School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: VI

| S. | Course | Course | Te | eaching | Load | | Pre-Requisite/Co | | | | |
|--------|------------------|---|----|---------|------|---------|------------------|--|--|--|--|
| No. | Code | | L | Т | P | Credits | Requisite | | | | |
| THEO | THEORY SUBJECTS | | | | | | | | | | |
| 1. | EEE334 | Switchgear & Protection | 3 | 0 | 0 | 3 | | | | | |
| 2. | EEE335 | Power System-II | 3 | 0 | 0 | 3 | | | | | |
| 3. | EEE442 | Embedded System and Robotics | 3 | 0 | 0 | 3 | | | | | |
| 4. | EEE463 | Optimization Techniques | 3 | 0 | 0 | 3 | | | | | |
| 5. | MOO307 | Computer vision and Image processing- Fundamentals and Application | 3 | 0 | 0 | 3 | | | | | |
| Practi | cal/Viva-Voce | Jury | | | | | | | | | |
| 6. | ARP302 | Higher Order Mathematics and Advanced People Skills | 0 | 0 | 4 | 2 | | | | | |
| 7. | EEP334 | Switchgear & Protection Lab | 0 | 0 | 2 | 1 | | | | | |
| 8. | EEP335 | Power System-II Lab | 0 | 0 | 2 | 1 | | | | | |
| 9. | EEP336 | Project Based Learning (PBL) -4 | 0 | 0 | 2 | 1 | | | | | |
| 10. | EEP339 | Technical Skill Enhancement Course-2 | 0 | 0 | 2 | 1 | | | | | |
| | TOTAL CREDITS 21 | | | | | | | | | | |



School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: VII

| S. | Course | Course | Т | eaching | Load | | Pre-Requisite/Co | | | |
|--------|-----------------|--|---|---------|------|---------|------------------|--|--|--|
| No. | Code | | L | Т | Р | Credits | Requisite | | | |
| THEO | THEORY SUBJECTS | | | | | | | | | |
| 1. | EEE444 | HVDC and Facts | 3 | 0 | 0 | 3 | | | | |
| 2. | EEE448 | PLC and SCADA | 3 | 0 | 0 | 3 | | | | |
| 3. | EEE453 | Wireless Sensor Networks and Applications | 3 | 0 | 0 | 3 | | | | |
| 4. | MOO402 | Introduction to Smart Grid | 2 | 0 | 0 | 2 | | | | |
| Practi | cal/Viva-Voc | e/Jury | | | | | | | | |
| 6. | EEP430 | Major Project- 1 | 0 | 0 | 6 | 3 | | | | |
| 7. | SC22 | Comprehensive Examination | 0 | 0 | 0 | 0 | | | | |
| 9. | EEE431 | Industrial Internship | 0 | 0 | 2 | 1 | | | | |
| 10. | ARP401 | Problem Solving Creative Thinking and Leadership Skills | 0 | 0 | 2 | 1 | | | | |
| | | 16 | | | | | | | | |



School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: VIII

| S. | Course | Course | T | eaching | Load | | Pre-Requisite/Co |
|-----|--------|-------------------|----|---------|-------|---------|------------------|
| No. | Code | | L | Т | Р | Credits | Requisite |
| | | | | | | | |
| 1. | EEP495 | Major Project – 2 | 0 | 0 | 16 | 8 | |
| | • | • | TO | TAL CR | EDITS | 8 | |
| | | | | | | | |



SYLLABUS TERM-I



Programming for problem solving

| Sc | hool: SET | | | |
|----|--------------------------|--|--|---|
| Pr | ogram: B.Tech | | | |
| Br | ranch: ECE | | | |
| Se | mester:1 | | | |
| 1 | Course Code | CSE113 | Course Name: Programming for problem solving | |
| 2 | Course Title | Programmi | ng for problem solving | |
| 3 | Credits | 4 | | |
| 4 | Contact Hours (L-T-P) | 3-0-2 | | |
| | Course Status | Core | | |
| 5 | Course Objective | str 2. lea | earn basic programming constructs –data types ructures, control structures in C arning logic aptitude programming in c langu eveloping software in c programming | |
| 6 | Course Outcomes | CO1: the giv CO2: progra CO3: CO4: strings CO5: CO6: C. | pletion of Course Students will be able to: demonstrate the algorithm, Pseudo-code and to ven problem. develop better understanding of basic concept amming. create and implement logic using array and fu construct and implement the logic based on the s and pointers. apply user-defined data types and I/O operation design and develop solutions to real world pro- | ts of C Inction. The concept of The cons in file. The boblems using |
| 7 | Course Description | | ng for problem solving gives the Understanding of C p code from flowchart or algorithm | rogramming and |
| 8 | Outline syllabus | | | CO Mapping |
| | Unit 1 | Logic Bui | lding | |
| | А | output, Bra | Elements, Identifying and understanding input anching and iteration in flowchart | CO1, |
| | В | Algorithm down/botto | design: Problem solving approach(top om up approach) | CO1 |
| | С | | ode : Representation of different construct, seudo-code from algorithm and flowchart | CO1 |
| | Unit 2 | Introducti | ion to C Programming | |
| | A | | on to C programming language, Data types, Constants, Identifiers and keywords, Storage | CO2 |
| | В | Assignmer | and expressions, Types of Statements: nt, Control, jumping. | CO2 |
| | С | Control sta | atements: Decisions, Loops, break, continue | CO2 |
| | Unit 3 | Arrays an | d Functions | |
| | А | | ne dimensional and multi dimensional arrays: n, Initialization and array manipulation (sorting, | CO3 |
| | В | Functions: | Definition, Declaration/Prototyping and | CO3 |



| | S 2 B e | yond Boundaries |
|---------------------|---|-----------------|
| | Calling, Types of functions, Parameter passing: Call by value, Call by reference. | |
| С | Passing and Returning Arrays from Functions, Recursive Functions. | CO3 |
| Unit 4 | Pre-processors and Pointers | |
| A | Pre-processors: Types, Directives, Pre-processors Operators (#,##,\) , Macros: Types, Use, predefined Macros | CO4, CO6 |
| В | Pointer: Introduction, declaration of pointer variables, Operations on pointers: Pointer arithmetic, Arrays and pointers, Dynamic memory allocation. | CO4 , CO6 |
| С | String: Introduction, predefined string functions, Manipulation of text data, Command Line Arguments. | CO4, CO6 |
| Unit 5 | User Defined Data Types and File Handling | |
| A | Structure and Unions: Introduction, Declaration, Difference, Application, Nested structure, self-referential structure, Array of structures, Passing structure in function. | CO5, CO6 |
| В | Files: Introduction, concept of record, I/O Streaming and Buffering, Types of Files: Indexed file, sequential file and random file, | CO5, CO6 |
| С | Creating a data file, Opening and closing a data file, Various I/O operations on data files: Storing data or records in file, adding records, Retrieving, and updating Sequential file/random file. | CO5, CO6 |
| Mode of examination | Theory | |
| Weightage | CA MTE ETE | |
| Distribution | 30% 20% 50% | |
| Text book/s* | Kernighan, Brian, and Dennis Ritchie. The C Programming Language | |
| Other References | B.S. Gottfried - Programming With C - Schaum's Outline Series - Tata McGraw Hill 3rdEdition .ISBN 9780070145900 E. Balagurusamy - Programming in ANSI C – 8thEdition - Tata McGraw Hill- 2019 | |

CO, PO & PSO MAPPING:



| Cos | PO1 | PO2 | PO3 | P04 | PO5 | P06 | PO7 | PO8 | 909 | PO1 0 | PO1 1 | PO1 2 | PSO 1 | PSO 2 | PSO 3 | |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|----------|----------|----------|----------|--|
| CSE113.1 | 1 | 2 | 1 | - | - | 1 | - | - | - | - | - | - | 1 | 1 | - | |
| CSE113.2 | 2 | - | 2 | - | - | 1 | - | - | - | - | 1 | - | 2 | 2 | - | |
| CSE113.3 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | - | 1 | - | |
| CSE113.4 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | - | 1 | - | |
| CSE113.5 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | - | 1 | - | |
| CSE113.6 | 2 | 2 | 2 | - | - | 2 | - | - | - | - | 1 | - | 2 | 2 | 1 | |
| CSE113 | 1.3 | 2 | 1.3 | | | 1.3 | | | | | 1 | | 1.6 | 1.3 | 1 | |



| C -1 | al Cal1 C | Beyond Boundari | ies |
|------|--------------------------|---|------------------------|
| | ool: School of | | |
| | c Sciences and | | |
| | earch | | |
| | gram: B.TECH . | | |
| Bra | | Semester: II | |
| | C/EC/EEE | | |
| 1 | Course Code | PHY 117 | |
| 2 | Course Title | Semiconductor Physics | |
| 3 | Credits | 4 | |
| 4 | Contact Hours (L-T-P) | 3-1-0 | |
| | Course Status | Compulsory | |
| 5 | Course Objective | To make students proverbial with the fundamental concepts of Semicond materials and their real life applications for configuring various elect devices. | |
| 6 | Course Outcomes | After the completion of this course, | |
| | | CO1: Students will learn the various fundamental theory of material concept of solid classification. | ls and |
| | | CO2: Students will learn the fundamental concepts of mobility, conduct electrons and holes in an intrinsic semiconductors, Donor and Acc impurities (n-type and p-type semiconductor), Fermi levels etc. | |
| | | CO3: Students will gain knowledge about the formation of depletion rebarrier potential, Zener diode, Characteristics of Zener diode etc. | egion, |
| | | CO4: Students will have a clear understanding of Coherent sources, inter of radiation with matter (spontaneous and stimulated emission), Eins relation, population inversion and pumping, etc. | |
| | | CO5: Students will learn the concept of optical sources: Light emitting (construction, basic working principle), semiconductor laser (constructions basic working principle), and optical detectors. | |
| | | CO6: Student will be familiar with the essential concepts of Semicond materials technology and their applications in industries. | uctors |
| 7 | Course Description | This course provides the basic foundation for understanding elect semiconductor devices and their applications and limitations. I introductory elements of various concept of material science. course is essential for students who desire to specialize their engine in Computer Sciences, Electronics, and Electronics and Elec- engineering. | t has This ering |
| 8 | Outline Syllabu | | CO oping |
| | Unit 1 | Physics of Semiconductor | 1 0 |



| | Beyond Bo | undaries |
|------|---|----------|
| A | Introduction, classical free electron theory (Lorentz-Drude theory and limitations), Quantum theory of free electron | CO1, CO6 |
| В | (Fermi energy, effect of temperature on Fermi-Dirac distribution) (qualitative analysis) | CO1 |
| С | Energy bands, Classification of Solids on the basis of energy band. | CO1 |
| Unit | 2 Transport phenomena in semiconductors | |
| A | Mobility, conductivity, electrons and holes in an intrinsic semiconductors, Donor and Acceptor impurities (n-type and p-type semiconductor) | CO2, CO6 |
| В | Fermi levels, carrier densities in semiconductor | CO2 |
| С | Concentration of electrons in conduction band and holes in valence band, Drift and diffusion current, Hall effect. | CO2 |
| Unit | 3 p-n Junction | |
| A | p-n junction, types of p-n junction (step-graded and Linearly- graded junction) | CO3 |
| В | formation of depletion region, barrier potential, Zener diode, Characteristics of Zener diode | CO3 |
| С | Avalanche and Zener breakdown, comparison of Zener diode and pn junction diode, concept of tunneling, I-V characteristics of tunnel diode. | CO3, CO6 |
| Unit | 4 Laser Physics | |
| A | Coherent sources, interaction of radiation with matter (spontaneous and stimulated emission), Einstein's relation | CO4 |
| В | population inversion and pumping, active components of laser, optical amplification or gain | CO4 |
| С | threshold condition for laser action, three and four level lasers, Ruby and He-Ne lasers. | CO4 |
| Unit | 5 Optoelectronic Devices | |
| A | optical sources: Light emitting diode (construction, basic working principle), semiconductor laser (construction, basic working principle) | CO5 |
| В | optical detectors: photodiode (working principle), p-i-n photodiode (working principle), | CO5, CO6 |



| | | | | oundaries |
|------------------------|------------------------------|---|-------------------|-----------|
| С | Photovoltaic effect, p-n jun | ction solar cell (basic | working idea). | CO5, CO6 |
| Mode of Examination | Theory | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 30% | 20% | 50% | |
| Text books | Integrated Electron Hill | nics- Millman - Halk | cias, Tata McGraw | |
| Other References | | vices Physics and Tec s -ISBN: 978-0-470-5 | <i>e.</i> | |
| | 2. Semiconductor De | evice Fundamentals- ongman –ISBN:02015 | Robert F. Pierret | |

CO, PO & PSO MAPPING:

| Cos | PO 1 | PO | PO | PO | PO | PO | PO 7 | PO | PO | PO1 | PO1 | PO1 | PSO | PSO | PSO 2 |
|--------------|---------|-----|-----|-----|-----|-----|---------|-----|-----|-----|-----|-----|-----|-----|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | / | 8 | 9 | 0 | 1 | 2 | 1 | 2 | 3 |
| PHY117. 1 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | - | - | - |
| PHY117. 2 | 3 | 3 | 2 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | |
| PHY117. 3 | 3 | 3 | 2 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - |
| PHY117. 4 | 3 | 3 | 3 | 2 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | |
| PHY117. 5 | 3 | 3 | 3 | 2 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - |
| PHY117. 6 | 3 | 3 | 3 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | |
| PHY117 | 3 | 2.8 | 2.3 | 2.3 | 2.7 | 1.8 | 1.0 | 1.0 | 1.2 | 1.0 | 1.0 | 1.0 | - | - | - |



| Sch | ool: SET | В | eyond Boundaries |
|-----|--------------------------|--|--|
| Pro | gram: B.Tech. | | |
| Bra | nch: ME, EC, | Semester: I | |
| EE, | , CE | | |
| 1 | Course Code | MTH 141 | |
| 2 | Course Title | CALCULUS, ANALYSIS AND LINEAR ALGEBRA | |
| 3 | Credits | 4 | |
| 4 | Contact Hours (L-T-P) | 3-1-0 | |
| | Course Status | Compulsory | |
| 5 | Course Objective | The objective of this course is to familiarize the prospect with techniques in calculus, multivariate analysis and lin aims to equip the students with standard concepts an intermediate to advanced level that will serve them tackling more advanced level of mathematics and ap they would find useful in their disciplines. | near algebra. It nd tools at an well towards |
| 6 | Course Outcomes | CO1: Explain the concept of differential calcu thecurvature and Maxima, minima and saddle point by of Lagrange. (K2,K3, K4) CO2: Explain the concept of integral calculus,desci Gamma function, calculatemultiple integration and eva volume. (K1, K2, K3, K4, K5) | using Method ibe Beta and |
| | | CO3:Describe the concept of sequence and series;disc convergence to evaluate convergence of series. (K1, K2, | |
| | | CO4: Discuss the basic of vector calculus; illustrate gra divergence. (K1, K3) | dient, curl and |
| | | CO5: Describe and use the concepts line and surface into and vector, explain the Green theorem. (K1,K2,K3, K4) | egral for scalar |
| | | CO6: Explain the basic concepts matrices and determine system of linear equation by using rank and inverse me Eigen values and Eigen vectors; Diagonalization of mat Hamilton Theorem.(K2,K 3,K4, K5) | thod, calculate |
| 7 | Course Description | This course is an introduction to the fundamental of Mat primary objective of the course is to develop the basic up of differential and integral calculus, sequence and series, calculus and linear algebra. | nderstanding |
| 8 | Outline Syllabu | | CO Mapping |
| | Unit 1 | Differential Calculus | |
| | A | Differentiation, Taylor's and Maclaurin's theorems with remainders; indeterminate forms and L' Hospital's rule; | CO1 |
| | В | Limits and continuity for multivariable and Partial derivatives, Euler's theorem total derivative; Tangent plane and normal line (basic concepts); | CO1 |
| | С | Expansion of functions of several variables, Maxima, minima and saddle points; Method of Lagrange | CO1 |



| | | manifications | | S 🌽 B | eyond Boundaries |
|---|--------------|---------------------------------------|------------------|-------------------------------|------------------|
| | TL | multipliers. | 1. 1. | | |
| | Unit 2 | Integral Ca | | 1.1. | |
| | А | Beta and Gar | CO2 | | |
| | | | | ble integrals (Cartesian), | |
| | | | | ion in double integrals, | |
| | В | | | sian to polar), Applications: | CO2 |
| | | | lumes, Center | | |
| | С | | |), Simple applications of | CO2 |
| | | triple integra | | | |
| | Unit 3 | Sequences a | | | |
| | А | | e of sequence a | | CO3 |
| | В | | vergence: com | parison test, D' Alembert's | CO3 |
| | | ratio test, | | | |
| | С | · · · · · · · · · · · · · · · · · · · | 2 | test; Power series. | CO3 |
| | Unit 4 | Vector Calc | | | |
| | А | Gradient, cui | rl and diverger | nce, Scalar line integrals, | CO4, CO5 |
| | В | vector line in | ntegrals, scalar | surface integrals, | CO4, CO5 |
| | С | vector surfac | e integrals, Th | neorems of Green's theorem. | CO4, CO5 |
| | Unit 5 | Matrices | | | |
| | А | Inverse and r | ank of a matri | ix, System of linear | CO6 |
| | | equations, | | • | |
| | В | Symmetric, s | skew-symmetr | ric and orthogonal matrices; | CO6 |
| | | Determinant | • | C A | |
| | С | Eigen values | and Eigen ve | ctors; Diagonalization of | CO6 |
| | | | yley - Hamilto | | |
| | Mode of | Theory | | | |
| | examination | 5 | | | |
| | Weightage | CA | MTE | ETE | |
| | Distribution | 30% | 20% | 50% | |
| | Text book/s* | 1. Krey | szig, E., | "Advanced Engineering | |
| | | - | - | n Wiley & Sons Inc ISBN | |
| | | | -470-45836-5 | | |
| | | | | | |
| | | | | yengar, S.R.K., "Advanced | |
| | | Ū. | - | Mathematics", Narosa | |
| | | Publi | cations 2007 | | |
| | Other | 1. Simn | nons, G.F., "D | ifferential Equations with | |
| | References | | | pplications", Tata McGraw- | |
| | | | second editio | | |
| | | | | 1ISBN 13: 9780070573758 | |
| | | | 10.001031310 | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| L | 1 | l | | | 1 |



CO, PO & PSO MAPPING:

| | PO | PO | РО | РО | РО | РО | РО | РО | РО | PO1 | PO1 | PO1 | PSO | PSO | PSO |
|---------|----|-----|-----|-----|-----|-----|----|----|----|-----|-----|-----|-----|-----|-----|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 1 | 2 | 1 | 2 | 3 |
| MTH141. | 3 | 3 | 2 | 2 | 2 | 1 | - | - | - | 1 | 1 | 1 | - | - | - |
| 1 | | | | | | | | | | | | | | | |
| MTH | 3 | 2 | 3 | 2 | 2 | 2 | - | - | - | 1 | 1 | 2 | - | - | - |
| 141.2 | | | | | | | | | | | | | | | |
| MTH | 3 | 2 | 2 | 2 | 3 | 1 | - | - | - | 2 | 1 | 1 | - | - | - |
| 141.3 | | | | | | | | | | | | | | | |
| MTH | 3 | 3 | 2 | 2 | 2 | 1 | - | - | - | 2 | 1 | 1 | - | - | - |
| 141.4 | | | | | | | | | | | | | | | |
| MTH | 3 | 2 | 2 | 2 | 2 | 1 | - | - | - | 1 | 1 | 2 | - | - | - |
| 141.5 | | | | | | | | | | | | | | | |
| MTH | 3 | 3 | 2 | 3 | 2 | 2 | - | - | - | 1 | 1 | 2 | - | - | - |
| 141.6 | | | | | | | | | | | | | | | |
| MTH 141 | 3 | 2.5 | 2.2 | 2.1 | 2.2 | 1.3 | | | | 1.3 | 1.0 | 1.5 | | | |



FEN101: FUNCTIONAL ENGLISH BEGINNER – I First Year (Odd Semester) SYLLABUS

| | 1 | | SYLLABUS | | |
|------|----------------|-------------|---|----------------|--|
| | Course | | | | |
| 1 | number | FEN101 | | | |
| 2 | Course Title | | nal English Beginner-1 | | |
| 3 | Credits | 1 | | | |
| | Contact | | | | |
| 4 | Hours (L-T-P) | 0-0-2 | | | |
| _ | Course | | = | graduate stude | ents with basic understanding of English |
| 5 | Pre-requisite | languag | | | |
| | | - | e students to hone the basic | communication | on skills: listening, speaking, reading and |
| | | writing. | n students to minimize the line | wistic and soc | io-cultural barriers emerging in a different |
| | Course | environ | - | | |
| 6 | Objective | | | nt accents and | standardise their existing English. |
| • | | i o neip | | | patterns in pronunciation of the English |
| | | | sentences. | - 8 | |
| | | | C02 : Students will be able to | understand the | e grammatical concepts and use new |
| | | | words. | | |
| | | | C03 : Students will be able to | | |
| | | | | | ragraphs and identify parts of speech. |
| | | | | evaluate and i | nterpret main ideas to differentiate |
| _ | Course | | between opinions and facts. | | |
| 7 | Outcomes | | | | ect sentences and punctuation. |
| 8 | Outline syllab | us: Functio | onal English Beginner-1 (FEN103 TOPICS | s) Ref. & | Cos |
| | | | TOPICS | Chapter | Cos |
| | FEN101.A | UNIT A | Sentence Structure | enupter | |
| | | | | | co2 |
| | | | Activities based on | Ref 1, Ref 2 | C02 |
| 8.01 | FEN101.A1 | Topic1 | Subject Verb Agreement | | - |
| | | | Activities based on parts | Ref 1, Ref 2 | |
| 8.02 | FEN101.A2 | Topic2 | of speech | | |
| | | | Writing well-formed | Ref 1, Ref 2 | |
| 0.00 | FEN101 A2 | Tanial | Writing well-formed sentences | Kei I, Kei Z | |
| 8.03 | FEN101.A3 | Topic3 | sentences | | |
| | | | | | |
| | FEN101.B | UNIT B | VocabularyBuilding and Pu | nctuation | |
| | | | Homonyms/ | Ref 1, Ref 2 | C01, C02, C06 |
| 8.04 | FEN101.B1 | Topic1 | homophones | | |
| 0.04 | TENIOI.DI | торіст | • | | - |
| 8.05 | FEN101.B2 | Topic2 | Synonyms/Antonyms | Ref 1, Ref 2 | 4 |
| 8.06 | FEN101.B3 | Topic3 | Punctuation | Ref 1, Ref 2 | |
| | | 19.000 | | I - | 1 |
| | | | | | |
| | FEN101.C | UNIT C | ReadingComprehension | r | |
| 8.07 | FEN101.C1 | Topic1 | Scanning based passages | Ref 4 | CO4, C05 |
| | | | Skimming based | Ref 4 | |
| | | | e e | | |
| 8.08 | FEN101.C2 | Topic2 | passages | | |



| | | | | | UNIVERSITY Beyond Boundaries | | | | | |
|------|--------------------|-------------|---|---------------|---|--|--|--|--|--|
| 8.00 | FEN101 C2 | Topic2 | Comprehension and Vocabulary based exercises | Ref 4 | | | | | | |
| 8.09 | FEN101.C3 | Topic3 | exercises | | | | | | | |
| | FEN101.D | | Speaking Skills | | | | | | | |
| | | UNIT D | Speaking Skills | | | | | | | |
| 8.10 | FEN101.D1 | Topic1 | Presentation | Ref 1 | C03 | | | | | |
| 8.11 | FEN101.D2 | Topic2 | Extempore | 4 | | | | | | |
| 8.12 | FEN101.D3 | Topic3 | Role-play of different situations | | | | | | | |
| | | | | | | | | | | |
| | FEN101.E | UNIT E | Reading texts | | | | | | | |
| 8.13 | FEN101.E1 | Topic1 | The Thief by Ruskin Bond (short story) | | CO4, C05 | | | | | |
| 8.14 | FEN101.E2 | Topic2 | The Hack Driver By Sinclair Lewis (short story) | | | | | | | |
| 8.15 | FEN101.E3 | Topic3 | Texts based discussions | | | | | | | |
| 0.15 | | TOPICS | | | | | | | | |
| 9 | Course Evaluat | tion | | | | | | | | |
| 9.1 | Course work: | 30% | | | | | | | | |
| 9.2 | Attendance | None | | | | | | | | |
| 9.3 | Homework | | nments, no weight | | | | | | | |
| 9.4 | Quizzes | - | uizzes (based on assignments); | 20 marks | | | | | | |
| 9.5 | Lab | | | 20 11101 K3 | | | | | | |
| | | Separat | e | | | | | | | |
| 9.6 | Presentations | None | | | | | | | | |
| 9.7 | Any other | None | | | | | | | | |
| 9.9 | MTE | One, 20% | | | | | | | | |
| 9.10 | End-term Exam | nination: (| Dne, 50% | | | | | | | |
| 10 | Reference Boo | ks, Videos | and Internet: | | | | | | | |
| | | 1. | Communication Skills by Sanja | y Kumar and I | PushpLata, OUP Publications. | | | | | |
| | | 2. | | by Meenak | shi Raman and Sangeeta Sharma, OUP | | | | | |
| | Touthart | 3. | Publications. Functional English Workbook I | Reginner I | | | | | | |
| | Text book | ● | | | ar and Composition, S.Chand& Company Ltd, | | | | | |
| | Poforance | | New Delhi. | | | | | | | |
| | Reference Books | • | Murphy's English Grammar with CD, Cambridge University Press. | | | | | | | |
| м | apping of Outcome | s vs. Topi | cs | | | | | | | |
| FI | LENAME: Functiona | l English I | Beginner 1 (FEN101) 2 CO3 CO4 CO5 CO6 | 7 | | | | | | |
| | u = 0 = 10 | | | 1 | | | | | | |

Outcome no. \rightarrow CO1CO2CO3CO4CO5CO6



| Syllabus topic↓ | | | | | | |
|-----------------|---|---|---|---|---|---|
| FEN101.A | | Х | | | | |
| FEN101.A1 | | Х | | | | |
| FEN101.A2 | | Х | | | | |
| FEN101.A3 | | Х | | | | |
| FEN101.B | Х | Х | | | | Х |
| FEN101.B1 | Х | Х | | | | Х |
| FEN101.B2 | Х | Х | | | | Х |
| FEN101.B3 | Х | Х | | | | Х |
| FEN101.C | | | | Х | Х | |
| FEN101.C1 | | | | Х | Х | |
| FEN101.C2 | | | | Х | Х | |
| FEN101.C3 | | | | Х | Х | |
| FEN101.D | | | Х | | | |
| FEN101.D1 | | | Х | | | |
| FEN101.D2 | | | Х | | | |
| FEN101.D3 | | | Х | | | |
| FEN101.E | | | | Х | Х | |
| FEN101.E1 | | | | Х | Х | |
| FEN101.E2 | | | | Х | Х | |
| FEN101.E3 | | | | Х | Х | |



Programming for problem solving lab

| | nool: SET ogram: B.Tech. | | | | | | | |
|---|-----------------------------|--|-----------------|--|--|--|--|--|
| | anch: nester: I | | | | | | | |
| 1 | Course Code | CSP113 | | | | | | |
| 2 | Course Title | Programming for problem solving lab | | | | | | |
| 3 | Credits | 1 | | | | | | |
| 4 | Contact | 0-0-2 | | | | | | |
| | Hours | | | | | | | |
| | (L-T-P) | | | | | | | |
| | Course Status | Compulsory | | | | | | |
| 5 | Course | 1. Learn basic programming constructs –data types, d | lecision | | | | | |
| | Objective | structures, control structures in C | | | | | | |
| | | 2. learning logic aptitude programming in c language | 2 | | | | | |
| | | 3. Developing software in c programming | | | | | | |
| 6 | Course | After Completion of Course Students will be able to: | | | | | | |
| | Outcomes | CO1: demonstrate the algorithm, Pseudo-code and flow | w chart for the | | | | | |
| | | given problem. | 6.0 | | | | | |
| | | CO2: develop better understanding of basic concepts of C | | | | | | |
| | | programming. | | | | | | |
| | | CO3: create and implement logic using array and function. | | | | | | |
| | | CO4: construct and implement the logic based on the c | concept of | | | | | |
| | | strings and pointers. | in filo | | | | | |
| | | CO5: apply user-defined data types and I/O operations in file.CO6: design and develop solutions to real world problems using C. | | | | | | |
| 7 | Course | Programming for problem solving gives the Understanding | | | | | | |
| , | Description | programming and implement code from flowchart or algor | | | | | | |
| 8 | Outline syllabu | | CO | | | | | |
| Ŭ | outilité sylluoe | 5U | Mapping | | | | | |
| | Unit 1 | Logic Building | | | | | | |
| | | Draw flowchart for finding leap year | CO1 | | | | | |
| | | Write a c Program to Add Two Integers | CO1 | | | | | |
| | | Write a program to create a calculator | CO1 | | | | | |
| | Unit 2 | Introduction to C Programming | | | | | | |
| | | Write a c program to convert length meter to cm | CO2 | | | | | |
| | | Write a c program to convert temp | CO2 | | | | | |
| | | Write a c program to swap two numbers | CO2 | | | | | |
| ı | 1 | | 1 | | | | | |



| | | | — — — — — — — — — — — — — — — — — — — | eyond Boundaries | | | | | |
|--------------|------------|---|---------------------------------------|------------------|--|--|--|--|--|
| Unit 3 | Arrays an | nd Function | | | | | | | |
| | Write a c | CO3 | | | | | | | |
| | Write a c | CO3 | | | | | | | |
| Unit 4 | Pre-proce | essors and l | Pointers | | | | | | |
| | Write a c | Write a c program to swap two values using pointers | | | | | | | |
| | Write a c | program | to find largest number from array | CO4, CO6 | | | | | |
| | using poin | nters | | | | | | | |
| Unit 5 | User Defi | ned Data T | ypes and File Handling | | | | | | |
| | Write a c | program to | store information of a student using | CO5, CO6 | | | | | |
| | structure | | | | | | | | |
| | Write a c | program to | store information of a student using | CO5, CO6 | | | | | |
| | union | | | | | | | | |
| | | | | | | | | | |
| Mode of | Practical | | | | | | | | |
| examination | | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 60% | 0% | 40% | | | | | | |
| Text book/s* | Kernighar | n, Brian, | and Dennis Ritchie. The C | | | | | | |
| | Programm | | | | | | | | |
| Other | 1. E. | | | | | | | | |
| References | Tat | | | | | | | | |
| | ISE | | | | | | | | |
| | 130 | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |

| | РО | РО | РО | РО | РО | РО | РО | РО | РО | РО | РО | РО | PSO1 | PSO2 | PSO3 |
|----------|-----|----|-----|----|----|----|----|----|----|----|----|----|------|------|------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | | | |
| CSE113.1 | 1 | 2 | 1 | - | - | 1 | - | - | - | - | - | - | 1 | 1 | - |
| CSE113.2 | 2 | - | 2 | _ | - | 1 | - | _ | - | - | 1 | - | 2 | 2 | _ |
| CSE113.3 | 1 | - | 1 | _ | - | - | _ | _ | - | - | - | - | _ | 1 | _ |
| CSE113.4 | 1 | - | 1 | - | - | - | _ | - | - | - | - | - | - | 1 | _ |
| CSE113.5 | 1 | - | 1 | _ | - | - | - | - | - | - | - | - | - | 1 | _ |
| CSE113.6 | 2 | 2 | 2 | - | - | 2 | - | - | - | - | 1 | - | 2 | 2 | 1 |
| CSE113 | 1.3 | 1 | 1.3 | - | - | 1 | - | - | - | - | 1 | - | 1 | 1.3 | 1 |



| School: SET Program: B.Tech Branch::EEE Semester: I 1 Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours 0-0-3 (L-T-P) Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the experiment and -able or reation graving and use the software packages for drafting or computer experience is necessary. | | | Computer Aldeu Design & Dratung Lab | |
|---|---|------------------|---|---|
| Branch: EEE Semester: 1 1 Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours (L-T-P) O-0-3 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course Outcomes After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. | | | | |
| Semester: I Image: Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours (L-T-P) 0-0-3 (L-T-P) 5 Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing echniques and be able to replicate speci | | 0 | | |
| 1 Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours 0-0-3 (L-T-P) Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD. CO3: Choose advance features in the engineering drawing in AutoCAD. CO4: Apply text and dimension features in the engineering drawing in AutoCAD. CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students | | | | |
| 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours (L-T-P) 0-0-3 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. 7 Outcomes After successful completion of tais course the student will be able to: CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and | | | MED 106 | |
| 3 Credits 1.5 4 Contact Hours (L-T-P) 0-0-3 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course Outcomes After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO Mapping List of Experiment 1 Intt | | | | |
| 4 Contact Hours (L-T-P) 0-0-3 5 Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course Outcomes After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to creat using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus | | | | |
| (L-T-P) Compulsory 5 Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD Software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO 8 <th></th> <th></th> <th></th> <th></th> | | | | |
| 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course Outcomes After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD. CO3: Choose advance features to present an engineering drawing to AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO 8 Outline syllabus CO 8 Outline syllabus CO 8 Outline syl | 4 | (L-T-P) | | |
| 8 Outline syllabus with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: Outcomes 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing in explored. No drafting or computer experience is necessary. 8 Outline syllabus CO 8 Outline syllabus CO 8 Dutline syllabus CO 8 Outline syllabus CO 8 Dutline syllabus | | | | |
| Outcomes CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO Mapping List of Experiment 1 Introduction to AutoCAD and its interface with assignment 1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2 | 5 | Course Objective | with computer-aided drafting/ design, introduce them abore commands, tools and dimension techniques for cre- presentation of various engineering drawing by using software which helps in visualization and problem | ut the basic eation and AutoCAD |
| Description proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO Mapping List of Experiments CO Experiment 1 Introduction to AutoCAD and its interface with assignment 1 CO1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2 | 6 | | CO1: Understand the fundamental features of AutoCAD and user interface. CO2: Apply the fundamental tools such as draw, edit, ar creating two dimensional engineering drawings in AutoCA CO3: Choose advance features to present an engineering AutoCAD CO4: Apply text and dimension features in the engineering CO5: Create different orthographic projections from a pict CO6: Analyze an engineering drawing and use the softwar | workspace nd view for AD. drawing in g drawing orial view. |
| List of Experiments Mapping Experiment 1 Introduction to AutoCAD and its interface with assignment 1 CO1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2 | | Description | This introductory course is offered to students to r proficient in design, layout, product development, and ot that require technical drawing. Using the current vers AutoCAD software, students will learn a variety of techniques and be able to replicate specific drawings perspectives. The pinnacle of the class is to empower students to create using the software provided. Career of and 3-D modelling, manufacturing, and engineering w | her careers ion of the of drawing in multiple and enable oportunities ill also be |
| List of Experiments List of Experiments Introduction to AutoCAD and its interface with assignment 1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, | 8 | Outline syllabus | | |
| Experiments CO1 Experiment 1 Introduction to AutoCAD and its interface with assignment 1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, | | | | Mapping |
| Experiment 1Introduction to AutoCAD and its interface with assignment 1CO1Experiment 2Working with coordinates, Drawing ofline, circle, arc,CO2 | | | | |
| Image: assignment 1 COI Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2 | | - | | |
| Experiment 2 Working with coordinates, Drawing ofline, circle, arc, | | Experiment 1 | | CO1 |
| | | Experiment 2 | | CO2 |

Computer Aided Design & Drafting Lab



| | | | | nd Boundaries |
|---------------|----------------------------------|-----------------|---------------------------------|---------------|
| | 2 | | | |
| Experiment 3 | Editing of dra tools with ass | | g editing Tools and Power | CO2 |
| Experiment 4 | Creating of a | advanced feat | ure like fillet, chamfer, hatch | CO3, |
| _ | and using of | reusable items | with assignment 4 | CO6 |
| Experiment 5 | Representing assignment 5 | | nensioning in AutoCADwith | CO4 |
| Experiment 6 | Creating the | drawing of the | e given assignment 6 by using | CO2, |
| _ | AutoCAD fea | atures. | | CO3 |
| Experiment 7 | Creating the AutoCAD. | drawing of | the given assignment 7 in | CO2,CO6 |
| Experiment 8 | Creating the | drawing of t | he given diagram and giving | CO2, |
| _ | dimensions in | n AutoCAD. | | CO4 |
| Experiment 9 | Creating the | drawing of Ta | jMahal in Autocad 2D | СОЗ, |
| | | | | CO6 |
| Experiment 10 | Creating of o | rthographic pi | rojections from a 3D figure | CO5, |
| _ | | | | CO6 |
| | | | | |
| Mode of | Practical | | | |
| examination | | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 60% | 0% | 40% | |
| Text book/s* | 1. Ibrahi | im Zaid,"CAD | /CAM- Theory and Practice", N | McGraw |
| | Hill, I | International E | Edition. ISBN 0-07-072857-7 | |
| | | | | |
| | | | | |
| Software | AutoCAD | | | |

| $\overline{00,10}$ | | | | | | | | | | | | | | |
|--------------------|----|----|-----|----|----|----|----|----|----|-----|-----|-----|-----|-----|
| COs | PO | PO | PO | PO | PO | PO | PO | PO | РО | PO1 | PO1 | PO1 | PSO | PSO |
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 1 | 2 | 1 | 2 |
| MEP10 | 2 | 2 | 2 | - | 3 | - | - | - | - | - | - | 3 | 3 | 3 |
| 6.1 | | | | | | | | | | | | | | |
| MEP | 2 | - | - | - | - | - | - | - | - | - | - | 3 | 3 | 3 |
| 106.2 | | | | | | | | | | | | | | |
| MEP | 2 | - | - | - | - | - | - | - | - | - | - | 3 | 3 | 3 |
| 106.3 | | | | | | | | | | | | | | |
| MEP | 2 | - | - | - | - | - | - | - | 2 | 2 | - | 3 | 3 | 3 |
| 106.4 | | | | | | | | | | | | | | |
| MEP | 2 | - | - | - | - | - | - | - | 2 | 2 | - | 3 | 3 | 3 |
| 106.5 | | | | | | | | | | | | | | |
| MEP | - | 2 | 3 | 3 | - | - | - | - | - | - | - | - | - | - |
| 106.6 | | | | | | | | | | | | | | |
| MEP | | | | | | - | - | - | | | | | | |
| 106 | 2 | 2 | 2.5 | 3 | 3 | | | | 2 | 2 | - | 3 | 3 | 3 |



| Sel | hool: SET | | |
|---------------|-----------------|--|---------------|
| | ogram: B.Tech | | |
| | anch:EEE | | |
| | mester:1 | | |
| | 1 | ECD100 | |
| $\frac{1}{2}$ | Course Code | ECP109 | |
| | Course Title | Introduction to Electronics Engineering | |
| 3 | Credits | 1 | |
| 4 | Contact | 0-0-2 | |
| | Hours | | |
| | (L-T-P) | | |
| | Course | Compulsory | |
| ~ | Status | | |
| 5 | Course | To be acquainted with few recent technologies in | the field of |
| - | Objective | Engineering. | |
| 6 | Course | After successful completion of this course the student will be able | to: |
| | Outcomes | CO1: Explain and classify few sensors | |
| | | CO2: Understand the importance of AI | |
| | | CO3: Describe the working of basic IoT system | 1 |
| | | CO4: Demonstrate and Identify the components of drone and | a practice of |
| | | indoor pilot | |
| | | CO5: Interpret the working of basic robot | |
| 7 | Comme | CO6: Apply the concept in various hardware based applicati | ons |
| / | Course | This course is an active introduction to developing | a addad ta |
| | Description | an engineering mindset by teaching the necessary skills to be | |
| | | your engineering toolbox. You will learn to identify opportu | |
| | | imagine new solutions, model your creations, make decision prototypes, and showcase your ideas that impact the world. | is, build |
| 8 | Outline syllabi | | СО |
| 0 | Outille syllab | 13 | Mapping |
| | Unit 1 | Sensors | Mapping |
| | A | Different type of Sensors | CO1 |
| | B | Application of Sensors | C01 |
| | C | Case study | C01,C06 |
| | Unit 2 | Artificial Intelligence | 01,000 |
| | A A | What is Artificial Intelligence? History of Artificial | CO2 |
| | | Intelligence | |
| | В | Applications | CO2 |
| | | | |
| | C | Case study | CO2,CO6 |
| | Unit 3 | | |
| | A | Basics of IoT | CO3 |
| | B | Applications Of IoT | CO3 |
| | С | Case study | CO3,CO6 |

Introduction to Electronics Engineering



| | | | | 🥿 🎾 Beyond Boundaries |
|--------------|---------|---------------|----------------------------|-----------------------|
| Unit 4 | Drone | | | |
| А | Basics | of Drone Te | echnology | CO4 |
| В | Applica | ations | | CO4,CO6 |
| С | Practic | ing of indoo | or pilot system/Case study | CO4,CO6 |
| Unit 5 | Roboti | CS | | |
| Α | Basics | of Robotics | | CO5 |
| В | Applica | ations | | CO5,CO6 |
| С | Case st | udy of fire b | pird robot | CO5,CO6 |
| Mode of | Practic | al & Viva | | |
| examination | | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 60% | 0% | 40% | |
| Text book/s* | Refer n | nanuals | | |
| Other | | | | |
| References | | | | |

| CO's | P01 | P02 | PO3 | P04 | P05 | P06 | P07 | PO8 | P09 | PO10 | P011 | P012 | PS01 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ECP106.1 | 3 | 2 | 2 | 1 | 1 | 2 | - | - | - | - | - | 1 | 2 | 1 | 2 |
| ECP106.2 | 2 | 2 | 2 | - | 2 | 2 | - | - | - | - | - | 3 | 1 | 1 | 1 |
| ECP106.3 | 2 | 1 | 1 | 1 | 2 | 1 | - | - | - | - | - | 2 | 3 | 1 | 2 |
| ECP106.4 | 2 | 3 | 3 | 1 | 1 | 1 | - | - | - | - | - | 2 | - | 2 | 1 |
| ECP106.5 | 3 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 | 1 |
| ECP106.6 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | - | - | - | - | 3 | 3 | 3 | 3 |



TERM-II

Principles of Electrical and Electronics Engineering



| Sch | ool: SET | S 🖉 Beyo | nd Boundaries |
|-----|------------------|--|---------------|
| Bat | | | |
| Pro | gram: B.Tech | | |
| Bra | nch: ECE | | |
| Sem | nester: II | | |
| 1 | Course Code | EEE112 | |
| 2 | Course Title | Principles of Electrical and Electronics Engineering | |
| 3 | Credits | 3 | |
| 4 | Contact | 2-1-0 | |
| | Hours | | |
| | (L-T-P) | | |
| | Course Status | Compulsory | |
| 5 | Course | To provide the students with an introductory concept in t | he field of |
| c . | Objective | electrical and electronics engineering to facilitate better under | |
| | 5 | | engineering |
| | | applications. | ingineering |
| 6 | Course | After completion of Course Students will be able to: | |
| 6 | Outcomes | CO1: To analyze and solve basic electrical circuits | |
| | Outcomes | CO3: To understand the working principle of transformer and | identify its |
| | | applications. | identify its |
| | | CO3: To understand the working principle of dc and ac motors | s and |
| | | identify the starting methods of single-phase induction motor | |
| | | CO4: To apply the basics of diode to describe the working of r | rectifier |
| | | circuits such as half and full wave rectifiers | |
| | | CO5: To apply the concepts of basic electronic devices to desi | gn various |
| | | circuits | |
| | | CO6:Apply the basic concepts in Electrical and Electronics En | gineering |
| 7 | 9 | for multi-disciplinary tasks | 6 1 4 1 1 |
| 7 | Course | This initial course introduces the concepts and fundamentals of and electronic circuits and devices. Topics include basic circuits | |
| | Description | and electronic circuits and devices. Topics include basic circu diode and transistor fundamentals and applications. This of | - |
| | | introduces working principle and applications of dc/ac r | |
| | | transformers. | notors and |
| 8 | Outline syllab | | СО |
| | 5 | | Mapping |
| | Unit 1 | DC & AC Circuits (6 lectures) | |
| Ī | А | Electrical circuit elements (R, L and C), series and parallel | CO1 |
| | | circuits, concept of equivalent resistance, Kirchhoff current | |
| _ | | and voltage laws, star-delta conversion | |
| | В | Analysis of simple circuits with dc excitation and | CO1 |
| | | Superposition Theorem, Representation of sinusoidal | |
| | | waveforms, peak and rms values, real power, reactive power, | |
| | ~ | apparent power, power factor | <u> </u> |
| | С | Introduction to three phase system, relationship between | CO1 |
| | TI:4 2 | phase voltages and line voltages, | |
| - | Unit 2 | Transformer(4 lectures) | CO2 |
| | А | Working principle and construction of transformer, EMF equation | 002 |
| | | Quanon | |



| | | | Bev | ond Boundaries |
|-----------|------------------------|-------------------------|---|----------------|
| В | Efficient transform | • | nsformer, Power and distribution rence between them | CO2 |
| С | Transfor electrica | | ions in transmission and distribution of | CO2 |
| Unit | | al Motors ((| 6 lectures) | |
| A | | (| g principle, torque-speed characteristic | СОЗ, |
| | | lications of do | | CO6 |
| В | 11 | | g principle and applications of a three- | CO3, |
| | | | or, significance of torque-slip | CO6 |
| | characte | | -,8 | |
| С | | | arting methods and applications of | СОЗ, |
| | | hase induction | | CO6 |
| Unit | | | le and Rectifier (5 lectures) | |
| A | | tion and its b | | CO4, |
| | i i quite | fion and its of | lusing | CO6 |
| В | Semicor | ductor diode | , ideal versus practical diode, VI | CO4, |
| D | | ristics of diod | - | CO4, CO6 |
| С | | | ave rectifiers with and without filters. | CO4, |
| C | I all wa | | ave rectifiers with and without filters. | CO4, CO6 |
| Unit | 5 Transis | tors (5 lectu | roc) | 000 |
| A | | | nsistor (BJT) –Construction, working | CO5, |
| А | | | utput characteristics | CO3, CO6 |
| В | | | and as a switch | CO5, |
| D | DJI as (| | and as a switch | CO5, CO6 |
| С | Introduc | tion to JFET | | CO5, |
| C | introduc | | | CO5, CO6 |
| Mode of | Theory | | | |
| examina | - | | | |
| Weighta | | MTE | ETE | |
| Distribut | | 20% | 50% | |
| Text boo | | | and I. J. Nagrath, "Basic Electrical | |
| 1CAL 000 | | | _ | |
| | | 0 0 / | , Tata McGraw Hill, 2010- ISBN: | |
| | | - | 9781259081538 | |
| | | | harya, "Basic Electrical and Electronics | |
| | I | Engineering", | , Pearson Publication,2011 | |
| | I | SBN-813175 | 4561, 9788131754566 | |
| | 3. I | Robert L Boy | lestad, "Electronic Devices and Circuit | |
| | | 5 | son Education, 2013 | |
| | | 1^{th} edition | Son Education, 2015 | |
| | | | 2000 1000 | |
| | | SBN- 978013 | 30004033 | |
| Other | 1 | . V.D. Tor | o. "Electrical Engineering | |
| Reference | | | ntals", Prentice Hall India, 2003 | |
| | 1 | i unuamer. | 10110 , 1 10111100 11011 111010, 2000 | |
| Other | 1 | . V. D. Tor | o, "Electrical Engineering | |
| Reference | | | · · · · · · | |



| Cos | P01 | P02 | PO3 | P04 | PO5 | P06 | PO7 | PO8 | 60d | P01 | P01 | ۲01 ۲ | PSO | PSO 2 | PSO 3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|-----|----------|----------|
| EEE112.1 | 3 | 3 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | | 1 |
| EEE112.2 | 1 | 1 | 2 | - | - | - | - | - | - | - | - | - | - | 2 | - |
| EEE112.3 | 2 | 2 | 1 | - | - | - | - | - | | - | - | - | | 1 | 2 |
| EEE112.4 | 2 | 1 | 2 | - | - | - | - | - | - | - | 1 | - | - | 2 | - |
| EEE112.5 | 3 | 2 | 1 | - | - | - | - | - | - | - | 1 | - | 1 | - | 1 |
| EEE112.6 | 2 | 2 | 3 | 1 | - | - | - | - | - | - | 1 | - | - | - | - |
| EEE112 | 2.1 | 1.8 | 1.8 | 1 | - | - | - | - | - | - | 1 | - | 1 | 1 | 1 |



Principles of Electrical and Electronics Engineering Lab

School: SET Program: B.Tech

| Pro | gram: B.Tech | | |
|-----|--------------------------|---|---------------|
| | nch: EEE | | |
| | nester: II | EED110 | |
| 1 | Course Code | EEP112 | |
| 2 | Course Title | Principles of Electrical and Electronics Engineering Lab | |
| 3 | Credits | 1 | |
| 4 | Contact Hours (L-T-P) | 0-0-2 | |
| | Course Status | Compulsory | |
| 5 | Course | To provide the students with an introductory concept in the field of e | lectrical and |
| | Objective | electronics engineering to facilitate better understanding of the devices, tea equipment's used in engineering applications. | chniques and |
| 6 | Course | After successful completion of this course the student will be able to: | |
| Ũ | Outcomes | CO1: To configure and analyze any given circuit. | |
| | | CO2: To inspect the working of transformer and calculate its efficiency | |
| | | CO3: To understand the working of dc and ac motors and measure its vario | us operating |
| | | parameters. | |
| | | CO4: To design rectifier circuits such as half and full wave rectifiers and of | bserve its |
| | | output waveforms. | |
| | | CO5: To obtain the characteristics of BJT. | |
| | | CO6: Apply the basic concepts in Electrical and Electronics Engineering fo | r multi- |
| | | disciplinary tasks. | |
| 7 | Course | This initial course introduces the concepts and fundamentals of electrical a | |
| | Description | circuits and devices. Topics include basic circuit analysis, diode an | |
| | | fundamentals and applications. This course also introduces working p | rinciple and |
| | | applications of dc/ac motors and transformers. | |
| 8 | Outline syllabus | | CO |
| | | | Mapping |
| | Unit 1 | Practical based on DC & AC Circuits | CO1 |
| | | To configure a dc circuit on breadboard, and measure voltage/current | CO1 |
| | | across/through each element | 001 |
| | | To verify Kirchhoff's Laws | CO1 |
| | | To verify Superposition Theorem | CO1 |
| | | To find the real power, reactive power, apparent power and power factor | C01 |
| | | of RL & RC load | COI |
| | Unit 2 | Practical related to Transformers | |
| | | To find the efficiency of transformer by obtaining its losses. | CO2, |
| | | | CO6 |
| | Unit 3 | Practical related to Electrical Motors | 000 |
| | Olift 5 | | 002 |
| | | | CO3, |
| | | To study cut-section of DC motor and induction motor. | CO6 |
| | | | CO3, |
| | | To start the DC motor and reverse its direction of rotation. | CO6 |
| | | | CO3, |
| | | | CO3, CO6 |
| | TT 14 4 | To start an induction motor and reverse its direction of rotation. | 000 |
| | Unit 4 | Practical related to Diode and Rectifier | |
| | | | CO4, |
| | | To determine voltage-current characteristic of diode | CO6 |
| | | To assemble and test half wave and full wave rectifier circuits for their | CO4, |
| | | input and output waveform | CO6 |
| | Unit 5 | | |
| | Unit 5 | Practical related to Transistors | |



| | | | Beyon | d Boundaries |
|---------------------|--|--|--|--------------|
| | | | | CO5, |
| | To determin | e input and ou | tput characteristics of BJT | CO6 |
| | | | | CO5, |
| | Validation of | of BJT as a sw | itch | CO6 |
| Mode of examination | Practical | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 60% | 0% | 40% | |
| Text book/s* | McGraw Hi 2. S. K. B Pearson Put | ll, 2010-ISBN hattacharya, "I blication.ISBN: Boylestad, "E 2009 | Nagrath, "Basic Electrical Engineering", Tata 9780070146112 Basic Electrical and Electronics Engineering", 9789332586505 lectronic Devices and Circuit Theory" Pearson | |
| Other References | На | D. Toro, "Elec ll India, 1989. N:978013247 | | |

| Cos | | | | | | | | | | | | | | | |
|---------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PSO2 | PSO3 |
| EEP112.1 | 3 | 3 | 3 | 1 | 1 | - | - | - | - | - | - | - | 2 | - | - |
| EEP112.2 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | - | 1 |
| EEP112.3 | 2 | 1 | 1 | - | - | - | - | - | - | - | - | - | - | - | - |
| EEP112.4 | 2 | 1 | 3 | - | - | - | - | - | - | - | - | - | 2 | - | - |
| EEP112.5 | 2 | 1 | 1 | - | - | - | - | - | - | - | - | - | 2 | - | - |
| EEP112.6 | 2 | 2 | 2 | 2 | 2 | | | | 2 | | 2 | - | 1 | 1 | - |
| EEP112 | 2.1 | 1.6 | 2 | 1 | 1 | - | - | - | 1 | - | 1 | - | 1.1 | 1 | 1 |



| 5 | haal SET | | Beyond Boundaries |
|---|---------------|---|-------------------|
| | chool: SET | , | |
| | ogram: B.Teo | ch | |
| | ranch: EEE | | |
| | mester: II | | |
| 1 | Course | CSE114 Course Name | |
| - | Code | | |
| 2 | Course | Application Based Programming in Python | |
| | Title | | |
| 3 | Credits | 3 | |
| 4 | Contact | 3-0-0 | |
| | Hours | | |
| | (L-T-P) | | |
| | Course | Compulsory | |
| | Status | | |
| 5 | Course | Emphasis is placed on procedural programming, algorithm desi | 0 0 0 |
| | Objective | constructs common to most high-level languages through Python | ů ů |
| 6 | Course | Upon successful completion of this course, the student will be ab | |
| | Outcomes | CO1. Apply decision and repetition structures in program design | |
| | | CO2. Demonstrate the use of Python lists, tuples and dictionaries | |
| | | CO3. Implement methods and functions to improve readability o CO4. Describe and apply object-oriented programming methodo | |
| | | CO5. Apply top-down concepts in algorithm design. | logy. |
| | | CO6. Write Python programs to illustrate concise and efficient al | gorithms |
| 7 | Course | Python is a language with a simple syntax, and a powerful set | • |
| ' | Description | widely used in many scientific areas for data exploration. T | |
| | Description | introduction to the Python programming language for stude | |
| | | programming experience. We cover data types, control flow | |
| | | programming. | |
| 8 | Outline sylla | bus | CO Mapping |
| | Unit 1 | Introduction | |
| | А | History, Python Environment, Variables, Data Types, Operators. | CO1 |
| | В | Conditional Statements: If, If- else, Nested if-else. | CO1 |
| | _ | Looping: For, While, Nested loops. | |
| | С | Control Statements: Break, Continue, And Pass. | CO1, CO6 |
| | - | Comments | , |
| | Unit 2 | List, Tuple and Dictionaries | |
| | A A | Lists and Nested List: Introduction, Accessing list, | CO2 |
| | 1 | Operations, Working with lists, Library Function and | 002 |
| | | Methods with Lists. | |
| | В | Tuple: Introduction, Accessing tuples, Operations, | CO2 |
| | D | Working, Library Functions and Methods with Tuples. | 02 |
| | С | Dictionaries :Introduction, Accessing values in | CO2 |
| | | dictionaries, Working with dictionaries, Library Functions | |
| | Unit 3 | Functions and Exception Handling | |
| | A A | · · · | CO3,CO6 |
| | A | Functions: Defining a function, Calling a function, Typesoffunctions,FunctionArguments | 03,000 |
| | В | Anonymous functions, Global and local variables | CO3,CO6 |
| | С | Exception Handling : Definition Exception, Exception | C03,C06 |
| | 1 N . | LACEPHON HANDING. DEIMINON LACEPHON, EACEPHON | |



| r | | | | Beyond Boundari | | | | | |
|--------------|----------------|--|---|-----------------|--|--|--|--|--|
| | handling | | | | | | | | |
| | Except cla | ause, Ti | ry? finally clause | | | | | | |
| Unit 4 | OOP and | File H | landling | | | | | | |
| А | OOPs con | ncept : | Class and object, Attributes, Abstraction, | CO4 | | | | | |
| | Encapsula | tion, P | olymorphism and Inheritance | | | | | | |
| В | Static ar | al Keyword, Access Modifiers and | CO4 | | | | | | |
| | specifiers | | | | | | | | |
| С | User Defi | CO4 | | | | | | | |
| Unit 5 | Module a | | | | | | | | |
| А | | | rting module, Math module, Random | CO5, | | | | | |
| | module | 1 | 5 | , | | | | | |
| В | Matplotlil | o, Packa | ages | CO5, | | | | | |
| С | | - | ching Linear Search, Binary Search. Sorting: | CO5, CO6 | | | | | |
| | Bubble So | , | | | | | | | |
| Mode of | Theory | | | | | | | | |
| examination | | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text | The Comple | te Refer | ence Python, Martin C. Brown, McGrwHill | | | | | | |
| book/s* | | | | | | | | | |
| | ISBN:97800 | | | | | | | | |
| Other | | | n to computing in problem solving using Python, | | | | | | |
| References | | | samy, McGrwHill- ISBN:9789352604173 | | | | | | |
| | | 2. Introduction to programming using Python, Y. Daniel Liang | | | | | | | |
| 1 | Pea | Pearson-ISBN:9780132747189 | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |

| COs | P01 | P02 | P03 | P04 | PO5 | P06 | P07 | PO8 | P09 | P010 | P011 | P012 | PS01 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CSE114.1 | 1 | 3 | 2 | 2 | 1 | - | - | - | 1 | - | 1 | - | 2 | 2 | 1 |
| CSE114.2 | 3 | 3 | 3 | 3 | 3 | - | - | - | 3 | - | 3 | - | 3 | 3 | 3 |
| CSE114.3 | 3 | 3 | 3 | 3 | 2 | - | - | - | 3 | - | 2 | - | 3 | 3 | 2 |
| CSE114.4 | 2 | 2 | 2 | 1 | 2 | - | | - | 2 | - | 1 | - | 2 | 1 | 1 |
| CSE114.5 | 2 | 3 | 2 | 1 | 2 | | | | 1 | | 2 | | 1 | 2 | 2 |
| CSE114.6 | 1 | 2 | 1 | 2 | 1 | | | | 1 | | 1 | | 3 | 2 | 2 |
| CSE114 | 2 | 2.7 | 2.2 | 2 | 1.8 | | | | 1.8 | | 1.7 | | 2.3 | 2.2 | 1.8 |

Application Based Programming in Python Lab



| Sc | hool: SET | | Beyond Boundaries |
|----|--------------------------------|--|--------------------------|
| | ogram: | | |
| | Tech | | |
| Br | anch:All | Semester: II | |
| 1 | Course | CSP114 | |
| | Code | | |
| 2 | Course | Application Based Programming in Python Lab | |
| | Title | | |
| 3 | Credits | 1 | |
| 4 | Contact | 0-0-2 | |
| | Hours | | |
| | (L-T-P) | | |
| | Course | Compulsory | |
| | Status | | |
| 5 | Course | Emphasis is placed on procedural programming, algo | |
| | Objective | constructs common to most high level languages thro | |
| 6 | Course | Upon successful completion of this course, the studer | |
| | Outcomes | CO1. Apply decision and repetition structures in prog | |
| | | CO2. Demonstrate the use of Python lists, tuples and CO3. Implement methods and functions to improve re | |
| | | CO4. Describe and apply object-oriented programmi | |
| | | CO5. Apply top-down concepts in algorithm design. | ng methodology. |
| | | CO6. Write Python programs to illustrate concise and | d efficient algorithms |
| 7 | Course | Python is a language with a simple syntax, and a pow | |
| | Description | widely used in many scientific areas for data explorat | |
| | | introduction to the Python programming language for | |
| | | programming experience. We cover data types, controprogramming. | of flow, object-oriented |
| 8 | Outline sylla | | CO Mapping |
| 0 | Outline syna | 545 | |
| | | | |
| | Unit 1 | Practical based on conditional statements | |
| | | and control structures | |
| | | 1. Program to implement all conditional | C01 |
| | | statements | |
| | | 2. Program to implement different control | |
| | I I · / C | structures | |
| | Unit 2 | Practical related to List, Tuples and | |
| | | dictionaries | |
| | | Program to implement operations on lists Program to implement operations on | CO2 |
| | | 2. Program to implement operations on Dictionary | |
| | | 3. Program to implement operations on Tuple | |
| | Unit 3 | Practical related to Functions and Exception | |
| | | Handling | |
| | | 1. Program to implement Exception Handling | CO3 |
| | | 2. Program to use different functions | |
| | Unit 4 | Practical related to Object Oriented | |
| | | Programming | |
| | | 1. Program to use object oriented concepts | CO4,CO6 |
| | | | |



| _ | | | | | 🥿 🥟 Beyond Boundaries |
|---|--------------|--------|-----------|-------------------------------------|-----------------------|
| | | | like inh | eritance, overloading polymorphism | |
| | | | etc. | | |
| | | 2. | Program | n for file handling | |
| | | _ | | | |
| | Unit 5 | | | ated to Modules and | |
| | | Appli | cations | | |
| | | 1. | Progra | m to use modules and package | CO5,CO6 |
| | | 2. | Progra | m to implement searching and | |
| | | | sorting | | |
| | | | | | |
| | Mode of | Practi | cal/Viva | 1 | |
| | examination | | | | |
| | Weightage | CA | MTE | ETE | |
| | Distribution | 60% | 0% | 40% | |
| | Text | | | Reference Python, Martin C. Brown, | |
| | book/s* | McGra | aw Hill,2 | 010-ISBN:9780072127188 | |
| | Other | • I | ntroduct | ion to computing in problem solving | |
| | References | τ | using Pyt | hon, E Balagurusamy, McGraw Hill | |
| | | Ι | SBN-97 | 89353160920 | |
| | | • I | introduct | ion to programming using Python, Y. | |
| | | Ι | Daniel Li | ang, Pearson | |
| | | | | 80132747189 | |
| | | | | | |

| COs | P01 | P02 | PO3 | P04 | PO5 | P06 | P07 | PO8 | P09 | P01 0 | P01 1 | P01 | PSO 1 | PSO 2 | PSO 3 | |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|-----|----------|----------|----------|--|
| CSP114.1 | 1 | 3 | 2 | 2 | 1 | - | - | - | 1 | - | 1 | - | 2 | 2 | 1 | |
| CSP114.2 | 3 | 3 | 3 | 3 | 3 | - | - | - | 3 | - | 3 | - | 3 | 3 | 3 | |
| CSP114.3 | 3 | 3 | 3 | 3 | 2 | - | - | - | 3 | - | 2 | - | 3 | 3 | 2 | |
| CSP114.4 | 2 | 2 | 2 | 1 | 2 | - | | - | 2 | - | 1 | - | 2 | 1 | 1 | |
| CSP114.5 | 2 | 3 | 2 | 1 | 2 | | | | 1 | | 2 | | 1 | 2 | 2 | |
| CSP114.6 | 1 | 2 | 1 | 2 | 1 | | | | 1 | | 1 | | 3 | 2 | 2 | |
| CSP114 | 2 | 2.7 | 2.2 | 2 | 1.8 | | | | 1.8 | | 1.7 | | 2.3 | 2.2 | 1.8 | |



Calculus and Abstract Algebra

| Sch | ool: SET | | |
|------|----------------|---|-----------------|
| Prog | gram: B.Tech. | | |
| | nch: ALL | Semester: <u>1/2</u> | |
| 1 | Course Code | MTH 142 | |
| 2 | Course Title | Calculus and Abstract Algebra | |
| 3 | Credits | 4 | |
| 4 | Contact | 3-1-0 | |
| | Hours | | |
| | (L-T-P) | | |
| | Course | Compulsory | |
| | Status | | |
| 5 | Course | The objective of this course is to familiarize the prospec | |
| | Objective | with techniques in basic calculus and linear algebra. It ain | |
| | | students with standard concepts and tools at an in advanced level that will serve them well towards t | |
| | | | |
| | | advanced level of mathematics and applications that the useful in their disciplines. | cy would find |
| 6 | Course | CO1: Explain the concept of differential calculus, illustrat | e thecurvature |
| | Outcomes | and Maxima, minima and saddle point. (K2, K3, K4) | |
| | | CO2: Explain the basic concepts matrices and determi | nate, evaluate |
| | | system of linear equation by using rank and inverse met | hod. (K2, K3, |
| | | K5) | |
| | | CO3: Explain the basic concept of sets, relation, fund | ctions, groups |
| | | Rings and Field. (K2, K4) | |
| | | CO4: Discuss the basic of Vector spaces. (K1, K3) | |
| | | CO5: Describe and use the linear transformation and evand kernel. (K1, K2, K3, K5) | valuate nullity |
| | | CO6:Explain the concept of Eigen values and Eigen vec the diagonalization of matrices,explain the basic introdu product spaces.(K2, K3, K4, K5) | |
| 7 | Course | This course is an introduction to the fundamental of Mathe | ematics. The |
| | Description | primary objective of the course is to develop the basic und | lerstanding of |
| | | differential and integral calculus, linear Algebra and Abstr | act Algebra. |
| 8 | Outline gullah | Nuclearly and Abstract Algebra | СО |
| 0 | Outline synab | ous:Calculus and Abstract Algebra | CO Mapping |
| | Unit 1 | Calculus | mapping |
| | A | | CO1 |
| | | Differentiation, Taylor's and Maclaurin theorems with remainders; indeterminate forms, L' Hospital's rule. | |
| | В | Maxima and minima, Partial derivatives, Euler's theorem. | CO1 |
| | | | |
| | C | Total derivative. Evaluation of double integration. | CO1 |
| | | Applications of double integral (to calculate area). | |
| | | | |



| | | | | Beyond Boundar | | | | | |
|------------------------|---|--|---|----------------|--|--|--|--|--|
| | | | | | | | | | |
| Unit 2 | Matrices | | | | | | | | |
| A | Matrices, vect matrix multip | | and scalar multiplication, | CO2 | | | | | |
| В | | | s, linear Independence, rank Cramer's Rule | CO2 | | | | | |
| С | | | elimination and Gauss-Jorda | n CO2 | | | | | |
| Unit 3 | Basic Algebr | a | | | | | | | |
| A | | Sets, relations and functions. Basics of groups, cyclic groups. | | | | | | | |
| В | , | | | | | | | | |
| С | Subgroups, basics of Rings and Field. | | | | | | | | |
| Unit 4 | | Vector spaces Vector Space, linear dependence of vectors, basis, | | | | | | | |
| А | Vector Space, dimension. | | | | | | | | |
| В | Linear transfo | Linear transformations (maps), range and kernel of a linear map, rank and nullity. Inverse of a linear transformation, Matrix associated with a linear map. | | | | | | | |
| С | Inverse of a li | | | | | | | | |
| Unit 5 | Vector space Module-4 Ve | | | | | | | | |
| А | Eigenvalues, | CO6 | | | | | | | |
| В | Symmetric, sl Diagonalizati | | ic, and orthogonal Matrices, | CO6 | | | | | |
| С | | ction of Inner | product spaces, Gram- | CO6 | | | | | |
| Mode of examination | Theory | 0 | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | geometry, 9th ISBN:9788177 2. Erwin Krey 10th Edition, | 30%20%50%1. G.B. Thomas and R.L. Finney, Calculus and Analytic geometry, 9th Edition, Pearson, Reprint, 2002- ISBN:9788177583250.2. Erwin Kreyszig, Advanced Engineering Mathematics, 10th Edition, John Wiley & Sons, 2011- ISBN: 97804704583651. D. Poole, Linear Algebra: A Modern Introduction, 2nd Edition, Brooks/Cole, 2011-ISBN: 97805387354522. Veerarajan T., Engineering Mathematics for first year, Tata McGraw-Hill, New Delhi, 2008- ISBN:97800704948243. Ramana B.V., Higher Engineering Mathematics, Tata McGraw Hill New Delhi, 11th Reprint, 2010- ISBN:9780230345980 | | | | | | | |
| Other References | D. Poole, L 2nd Edition, I Veerarajan Tata McGraw ISBN:9780070 Ramana E Tata McGraw | | | | | | | | |



| | РО | РО | РО | PO4 | PO | 5 P | PO | PO | РО | PO1 | PO1 | PO1 | PSO | PSO | PSO |
|---------|----|----|-----|----------|-----|-----|----|----|----|-----|-----|-----|-----|-----|-----|
| | 1 | 2 | 3 | | | 0 | 7 | 8 | 9 | 0 | 1 | 2 | 1 | 2 | 3 |
| | | | | | | 6 | | | | | | | | | |
| MTH142. | 3 | 3 | 2 | 2 | 3 | 1 | - | - | - | 1 | 1 | 1 | - | - | - |
| 1 | | | | | | | | | | | | | | | |
| MTH142. | 3 | 3 | 3 | 2 | 2 | 2 | - | - | - | 1 | 1 | 2 | - | - | - |
| 2 | | | | | | | | | | | | | | | |
| MTH142. | 3 | 3 | 2 | 2 | 2 | 1 | - | - | - | 1 | 1 | 1 | - | - | - |
| 3 | | | | | | | | | | | | | | | |
| MTH142. | 3 | 3 | 2 | 2 | 2 | 1 | - | - | - | 1 | 1 | 1 | - | - | - |
| 4 | | | | | | | | | | | | | | | |
| MTH142. | 3 | 3 | 2 | 2 | 2 | 1 | - | - | - | 1 | 1 | 2 | - | - | - |
| 5 | | | | | | | | | | | | | | | |
| MTH142. | 3 | 3 | 2 | 3 | 2 | 2 | - | - | - | 1 | 1 | 2 | - | - | - |
| 6 | | | | | | | | | | | | | | | |
| MTH142 | 3 | 3 | 2.2 | 2.1 7 | 2.2 | 1.3 | | | | 1.0 | | 1.5 | | | |



| | Cabaal | | | | | | | | | |
|-------------|-----------------|--|--------------|--|--|--|--|--|--|--|
| C I | School: | | | | | | | | | |
| | ol of Basic | | | | | | | | | |
| | ces and | | | | | | | | | |
| Resea | | | | | | | | | | |
| <u> </u> | ram: B.TECH. | | | | | | | | | |
| Bran CSE | cn: EC/EEE | Semester: II | | | | | | | | |
| 1 | Course Code | PHY 118 | | | | | | | | |
| 2 | Course Title | Electricity and Magnetism | | | | | | | | |
| 3 | Credits | 3 | | | | | | | | |
| 4 | Contact Hours | 2-1-0 | | | | | | | | |
| 4 | (L-T-P) | 2-1-0 | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | |
| 5 | Course | To make students familiar with the concepts of ele | etrostatics | | | | | | | |
| 5 | Objective | magnetostatics and electromagnetism and to utilize th | | | | | | | | |
| | Objective | electromagnetism on various problems. | | | | | | | | |
| 6 | Course | At the end of the course, the student will be able to: | | | | | | | | |
| Ŭ | Outcomes | | | | | | | | | |
| | | | | | | | | | | |
| | | CO1: learn the basic concepts of electrostatics. | | | | | | | | |
| | | CO2: learn the fundamental concepts of electric potentials. | | | | | | | | |
| | | CO3: gain knowledge about the principle of capacitor, dielectrics | | | | | | | | |
| | | materials and electric polarization. | | | | | | | | |
| | | CO4: have a clear understanding of fundamentals of magn | etic effects | | | | | | | |
| | | of | | | | | | | | |
| | | current and magnetism | | | | | | | | |
| | | CO5: learn the concept of Maxwell's Equations in differen | tial and | | | | | | | |
| | | integral form and their physical significance. | | | | | | | | |
| | <u> </u> | CO6: learn the fundamental concept of electricity and mag | | | | | | | | |
| 7 | Course | Today, life without electromagnetic technologies is almost unth | | | | | | | | |
| | Description | this reason, it is critically significant to understand the basic fun this paper. This course is able to explain the required basic | | | | | | | | |
| | | Both electricity and magnetism may be understood as force | | | | | | | | |
| | | balance and students learn to understand such concepts as cl | | | | | | | | |
| | | voltage, potential, current, resistance, and power within this fram | | | | | | | | |
| 7 | Outline Syllabu | s | СО | | | | | | | |
| | | | Mapping | | | | | | | |
| | Unit 1 | Electrostatics | | | | | | | | |
| | А | Introduction to the course and prerequisites required | CO1 | | | | | | | |
| | | Coulomb's law-force between two point charges, forces | | | | | | | | |
| | | between multiple charges; superposition principle and | | | | | | | | |
| | | continuous charge distribution. | | | | | | | | |
| | | | | | | | | | | |
| | В | Electric field, electric field due to a point charge, electric | CO1 | | | | | | | |



| T | 1 | | K Beyond | Boundaries |
|------------------------|--|---------------------------------|-------------------------------------|-------------|
| | flux. | | | |
| С | Gauss's theorem and its an infinitely long straight win plane sheet and uniformly (field inside and outside), c | re, uniformly / charged thin | charged infinite spherical shell | CO1 |
| Unit 2 | Potential | | | |
| A | Electric potential, potentia due to a point charge, | l difference, o | electric potential | CO2 |
| В | a dipole and system of char | ges; equipote | ential surfaces, | CO2 |
| С | Electrical potential energy charges and of electric dipo | | | CO2 |
| Unit 3 | Capacitance | | | |
| A | Conductors and insulator charges inside a conduc polarization. | | - | CO3 |
| В | Capacitors and capacitance plate, Cylindrical and spher | CO3 | | |
| С | Capacitance with and withe the plates of capacitor, ener | | CO3 | |
| Unit 4 | Magnetic Effects of Curre | ent and Magr | netism | |
| А | Biot-Savart law and its aj circular loop, | ~ | | CO4, CO6 |
| В | Ampere's law and its ap straight wire. | oplications to | infinitely long | CO4, CO6 |
| С | Ampere's law and its applie | cations to torc | idal solenoids. | CO4 |
| Unit 5 | Electromagnetism | | | |
| A | Electromagnetic induction | ; Faraday's la | w, induced emf | CO5 |
| В | Lenz's Law, displacement | current. | | CO5 |
| С | Maxwell's Equations in dif and their physical significat | ntegral form | CO5, CO6 | |
| Mode of Examination | Theory | | | |
| Weightage | CA | MTE | ETE | |



| Distribution | 30% | 20% | 50% | id Boundaries |
|---------------------|--------------------------------------|---|-------------------------------------|---------------|
| Text books | - | Magnetism, K.K. ni. ISBN:9788121900 | | |
| Other References | Walker, John V 2. Electricity and | of Physics, Hallic Wiley,2014 ISBN I Magnetism, J. Ya ersity Tutorial Pres | : 9781118230749 arwood and J. H. | |

| Cos | PO | PO | PO | PO | РО | РО | PO | РО | РО | PO1 | PO1 | PO1 | PSO | PSO | PSO |
|---------|-----|-----|-----|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 1 | 2 | 1 | 2 | 3 |
| PHY118. | 3 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 2 | 1 | - | - | - |
| 1 | | | | | | | | | | | | | | | |
| PHY118. | 3 | 3 | 2 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | |
| 2 | | | | | | | | | | | | | | | |
| PHY118. | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - |
| 3 | | | | | | | | | | | | | | | |
| PHY118. | 3 | 3 | 3 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | |
| 4 | | | | | | | | | | | | | | | |
| PHY118. | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - |
| 5 | | | | | | | | | | | | | | | |
| PHY118. | 3 | 3 | 3 | 3 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | |
| 6 | | | | | | | | | | | | | | | |
| PHY118 | 2.8 | 2.7 | 2.5 | 2.5 0 | 2.3 | 1.2 | 1.0 | 1.0 | 1.0 | 1.0 | | 1.0 | - | - | - |



ENGINEERING CHEMISTRY (CHY 111) (TERM I/II)

| Sch | ool: SET | |
|-----|--------------------|--|
| Pro | gram: B.Tech. | |
| Bra | nch: | Semester:2 |
| CS/ | EC/IT/EEE | |
| 1 | Course Code | CHY 111 |
| 2 | Course Title | Chemistry for engineers |
| 3 | Credits | 4 |
| 4 | Contact Hours | 3-1-0 |
| | (L-T-P) | |
| | Course Status | Compulsory |
| 5 | Course | 1. Make it comprehended the importance of clean water. |
| | Objective | Describe to the basic concepts of spectroscopy as described in the module content and is to teach getting of valuable information from the same to apply in various engineering applications. To provide an introduction to the basic concepts in Electrochemistry and apply them to understand batteries and corrosion. To equip the students with the knowledge of modern technologies i.e. nanotechnology and its various engineering applications. |
| 6 | Course Outcomes | Students will be able to understand : Realize the importance of clean and healthy water by giving knowledge about water quality parameters and cleaning measures. In sighting the structural features of material by having the knowledge of spectroscopic techniques. State the main cause of corrosion and prevention measures. Name the components of galvanic cell and applies these to the understand the batteries and corrosion of a metal. |

| | | | HARDA |
|---|-----------------------|---|-----------------------------|
| | | 4. Able to apply the basic information of eng materials and their applications. | gineering |
| | | Able to have a basic knowledge of technology in days i.e. Nanotechnology and its various applicat | |
| | | Have a thorough grounding in chemistry and a worknowledge of advanced chemistry. | king |
| 7 | Course Description | The course includes the fundamentals of The Electrochemistry and batteries, corrosion, in Chemistry of Materials, water technology and na This course satisfies the requirements of the program. | troduction to notechnology. |
| 8 | Outline syllabu | CO Mapping | |
| | Unit 1 | Water: Analysis and its treatment | |
| | A | Water and water treatment: Drinking water standards, Water quality parameters and their measurement: pH (alkalinity and acidity –determination by titrimetry), Turbidity, Dissolved Oxygen (DO), biological oxygen demand (BOD), chemical oxygen demand (COD), chloride, fluoride, oil and fats, | CO1 |
| | В | hardness (definition and expression, estimation of hardness (EDTA method), nutrients (N, P, etc.), nitrate, dissolved metals. | CO1 |
| | С | Municipal water treatment process - screening, sedimentation, flocculation;Coagulation, Filtration (Slow sand and rapid sand), disinfaction-chlorination. | CO1 |
| | Unit 2 | Spectroscopic studies of materials | |
| | A | Principles of spectroscopy and selection rules. Electronic spectroscopy: basic principle, 'Lamberts Beer's law, | CO2 |
| | В | chromophore, effect of conjugation on chromophore and applications, Fluorescence and its applications in medicine. | CO2 |
| | С | Basic principle and applications of Nuclear magnetic | CO2 |



| | resonance and magnetic resonance imaging spectroscopy. | evond Boundari |
|--------|---|----------------|
| Unit 3 | Electrochemistry, energy storage devices and corrosion | |
| A | Electrochemistry: Redox reactions, Nernst Equation, relation of e.m.f. with thermodynamic functions (Δ H, Δ F and Δ S). Electrochemical cells- | CO3 |
| В | Galvanic cells and Concentration cell, electrode potentials and its relevance to oxidation and reduction, measurement of EMF under standard conditions, determination of pH using Hydrogen electrode, | CO3 |
| С | primary battery: dry cells, secondary battery: Lead acid accumulator and Li Ion, fuel cells: H 2- O 2 .Corrosion: Types of corrosion, mechanism of Electrochemical corrosion, galvanic corrosion and protection against electrochemicalcorrosion. | CO3, CO6 |
| Unit 4 | Chemistry of materials | |
| A | :Structure, properties and application of carbon materials such as diamond, graphite, fullerenes, graphene. Liquid crystals: classification, Molecular ordering, identification, polymeric liquid crystals, and application of liquid crystals: displays and thermography. | CO4 |
| В | Organic and inorganic semiconductors.Basic concepts of Conducting polymer, types,p-doping, n-doping, comparison with metallic conductors, examples and applications. | CO4 |
| С | Biodegradable polymers: Basic information with common examplesPolyglycolic acid (PGA), Polyhydroxy butyrate (PHB), Polyhydroxybutyrates-co-beta hydroxyl valerate(PHBV), Polycaprolactone(pcl). | CO4, CO6 |
| Unit 5 | Nano science and technology | |
| A | Introduction to nanoscience and technology, bio- nanoinformation, | CO5, CO6 |

| | | | | SHARDA | | | | |
|------------------------|--|--|--|----------|--|--|--|--|
| В | lithograp CNT's | hy, soft lithograpl | ny, Dip pen nanolithography, | CO5, CO6 | | | | |
| С | | Application of nanotechnology in microelectronics and in memory devices. | | | | | | |
| Mode of examination | Theory | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | |
| Distribution | 30% | 20% | 50% | | | | | |
| Text book/s* | ii. P ii. E o iii. U iv. E v. F vi. Ii F vi. Ii F vii. N | Principles of Plaublishing compan BahlArun, Bahl B. f Physical C. Co.,2000 University chemistr Engineering Chemi B. L. Tembe, Kama Physical Chemistry Introduction to na J. Owens, willeyi Vanotechnology, pportunity, LE fos | notechnology: C.P poole,Jr. nterscience 2003. science, innovation and ster, Pearson education 2007. | | | | | |
| Other | | | uid Crystals", Princeton | | | | | |
| References | U | University PressIS | SBN:9781439811450 | | | | | |
| | |).P. Vermani, A.K hemistry", Galgot | . Narula, "Industrial ia Publications | | | | | |

CO-PO MAPPING EC/EEE

| CO/PO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO 10 | PO 11 | PO 12 | PSO1 | PSO2 | PSO3 |
|----------------------|-----|-----|-----|------|-----|-----|-----|-----|-----|----------|----------|----------|------|------|------|
| CHY 111. 1 | 3 | 1 | 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - |
| CHY 111.2 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - |
| CHY 111.3 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - |
| CHY 111. 4 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - |
| CHY 111. 5 | 3 | 1 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - |
| CHY 111. 6 | 3 | 1 | 2 | 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - |
| CHY 111 | 3.0 | 1.0 | 1.3 | 1.17 | 1.3 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | - |



FEN104: Functional English Intermediate-2 First Year (Odd Semester) SYLLABUS

| | T | T | JILLADOJ | | | | | | | | |
|----------|-----------------------|-------------------|--|------------------------|-----------------------|--|--|--|--|--|--|
| | Course | | | | | | | | | | |
| 1 | number | FEN104 | | | | | | | | | |
| 2 | Course Title | Functiona | al English Intermediate-2 | | | | | | | | |
| 3 | Credits | 1 | | | | | | | | | |
| | Contact | | | | | | | | | | |
| 4 | Hours (L-T-P) | 1-0-0 (| -0-0 (However Contact hours : 2 hrs in a week) | | | | | | | | |
| | Course | A skill-bas | skill-based course designed for undergraduate students with basic understanding of | | | | | | | | |
| 5 | Pre-requisite | English la | nglish language | | | | | | | | |
| | | To guide | guide the students to hone the basic communication skills: listening, speaking, | | | | | | | | |
| | | reading a | ading and writing. | | | | | | | | |
| | | | students to minimize the linguistic and soci | o-cultural barriers ei | merging in a | | | | | | |
| | Course | | environment. | | | | | | | | |
| 6 | Objective | To help st | tudents to understand different accents and | d standardise their e | xisting English. | | | | | | |
| | | | would be able to: | | | | | | | | |
| | | CO1: Utili | ize receptive language skills in order to cor | nprehend complex f | actual/literary | | | | | | |
| | | text | | | | | | | | | |
| | | CO2: Und | lerstand long complex speeches and lectur | es | | | | | | | |
| | | CO3: Com | npose clear and well-structured text to info | orm/express view po | pint | | | | | | |
| | | CO4: Exp | ress opinions about complex subjects by d | eveloping argument | s through | | | | | | |
| | | - | ve language skills | | | | | | | | |
| | | - | ically evaluate arguments in terms of the s | trength of evidence | and reasoning: | | | | | | |
| | | | clusions through discussion | trength of evidence | and reasoning, | | | | | | |
| | | | - | | | | | | | | |
| | | | ognize and apply vocabulary and grammat | ical knowledge to ex | press thought | | | | | | |
| | | and actio | n; | | | | | | | | |
| 7 | Course | | | | | | | | | | |
| 7 | Outcomes | | al Fuelish Internetists 2 | | | | | | | | |
| 8 | Outline syllad | ous: Function | nal English Intermediate-2 TOPICS | Def 9 Chanten | 60- | | | | | | |
| 8.0 | | | | Ref. & Chapter | COs | | | | | | |
| 8.0 1 | FEN104.A | UNIT A | LISTENING & DISCUSSION | | | | | | | | |
| 1 8.0 | FEN104.A | | Class discussion on Steven Spielberg's | | CO1, CO2, | | | | | | |
| 8.0 2 | FEN104.A1 | Topic 1 | Commencement Speech at Harvard | Ref 3, Ref 2 | CO1, CO2, CO5, CO7 | | | | | | |
| 2 | TEN104.AI | | Informative listening (Comprehension): | | | | | | | | |
| 8.0 | | | Lecture by Johan Rockstrom: Let the | | | | | | | | |
| 3 | FEN104.A2 | Topic 2 | Environment Guide our Development | Ref 4, Ref 2 | | | | | | | |
| | 1 21110 7.72 | | Expressing views on lessons learnt from | | - | | | | | | |
| 8.0 | | | the "Inspirational Speech for Students | Doff Dofa | | | | | | | |
| 4 | FEN104.A3 | Topic 3 | by Dr. APJ Abdul Kalam" | Ref 5, Ref 2 | | | | | | | |
| 8.0 | | | READING TEXT & DISCUSSION | <u>I</u> | <u> </u> | | | | | | |
| 5 | FEN104.B | UNIT B | | | | | | | | | |
| | | | Short Stories: "The Tiger in The Tunnel" | Ref 6, Ref 2 | | | | | | | |
| 8.0 | | | by Ruskin Bond (Comprehension & | | CO1, CO5, | | | | | | |
| 6 | FEN104.B1 | Topic 1 | Critical Analysis) | | CO7 | | | | | | |
| - | | | Poetry: "Where the Mind is Without | 1 | | | | | | | |
| 8.0 | | | <i>Fear</i> " by Rabindranath Tagore (Critical | | | | | | | | |
| 7 | FEN104.B2 | Topic 2 | Appreciation and Discussion) | | | | | | | | |
| | | | <i>"The Coffee House of Surat"</i> by Leo | 1 | | | | | | | |
| 8.0 | | | Tolstoy (Comprehension & Critical | | | | | | | | |
| | 1 | 1 | | 1 | | | | | | | |
| 8 | FEN104.B3 | Topic 3 | Analysis) | | | | | | | | |
| 8 8.0 | FEN104.B3 FEN104.C | Topic 3 UNIT C | Analysis) CREATIVE WRITING & DISCUSSION | | | | | | | | |



| 9 | 1 | I | I | 🥿 🎾 Bey | ond Boundaries |
|----------|---------------|------------|---|----------------------|----------------|
| 9 8.1 | | | Short Story Writing | Ref 2 | CO3, CO4, |
| 0 | FEN104.C1 | Topic 1 | | Net 2 | CO5, CO7 |
| 8.1 | | | Picture Interpretation | | 003,007 |
| 1 | FEN104.C2 | Topic 2 | | | |
| 8.1 | | | Review Writing | | |
| 2 | FEN104.C3 | Topic 3 | | | |
| 8.1 | | | TECHNICAL WRITING | | 1 |
| 3 | FEN104.D | UNIT D | | | |
| | | •••••• | Emails & formal Letters | | CO3, CO4, |
| 8.1 | | | | Ref 1 (pages 478 | CO8 |
| 4 | FEN104.D1 | Topic 1 | | to 593) | |
| 8.1 | | Tania 2 | Technical Reports (Informative & | | |
| 5 8.1 | FEN104.D2 | Topic 2 | Routine based) | | |
| 8.1 6 | FEN104.D3 | Topic 3 | Technical Proposal | | |
| 0 | FEINI04.D5 | TOPIC 5 | | | |
| 8.1 | | | VOCABULARY BUILDING AND GRAM | | |
| 7 | FEN104.E | UNIT E | LISTENING THE TEXTS) | | |
| · | | | Phrasal Verbs; Idioms and Phrases; | Ref 2 | CO3, CO6 |
| | | | Proverbs; Functional Vocabulary; | | 000,000 |
| 8.1 | | | Notional Concepts; Connectors and | | |
| 8 | FEN104.E1 | Topic 1 | Linkers | | |
| | | | Text based activities on: Non-finite | | |
| | | | verbs; Reported Speech (Dialogue | | |
| | | | Writing); Passives (Imperative | | |
| 8.1 | | | sentences); Process description; | | |
| 9 | FEN104.E2 | Topic 2 | Spotting error; Relative clauses. | | |
| 8.2 | | | Spellings and Punctuations | | |
| 0 | FEN104.E3 | Topic 3 | | | |
| | | | | | |
| 9 | Course Evalu | ation | | | |
| 9.1 | Course work: | | | | |
| 9.2 | Attendance | None | | | |
| 9.3 | Homework | | nents, no weight | | |
| 9.4 | Quizzes | | zzes (based on assignments); 20 marks | | |
| 9.5 | Lab | | | | |
| | Presentatio | | | | |
| 9.6 | ns | None | | | |
| 9.7 | Any other | None | | | |
| | | One, | | | |
| 9.9 | MTE | 20% | | | |
| 9.1 | | | | | |
| 0 | End-term Exa | | | | |
| 10 | Reference Boo | | | | |
| | | 1. C | ommunication Skills by Sanjay Kumar and P | ushpLata, OUP Public | ations. |
| | Text book | 2. Fi | unctional English Workbook (Intermediate) | 2 | |
| | | 3. St | even Spielberg's Commencemen | it Speech a | t Harvard |
| | | (۲ | https://www.youtube.com/watch?v=TYtoDu | <u>unfu00</u>) | |
| | | 4. Le | | ide our | Development |
| | | | http://www.ted.com/talks/johan_rockstrom | | • |
| | | - | development) | | nt_guide_our |
| | | | | | |
| | Videos and | | spirational Speech for Students | , | vbdul Kalam |
| | Internet | (<u> </u> | <pre>https://www.youtube.com/watch?v=7E-cwo</pre> | dnsiow) | |
| | | | | | |



6. Reading texts

Mapping of Outcomes vs. Topics FILENAME: Functional English Intermediate-2 (FEN104)

| Outcome no. \rightarrow | CO1 | CO2 | CO3 | CO4 | CO5 | CO6 | C07 | CO8 |
|---------------------------|-----|-----|-----|-----|-----|-----|-----|-----|
| | 001 | 02 | 005 | 04 | 005 | 000 | 07 | 008 |
| Syllabus topic↓ | | | | | | | | |
| FEN104.A | Х | Х | | | Х | | Х | |
| FEN104.A1 | Х | Х | | | Х | | Х | |
| FEN104.A2 | х | х | | | х | | Х | |
| FEN104.A3 | Х | Х | | | Х | | Х | |
| FEN104.B | Х | | | | Х | | Х | |
| FEN104.B1 | Х | | | | Х | | Х | |
| FEN104.B2 | Х | | | | Х | | Х | |
| FEN104.B3 | Х | | | | Х | | Х | |
| FEN104.C | | | Х | Х | Х | | Х | |
| FEN104.C1 | | | Х | Х | Х | | Х | |
| FEN104.C2 | | | Х | Х | Х | | Х | |
| FEN104.C3 | | | Х | Х | Х | | Х | |
| FEN104.D | | | Х | Х | | | | х |
| FEN104.D1 | | | Х | Х | | | | Х |
| FEN104.D2 | | | Х | Х | | | | Х |
| FEN104.D3 | | | Х | Х | | | | Х |
| FEN104.E | | | Х | | | Х | | |
| FEN104.E1 | | | Х | | | Х | | |



Engineering Chemistry Lab (CHY-161)

| Sch | ool: SET | | | | | | | | | |
|-----|--|--|-----------------|--|--|--|--|--|--|--|
| Pro | gram: B.Tech | | | | | | | | | |
| | nch: All | Semester: II | | | | | | | | |
| 1 | Course Code | CHY-161 Course Name: Engineering Chemistry Lab |) | | | | | | | |
| 2 | Course Title | Engineering Chemistry Lab | | | | | | | | |
| 3 | Credits | 1 | | | | | | | | |
| 4 | Contact | 0-2 | | | | | | | | |
| | Hours | | | | | | | | | |
| | (L-T-P) | | | | | | | | | |
| | Course Status | Basic Engineering | | | | | | | | |
| 5 | Course | 1. To learn methods for preparation of solution of c | lifferent | | | | | | | |
| | Objective | concentration, their standardization | | | | | | | | |
| | | 2. To learn quantitative estimation of different cher | nical species | | | | | | | |
| | | by various volumetric methods. | | | | | | | | |
| | | 3. To understand the practical concepts of reaction | | | | | | | | |
| | | 4. To understand the procedure for testing of COD | of water | | | | | | | |
| | | samples. | | | | | | | | |
| 6 | Course | CO1 Propose solutions of different strength and standard | lize them | | | | | | | |
| 0 | Outcomes | CO1.Prepare solutions of different strength and standard | | | | | | | | |
| | Outcomes | CO2.Estimate water alkalinity and hardness and hence water quality, the chloride ion/residual chlorine after disinfection | | | | | | | | |
| | | CO3.Understand the different order of reactions like Zer | | | | | | | | |
| | | Second order. | io, i list alla | | | | | | | |
| | | CO4.Prepare simple thermosetting polymers at small sc | ale in | | | | | | | |
| | | laboratory. | | | | | | | | |
| | | CO5.Understand the importance of microbial free water | by testing for | | | | | | | |
| | | COD. | | | | | | | | |
| | | CO6.Understand the basics of analytical chemistry w | which may be | | | | | | | |
| | | helpful to perform major engineering applications. | | | | | | | | |
| 7 | Course | This course include various titration methods like acid- | | | | | | | | |
| | Description | complexometric titration, precipitation titration etc. It | | | | | | | | |
| | | various calculations and units frequently used in analytic | | | | | | | | |
| 8 | Outline syllabu | 15 | CO | | | | | | | |
| | TT | Desperation of standard solution | Mapping | | | | | | | |
| | Unit 1 | Preparation of standard solution | | | | | | | | |
| | A | To prepare N/10 normality solution of sodium carbonate and use it to standardize the given | | | | | | | | |
| | | hydrochloric acid solution. | | | | | | | | |
| | BTo prepare N/30 normality solution of potassium dichromate and use it to standardize the given hypoCO1 | | | | | | | | | |
| | | | | | | | | | | |
| | | solution. To determine the strength of given HCl solution by | | | | | | | | |
| | С | | | | | | | | | |
| | | titrating with standard NaOH solution by (a)Indicator | | | | | | | | |
| | | method (b) pH metrically | | | | | | | | |
| L | 1 | | ı] | | | | | | | |



| | - | | | Beyond Boundaries | | | |
|--------------|--|-------------------------------------|-------------------------------|-------------------|--|--|--|
| Unit 2 | Analysis of w | ater | | | | | |
| А | To determine | the amount an | nd constituents of alkalinity | | | | |
| | of given water | | | | | | |
| В | To determine the hardness of water by EDTA method. | | | | | | |
| С | To determine | CO2 | | | | | |
| | Method. | | | | | | |
| D | To determine | | | | | | |
| | sample. | | | | | | |
| Unit 3 | Synthesis of | | | | | | |
| А | Preparation of | f Bakelite and | Urea formaldehyde resin. | CO3 | | | |
| Unit-4 | Determinatio | Determination of kinetic parameters | | | | | |
| | To determine | e the rate co | onstant and order of the | | | | |
| | reaction of hy | drolysis of an | ester catalyzed by an acid. | | | | |
| | To determine | the rate cons | stant of hydrolysis of ethyl | CO4 | | | |
| | acetate with | NaOH and sh | now that the reaction is of | | | | |
| | second order. | | | | | | |
| Unit-5 | Determinatio | on of COD | | | | | |
| | To determine | the chemical | oxygen demand (COD) in | CO5,CO6 | | | |
| | the given wate | er sample. | | 005,000 | | | |
| | | | | | | | |
| Mode of | Practical | | | | | | |
| examination | | | | | | | |
| Weightage | CA | MTE | ETE | | | | |
| Distribution | 60% | % None 40% | | | | | |
| Text book/s* | Text book, L | ab Manuals | · | | | | |
| Other | Other Deferre | | | | | | |
| References | Other Refere | nces | | | | | |
| | | | | | | | |

CO and PO Mapping

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| CHY161.1 | 2 | 3 | 1 | - | 2 | 1 | 2 | - | 3 | 3 | 2 | 2 | - | - |
| CHY161.2 | 2 | 3 | 1 | - | 2 | 1 | 2 | - | 3 | 3 | 2 | 2 | - | - |
| CHY161.3 | 2 | 3 | 1 | - | 2 | 1 | 2 | - | 3 | 3 | 2 | 2 | - | - |
| CHY161.4 | 2 | 3 | 1 | - | 2 | 1 | 2 | - | 3 | 3 | 2 | 2 | - | - |
| CHY161.5 | 2 | 2 | 2 | - | 2 | 1 | 1 | - | 3 | 3 | 1 | 2 | - | - |
| CHY161.6 | 2 | 2 | 2 | - | 2 | 1 | 1 | - | 3 | 3 | 1 | 2 | - | - |
| CHY161 | 2.0 | 2.7 | 1.3 | | 2.0 | 1.0 | 1.7 | | 3.0 | 3.0 | 1.7 | 2 | - | - |



| | am: B.Tech h: ECE | |
|---|--------------------------|--|
| 1 | Course Code | ECP 120 |
| 2 | Course Title | Mechanical Workshop |
| 3 | Credits | 1.5 |
| 4 | Contact Hours (L-T-P) | 0-0-3 |
| | Course Status | Compulsory |
| 5 | Course Objective | The objective of this course is to make the students, familiar with the modern day manufacturing processes, introduce them to various hand tools and equipment, acclimatize with the measuring devices, and perform basic machine tool operations in various machine tools. |
| 6 | Course Outcomes | On successful completion of this course, students will be able to CO1: Apply 5S (Seiri,Seiton, Seiso,Seiketsu and Shitsuke) methodology at workplace. CO2: Select the various hand tools used in the basic mechanical engineering workshop sections-smithy, carpentry, assembling, welding etc. CO3: Choose different measuring devices according to the job CO4: Differentiate between various machine tools and their operation CO5: Classify and select suitable tools for machining processes including turning, facing, thread cutting and tapping, milling, drilling and shaping. CO6: Apply the knowledge for advanced manufacturing experiments. |
| 7 | Course Description | Black Smithy Shop: Simple exercises based on black smithy operations such as upsetting, practice of S -Hook from circular bar using hand forging operations. Carpentry Shop : Study of different types of wood , Carpentry Tools, Equipment and different joints, Practice of T joint, cross lap joint, Mortise and Tenon T joint, Bridle T joint Fitting Shop: Preparation of Square joint, V joint, half round joint, dovetail jointas per the given specifications, which contains: Sawing, Filing, Grinding, and Practice marking operations. Sheet Metal Shop: Study of galvanized Iron (G.I.) Sheet material properties, hand tools and sheet metal machines, and projective geometry, demonstration of different sheet metal operations and practice of development of Tray, cylinder, hopper, funnel etc. Welding Shop: Introduction, Study of Tools and welding Equipment (Gas and Arc welding), Selection of welding electrode and current, Bead practice and Practice of Butt Joint, Lap Joint. |

| | | | | SH UNI Beyon | ARDA VERSITY | |
|--------|------------------------|---|---|---|---|--|
| | | parts, different operations on I taper turning, k Shaper. Foundry Sho ingredients of | operations, stud Lathe machine, la cnurling and par p: Introduction moulding sand p of mould prep | nine tools in particular Lathe mach dy of cutting tools), Demonstration Practice of Facing, Plane Turning, rting and Study of Quick return n n to foundry, Patterns, pattern and melting furnaces. Foundry to paration and Practice – Preparation | n of different step turning, nechanism of allowances, ols and their | |
| 8 | Outline syllabus | | | | CO Mapping | |
| | List of Experiments | | | | | |
| Unit 1 | Experiment 1 | To make a S-sl forging techniq | | n a given circular rod using hand | CO1 | |
| | Experiment 2 | | etail lap joint in (| Carpentry shop. | CO1 | |
| Unit 2 | Experiment 3 | | | n Carpentry shop. | CO2 | |
| | Experiment 4 | shop. | | iven mild steel pieces in fitting | CO2 | |
| Unit 3 | Experiment 5 | To prepare a v shop. | V-Fit from the | given mild steel pieces in fitting | СО3, | |
| | Experiment 6 | To make a recta shop. | angular tray of s | pecified dimensions in sheet metal | CO3 | |
| Unit 4 | Experiment 7 | To make a Lap welding. | joint, using the | given mild steel pieces using arc | CO4 , CO6 | |
| | Experiment 8 | To perform step work piece | turning and tap | er turning operations on the given | CO4, CO6 | |
| Unit5 | Experiment 9 | To prepare a sa | nd mold, using t | he given single piece pattern | CO5, CO6 | |
| | Experiment 10 | To prepare a s | and mold, usin | g the given Split-piece pattern. | CO5, CO6 | |
| | Mode of | Practical | | | | |
| | examination | | | | | |
| | Weight- age | СА | MTE | ETE | | |
| | Distribution | 60% | 0% | 40% | | |
| | Text book/s* | DhanpathRai 2. Kannaiah | & SonsISB P. and Naray | Workshop Technology Vol N:9788120340824 vana K.L., Workshop Manual 9788122419177, | | |



| COs | P01 | P02 | P03 | P04 | PO5 | P06 | P07 | P08 | P09 | PO10 | P011 | P012 | PS01 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| MEP105.1 | - | - | - | - | - | 2 | - | 2 | - | - | - | 2 | - | - | - |
| MEP105.2 | 1 | - | - | - | 1 | 2 | - | - | - | - | - | 1 | 1 | 1 | - |
| MEP105.3 | 2 | - | - | - | 1 | 2 | - | - | - | - | - | 2 | 1 | 1 | - |
| MEP105.4 | 2 | - | 1 | - | 2 | 2 | - | - | - | - | - | 2 | 1 | 1 | - |
| MEP105.5 | 2 | - | 1 | - | 2 | 2 | - | - | - | - | - | 2 | 2 | 1 | - |
| MEP105.6 | 2 | - | 1 | - | 2 | 2 | - | - | - | - | - | 2 | 2 | - | 1 |
| MEP105 | 2 | - | 1 | - | 2 | 2 | - | - | - | - | - | 2 | 2 | - | 1 |



Tinkering Labs

| Pr Br | hool: SET ogram: B.TEC anch: EEE mester:2 | ĊH | | | | | | | | |
|----------|--|-------------|--------------|--------------------------------------|------------------|--|--|--|--|--|
| 1 | Course Code | ECP10 |)7 | | | | | | | |
| 2 | Course Title | | | | | | | | | |
| 3 | Credits | 1 | ing Labs | | | | | | | |
| 4 | Contact Hours | _ | | | | | | | | |
| | (L-T-P) | | | | | | | | | |
| | Course Status | Compu | ulsory | | | | | | | |
| 5 | Course Objective | • | To be acqua | ainted with hardware's in Consumer E | lectronics goods | | | | | |
| 6 | Course Outcomes | ts. | | | | | | | | |
| 7 | Course | | | e their Knowledge on consumer produ- | | | | | | |
| | Description | | | | | | | | | |
| 8 | Outline syllab | us | | | CO Mapping | | | | | |
| | Unit 1 | Inside Ce | ll phone Ch | arger | | | | | | |
| | А | Unscrew | • | | CO1 | | | | | |
| | В | Identifyin | g parts | | CO1 | | | | | |
| | С | Working | 01 | | CO1, CO6 | | | | | |
| | Unit 2 | Mobile pl | iones | | | | | | | |
| | А | Unscrew | | | CO2 | | | | | |
| | В | Identifyin | g parts | | CO2 | | | | | |
| | С | Working | | | CO2, CO6 | | | | | |
| | Unit 3 | USB | | | | | | | | |
| | А | Basics | | | CO3 | | | | | |
| | В | Inside US | B cable/Port | | CO3 | | | | | |
| | С | Working | | | CO3, CO6 | | | | | |
| | Unit 4 | Speakers | | | | | | | | |
| | А | Unscrew | | | CO4 | | | | | |
| | В | Identifyin | g parts | | CO4 | | | | | |
| | С | Working | | | CO4, CO6 | | | | | |
| | Unit 5 | Compute | rs | | | | | | | |
| | А | Unscrew CO5 | | | | | | | | |
| | В | Identifyin | g parts ,Wor | king | CO5 | | | | | |
| | С | Screw up | | | CO5, CO6 | | | | | |
| | Mode of | Practical & | & Viva | | | | | | | |
| | examination | | | | | | | | | |
| | Weightage | CA | MTE | ETE | | | | | | |
| | Distribution | 60% | 0% | 40% | | | | | | |
| | Text | Lab Manu | als | · | | | | | | |
| | | • | | | | | | | | |



| book/s* | | d Boundaries |
|------------|---|--------------|
| Other | https://www.youtube.com/watch?v=WNRzU5DLA0I | |
| References | https://www.youtube.com/watch?v=jghFENiUsBI | |

| Cos | P01 | P02 | P03 | P04 | P05 | P06 | P07 | P08 | P09 | P010 | P011 | P012 | PS01 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ECP107.1 | 3 | 1 | 1 | - | 1 | 2 | 1 | - | 2 | 1 | - | 1 | 1 | 1 | 2 |
| ECP107.2 | 3 | 1 | 1 | - | 1 | 2 | 1 | - | 2 | 1 | - | 1 | 1 | 1 | 2 |
| ECP107.3 | 3 | 1 | 1 | - | 1 | 2 | 1 | - | 2 | 1 | - | 1 | 1 | 1 | 2 |
| ECP107.4 | 3 | 1 | 1 | - | 1 | 2 | 1 | - | 2 | 1 | - | 1 | 1 | 1 | 2 |
| ECP107.5 | 3 | 1 | 1 | - | 1 | 2 | 1 | - | 2 | 1 | - | 1 | 1 | 1 | 2 |
| ECP107.6 | 3 | 1 | 1 | - | 1 | 2 | 1 | - | 2 | 1 | - | 1 | 1 | 1 | 2 |
| ECP107 | 3.0 | 1.0 | 1.0 | | 1.0 | 2.0 | 1.0 | | 2.0 | 1.0 | | 1.0 | 1.0 | 1.0 | 2 |

| * | SHARDA |
|---|---------------------------------|
| | UNIVERSITY Beyond Boundaries |

| School Techno | l: School of Engineering and ology | Neyond Bou | |
|------------------|---------------------------------------|--|---|
| Progra | ım: B.Tech. | | |
| Branch | 1: Physics | Semester: I,II | |
| 1 | Course Code | PHY 161 | |
| 2 | Course Title | Physics Lab 1 | |
| 3 | Credits | 1 | |
| 4 | Contact Hours (L-T-P) | 0-0-2 | |
| | Course Status | Compulsory | |
| 5 | Course Objective | To gain practical knowledge by applying the experimental method with the Physics theory. | s to correlate |
| 6 | Course Outcomes | On successful completion of the course the students will have: CO1: Knowledge and study of basic physics experiments base harmonic motion CO2: Use the concept of stress, strain to calculate modulus of rigi modulus. CO3: Understand how to determine moment of inertia of different CO4: Understand how to draw characteristic curves of different CO4: Understand how to calculate frequency using Melde's Experin CO5: Understand how to calculate frequency using Melde's Experin CO6: Apply the mathematical concepts/equations to obtain quantia and ability to conduct, analyze and interpret experiments | dity, Young's bodies. nt electronic ment |
| 7 | Outline Syllabus | | CO Mapping |
| | Unit 1 | | |
| | А | 1. To verify the relation of time period using simple | CO1 |
| | B C | pendulum.2. To determine the acceleration due to gravity and radius of Gyration of compound pendulum and compare with | |
| | | theoretical value. | |
| | Unit 2 | 2. To measure the memory of inertia of a flow heal | |
| | A | To measure the moment of inertia of a flywheel. To determine the Young's modulus of a beam using | 603 |
| | B C | 4. To determine the roung's modulus of a beam using cantilever beam experiment apparatus.5. To determine vertical distance between two points using sextant. | CO2 |
| | Unit3 | | |
| | A B | 6. To determine the modulus of rigidity of a material of a given wire with an inertia table (torsion pendulum) by | CO3 |
| | С | dynamical method. 7. To calculate Moment of inertia of different irregular shapes. | CO4 |
| | Unit 4 | | |
| | A | 8. To determine the frequency of an electrically maintained | |
| | В | tuning fork using Melde's Apparatus. (i) Transverse mode of vibration (ii) Longitudinal mode of vibration. | CO4,CO6 |
| | С | To determine the coefficient of viscosity of water by Poiseuille's method. | |
| | Unit 5 | | |
| | A | 10. To draw the characteristic curve of a PN junction diode. | |
| | B C | 11. To trace the circuit of a Half Wave Rectifier circuit and determine efficiencies and ripple factors with capacitor and inductor filters. | CO5,CO6 |



| | 1 | | Beyond Boundaries | | | | | | | | | | |
|------------------------|--|--|---------------------|--|--|--|--|--|--|--|--|--|--|
| | | 12. To trace the circuit of a Full Wave Rectifier circuit and determine efficiencies and ripple factors with capacitor and inductor filters. | | | | | | | | | | | |
| Mode of Examination | Mode of Examination Practical/Viva | | | | | | | | | | | | |
| Weightage Distribution | CA | ETE | | | | | | | | | | | |
| | 60% | 0% | 40% | | | | | | | | | | |
| Text books | 1. B.Sc. Practical Physics- | Harnam Singh, S. Chanc | l Publishing. | | | | | | | | | | |
| | 2. B.Sc. Practical Physics- | C L Arora, S. Chand Pub | lishing. | | | | | | | | | | |
| Other References | 1. GeetaSanon, BSc Pract | ical Physics, 1st Edn. (20 | 07), R. Chand & Co. | | | | | | | | | | |
| | 2. B. L. Worsnop and H. T. Flint, Advanced Practical Physics, Asia | | | | | | | | | | | | |
| | Publishing House, New | | | | | | | | | | | | |

| Cos | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| PHY161.1 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | 3 | 3 | 2 | 3 | - | - | - |
| PHY161.2 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | 3 | 3 | 2 | 3 | - | - | - |
| PHY161.3 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | 3 | 3 | 2 | 3 | - | - | - |
| PHY161.4 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | 3 | 3 | 2 | 3 | - | - | - |
| PHY161.5 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | 3 | 3 | 2 | 3 | - | - | - |
| PHY161.6 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | 3 | 3 | 2 | 3 | - | - | - |
| PHY161 | 2.0 | 2.0 | 2.0 | 1.0 | 1.0 | 1.0 | 2.0 | 3.0 | 3.0 | 3.0 | 2.0 | 3.0 | - | - | - |



III TERM

SU/SET/B. Tech./EEE

Page 42



| | 1 000 | | Beyon |
|-----|--------------------------|---|------------------------------|
| | ool: SET | | |
| | gram: B. Tech. | | |
| Bra | | Semester: 03 | |
| | E/EE/ECE | EEE220 | |
| 1 | Course Code | EEE220 | |
| 2 | Course Title | Network Analysis and Synthesis | |
| 3 | Credits | 3 | |
| 4 | Contact Hours (L-T-P) | 3-0-0 | |
| | Course Status | Compulsory | |
| 5 | Course Objective | To develop problem solving skills and understanding of cir through the application of techniques and principles of ele analysis to common circuit problems. | - |
| | | After successful completion of the course, student will be a CO1 Obtain circuit matrices of linear graphs and analyze using graph theory CO2 Select appropriate and relevant technique for solving network in different conditions | networks |
| 6 | Course Outcomes | CO3 Learn conditions for stability and realizability of net functions CO4 Solve two port network functions CO5 Synthesize driving point functions of RL, RC and R | |
| | | CO6 Apply mathematics in analyzing and synthesizing the time and frequency domain. | ne networks in |
| 7 | Course Description | This course deals with the fundamentals of electric components and the mathematical tools used to represent electrical circuits. It also deals with analysis of stability of transfer function and also to design circuit from transfer fur- | nt and analyze network using |
| 8 | Outline syllabus | S | CO Mapping |
| | Unit 1 | GRAPH THEORY | |
| | А | Graph of a network, definitions, tree, co tree, link, basic loop and basic cut set | CO1, CO2 |
| | В | Incidence matrix, cut set matrix, tie set matrix | CO1, CO2 |
| | С | Duality, loop and node methods of analysis | CO1, CO2 |
| | Unit 2 | NETWORK THEOREMS (FOR AC NETWORKS) | |
| | А | Super-position theorem, Thevenin's theorem, Norton's theorem, Maximum power transfer theorem | CO1, CO2 |
| | В | Reciprocity theorem, Millman's theorem | CO1, CO2 |
| | С | Compensation theorem, Tellegen's theorem | CO1, CO2 |
| | Unit 3 | NETWORK FUNCTIONS | |



| _ | | | | | Beyon |
|---|--------------|-------------------------------|-------------------|----------------------------------|----------|
| | A | - | | ncy, Transform Impedances | CO3, CO6 |
| | | | 1 | ort and two port networks, | |
| | В | | | properties of driving point and | CO3 |
| | | transfer funct | | | |
| | С | 1 | | from pole zero plot | CO3 |
| | Unit 4 | TWO PORT | NETWORKS | 5 | |
| | А | Characterizat and h parame | | port networks Z, Y, ABCD | CO2, CO6 |
| | В | Reciprocity a | nd symmetry, | Inter-relationships between | CO2 |
| | | the parameter | 'S | - | |
| | С | Inter-connect | ions of two poi | rt networks, Ladder and Lattice | CO2 |
| | | networks, T & | k П Representa | ation | |
| | Unit 5 | NETWORK | SYNTHESIS | | |
| | А | Positive real | function: definit | ition and properties, properties | CO4,CO5 |
| | | of LC, RC an | d RL driving p | oint functions | |
| | В | Synthesis of I | LC, RC and RI | driving point immittance | CO4, CO5 |
| | | functions usin | ng Foster and C | Cauer first and second forms | |
| | C | | | ctive filter fundamentals, low | CO4, CO5 |
| | | 1 0 1 | ss, band pass, b | and elimination filters. | |
| | Mode of | Theory | | | |
| | examination | | 1 | 1 | |
| | Weightage | CA | MTE | ETE | |
| | Distribution | 30% | 20% | 50% | |
| | Text book/s* | Franklin F. K | uo,"Network | Analysis and Synthesis", John | |
| | | Wiley & Son | s ISBN:978812 | 26510016, 8126510013 | |
| | Other | 1. M.E. Van | Valkenburg," | Network Analysis", Prentice | |
| | References | Hall of India | ISBN:9788131 | 701584, 8131701581 | |
| | | 2. Donald E. | Scott: "An Intr | oduction to Circuit analysis: A | |
| | | System App | oroach" McG | raw Hill Book Company. | |
| | | | 0561274, 0070 | | |
| | | • | | emmerly, Engineering Circuit | |
| | | - | ata McGraw | Hill. ISBN:9789814646345, | |
| | | 9814646342 | | | |

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SU/SET/B. Tech./EEE



COURSE ARTICULATION MATRIX:

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|-----|------|-----|-----|------|------|------|------|------|------|
| CO1 | 3 | 2 | 1 | 1 | | | 2 | | | | | | 2 | | |
| CO2 | 3 | 3 | 1 | 2 | | | | | | | 2 | | 3 | 3 | |
| CO3 | 3 | 3 | 3 | 3 | 2 | | 3 | | | | 2 | | 3 | 3 | |
| CO4 | 3 | 2 | 2 | 2 | 1 | | | | | | | | 2 | 1 | |
| CO5 | 3 | 2 | 1 | 1 | 2 | | 3 | | | | 2 | | 2 | 2 | |
| CO6 | 3 | 2 | 2 | 2 | | | | | | | | | 2 | 1 | |
| | 3.00 | 2.33 | 1.67 | 1.83 | 1.67 | | 2.67 | | | | 2.00 | | 2.33 | 2.00 | |

SU/SET/B. Tech./EEE



| Sch | ool: SET | | |
|-----|------------------------------|---|-------------------------------------|
| Pro | gram: B.Tech | | |
| | nch: EEE/EE | Semester: 3 | |
| 1 | Course Code | EEE221 | |
| 2 | Course Title | Electrical Machines-I | |
| 3 | Credits | 3 | |
| 4 | Contact Hours (L-T-P) | 3-0-0 | |
| | Course Status | Compulsory | |
| 5 | Course Objective | To provide students with: 1. knowledge of basic principles of electromechanical energy 2. the understanding of operation principles of electrical mac 3. ability to analyse different electrical machines | |
| 6 | Course Outcomes Course | 1: After completion of this course students will be able to: CO 1. Understand the concepts of magnetic circuits. CO 2. describe the basic energy conversion principles and di magnetic field systems CO 3. Understand the operation of dc machines CO 4. Analyse the differences in operation of different dc maconfigurations. CO 5. Analyse single phase and three phase transformers circuits CO 6 Combine an understanding of the established principle concepts and terminology relevant to electrical machines wit application. | achine rcuits. les, theories, |
| , | Description | The course covers the basics of electromechanical energy co- electrical machines. The operating principles of DC machine transformers are thoroughly described as well as their testing control methods. | es and |
| 8 | Outline syllabu | 15 | CO Mapping |
| | Unit 1 | Magnetic fields, Electromagnetic force and torque | |
| | A | Review of magnetic circuits - MMF, flux, reluctance, inductance; Visualization of magnetic fields produced by a bar magnet and a current carrying coil - through air and through a combination of iron and air | CO1,CO6 |
| | В | Influence of highly permeable materials on the magnetic flux lines. B-H curve of magnetic materials, energy stored in the magnetic circuit | CO1 |
| | С | force as a partial derivative of stored energy with respect to position of a moving element; torque as a partial derivative of stored energy with respect to angular position of a rotating | CO2 |



| | element. | | | | | | |
|-------------|--|---------|--|--|--|--|--|
| Unit 2 | DC machines | | | | | | |
| А | Basic construction of a DC machine, visualization of magnetic | CO3, CO | | | | | |
| | field produced by the field winding excitation with armature | | | | | | |
| | winding open, air gap flux density distribution, flux per pole ; | | | | | | |
| | Armature winding and commutation - Elementary armature coil | | | | | | |
| | and commutator, lap and wave windings, construction of | | | | | | |
| | commutator | | | | | | |
| В | DC generator: principle of operation, induced EMF in an | CO3 | | | | | |
| | armature coil, commutation, methods of improving | | | | | | |
| | commutation, parallel operation of DC generator | | | | | | |
| С | DC Motor: principle of operation, Derivation of back EMF | CO3, CC | | | | | |
| | equation, derivation of torque equation | | | | | | |
| Unit 3 | DC machine – Speed Control and Testing | | | | | | |
| A | Armature reaction, Cross magnetizing and de-magnetizing | CO3, CC | | | | | |
| | AT/pole, Types of field excitations - separately excited, shunt | , _ 0 | | | | | |
| | and series. Characteristics of separately excited and self-excited | | | | | | |
| | generators, build-up of EMF, critical field resistance and critical | | | | | | |
| | speed | | | | | | |
| В | Characteristics and torque-speed characteristics of separately | | | | | | |
| D | excited, shunt and series motors. Speed control of DC Motors: | | | | | | |
| | armature voltage and field flux control methods. Ward-Leonard | CO3, CC | | | | | |
| | system | 005,00 | | | | | |
| С | Losses of DC machines: constant and variable losses, calculation | CO4 | | | | | |
| C | of efficiency, condition for maximum efficiency. DC machine | 001 | | | | | |
| | Testing: direct, indirect and regenerative testing: brake test, | | | | | | |
| | Swinburne's test, Hopkinson's test, field's test, | | | | | | |
| Unit 4 | Transformers | | | | | | |
| A | Principle, construction and operation of single-phase | CO5, CC | | | | | |
| | transformers, EMF equation, equivalent circuit, phasor | , | | | | | |
| | diagram, voltage regulation, losses and efficiency, condition for | | | | | | |
| | maximum efficiency, All day efficiency, regulation and | | | | | | |
| | condition for maximum voltage regulation | | | | | | |
| В | Three-phase transformer - construction, types of connection | CO5 | | | | | |
| | and their comparative features, Parallel operation of single- | | | | | | |
| | phase and three-phase transformers, | | | | | | |
| С | Autotransformers - construction, principle, applications and | CO5 | | | | | |
| | comparison with two winding transformer | | | | | | |
| Unit 5 | Transformers Testing | | | | | | |
| А | Testing - open circuit and short circuit tests, polarity test, back- | CO5, CO | | | | | |
| | to-back test, separation of hysteresis and eddy current losses | | | | | | |
| В | Poly phase connections, third harmonics and their effect | CO5 | | | | | |
| С | three winding transformers, tertiary winding, Scott connection | CO5 | | | | | |
| Mode of | Theory/Jury/Practical/Viva | | | | | | |
| examination | moory, sury, radioul, viva | | | | | | |
| v.a.mation | CA MTE ETE | + | | | | | |



| Distribution | 30% | 20% | 50% | |
|---------------------|------------------------------------|---|---|------------------------------------|
| Text book/s* | | chines by I.J. N ers. , ISBN 125 | agrath & D.P. Kothari, Tata 9081532 2010 | Mc Graw – |
| Other References | Ma 201 2. 2. <i>A</i> and | chinery", Nev 4. ISBN:978 A. E. Clayton design of DC | and C. Kingsley, "Electric v York, McGraw Hill Edu 0071326469, 0071326464 and N. N. Hancock, "Perf C machines", CBS Publish 0852268131, 0852268130 | ucation, 4 formance ners, |

COURSE ARTICULATION MATRIC

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|-----|-----|-----|------|------|------|------|------|------|------|
| CO1 | 3 | 2 | 2 | 2 | 2 | | | | 1 | | | | 2 | 2 | 2 |
| CO2 | 3 | 2 | 3 | 2 | 3 | | | | 1 | | | | 2 | 2 | 3 |
| CO3 | 3 | 3 | 3 | 2 | 3 | | | | 1 | | | | 3 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 3 | 3 | | | | 1 | | | | 3 | 3 | 3 |
| CO5 | 3 | 3 | 3 | 2 | 3 | | | | 1 | | | | 2 | 3 | 3 |
| CO6 | 3 | 3 | 2 | 3 | 3 | | | | 1 | | | | 3 | 2 | 3 |
| | 3.00 | 2.67 | 2.67 | 2.33 | 2.83 | | | | 1.00 | | | | 2.50 | 2.50 | 2.83 |

SU/SET/B. Tech./EEE



| Sch | ool: SET | | |
|-----|------------------|--|--------------------|
| | gram: B.Tech | | |
| | nch: EEE/EE | Semester: 3 | |
| 1 | Course Code | EEP221 | |
| 2 | Course Title | Electrical Machines-I Lab | |
| 3 | Credits | 1 | |
| 4 | Contact Hours | 0-0-2 | |
| | (L-T-P) | | |
| | Course Status | Compulsory | |
| 5 | Course | The capability to analyze the operation of electric machine | s under |
| | Objective | different loading conditions | |
| | 5 | The ability to conduct testing and experimental procedures | on different |
| | | types of electrical machines. | |
| | | | |
| 6 | Course | CO1: Experimentally obtain the load characteristics of var | ious dc motors |
| | Outcomes | and generators. | |
| | | CO2: Determination of various performance curves of DO | C Motor |
| | | CO3: Experimentally perform speed control of DC motor | |
| | | CO4: Understand the concept of efficiency and the short ci | |
| | | impedance of a single-phase transformer from no-load test | , winding |
| | | resistance, short circuit test, and load test | <i>c</i> |
| | | CO5: Understand the concept of parallel operation of trans | |
| | | CO6 Combine an understanding of the established princ. | • · · · · · |
| | | concepts and terminology relevant to electrical machines v application. | vitii practical |
| 7 | Course | | |
| , | Description | | |
| | Description | The course covers practical experiment on transformers an | d |
| | | DC machines. It includes load test on various dc machines | |
| | | transformer and also speed control of DC motor. | |
| | | I I I I I I I I I I I I I I I I I I I | |
| | | | |
| | | | |
| 8 | Outline syllabus | | CO Mapping |
| | Unit 1 | Practical based on Load Test of DC Generator | |
| | | Load test on DC shunt generator and determination of | CO1,CO6 |
| | | characteristics. | |
| | | Load test on DC series generator and determination of | CO1 |
| | | characteristics. | CO1 |
| | | Load test on DC compound generator and determination of | CO1 |
| | Unit 2 | characteristics. Practical related to Characteristic of DC Generator | |
| | | | CO1 |
| | | Magnetization characteristics of DC shunt generator and determination of critical field resistance and critical speed. | |
| | | determination of entical neithresistance and entical speed. | + |
| | | | <u> </u> |



| Unit 3 | Practical rel | ated to DC | ² Motor | |
|---------------------|-----------------------------------|--------------|----------------------------|----------|
| | Swinburne's | test of DC M | achine | CO2, CO6 |
| | Brake test on | DC compou | nd motor and determination | of CO2 |
| | performance | curves. | | |
| | Hopkinson te | st on two id | entical DC machine. | CO2 |
| | Brake test on | DC shunt mo | otor and determination of | CO2 |
| | performance of | curves. | | |
| | speed control efficiency. | of DC shunt | motor and predetermination | of CO3 |
| Unit 4 | Practical rel | ated to Tes | sting of Transformer | |
| | OC and SC test | CO4, CO6 | | |
| | Sumpner's tes | CO4 | | |
| | To perform loa | CO4 | | |
| Unit 5 | Practical rel | | | |
| | Parallel operat | CO5, CO6 | | |
| | Polarity test o | | | |
| | Study of Scott | | | |
| Mode of examination | Jury/Practica | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 60% | 0% | 40% | |
| Text book/s* | Electric Machi – Hill Publishe | c Graw | | |
| Other | 1. A.E. | Fitzgerald | and C. Kingsley, "Electric | |
| References | Mach | inery", Nev | v York, McGraw Hill Educ | ation, |
| | 2014. | ISBN:978 | 0071326469, 0071326464 | |
| | 2. A. | | | |
| | | CBS | | |
| | | | d design of DC machines", | |
| | | | . ISBN:9780852268131, | |
| | 08522 | 268130 | | |

COURSE ARTICULATION MATRIX:



| | 1 | 1 | | | | | | | | | | | | | |
|-----|------|------|------|------|------|-----|-----|-----|-----|------|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 3 | 2 | 2 | 1 | 3 | | | | | | | | 3 | 3 | 3 |
| CO2 | 3 | 2 | 2 | 2 | 3 | | | | | | | | 2 | 2 | 3 |
| CO3 | 3 | 3 | 2 | 2 | 2 | | | | | | | | 3 | 3 | 2 |
| CO4 | 3 | 2 | 3 | | 3 | | | | | | | | 2 | 3 | 3 |
| CO5 | 3 | 2 | 2 | | 3 | | | | | | | | 2 | 2 | 3 |
| CO6 | 3 | 3 | 2 | 2 | 3 | | | | | | | | 3 | 2 | 2 |
| | 3.00 | 2.33 | 2.17 | 1.75 | 2.83 | | | | | | | | 2.50 | 2.50 | 2.67 |



IV TERM

SU/SET/B. Tech./EEE



| | ool: SET | | |
|---|--------------------------|---|----------------|
| | gram: B.Tech | | |
| | nch: EEE/EE | Semester: 4 | |
| 1 | Course Code | EEE224 | |
| 2 | Course Title | Electrical Machines-II | |
| 3 | Credits | 3 | |
| 4 | Contact | 3-0-0 | |
| | Hours | | |
| | (L-T-P) Course Status | Compulsory | |
| 5 | Course Status Course | Compulsory To provide students with: | |
| 5 | Objective | To provide students with: 1. fundamentals of AC machine construction | |
| | Objective | 2. the understanding of operation principles of AC electrical | machines |
| | | 3. ability to analyse performance characteristics of ac machin | |
| 6 | Course | After completion of this course students will be able to: | |
| 0 | Outcomes | CO 1. Understand the concepts of rotating magnetic field. | |
| | 0 | CO 2. demonstrate the operation of Synchronous generator a | nd motor |
| | | CO 3. define, analyse and solve problem based on Three-pha | |
| | | machine | |
| | | CO 4. identify the problem in three-phase Induction motor starting | ng and analyse |
| | | different type of starters | |
| | | CO 5. analyse the principle of operation of special electrical | |
| | | CO6 Combine an understanding of the established principl | |
| | | concepts and terminology relevant to electrical machines wit | h practical |
| | | application. | |
| 7 | Course | | |
| | Description | This course provides a basic understanding of AC maching | • |
| | | fundamentals, constructional features, operational analysis phasor diagrams, equivalent circuits, determination of perfe | |
| | | parameters, testing and applications | ormance |
| | | parameters, testing and appreations | |
| 8 | Outline syllabu | 18 | CO Mapping |
| | Unit 1 | Fundamentals of AC machine windings | |
| | А | Physical arrangement of windings in stator and cylindrical rotor; | CO1,CO6 |
| | | slots for windings; single turn coil - active portion and overhang; | |
| | В | full-pitch coils, concentrated winding, distributed winding, | CO1 |
| | | winding axis, 3D visualization of the above winding types | |
| | C | Air-gap MMF distribution with fixed current through winding - | CO1 |
| | | concentrated and distributed, Sinusoidally | |
| | | distributed winding, winding distribution factor | |
| | Unit 2 | Synchronous machines | |
| | А | Principle of rotating magnetic field, Constructional features, | CO2, CO6 |
| | | cylindrical rotor synchronous machine, Salient pole, generated | |
| | | EMF, equivalent circuit and phasor diagram, armature reaction, | |
| | | voltage regulation: EMF, MMF, ZPF and ASA methods. | |



| В | Synchronous | motor: Prin | ciple of operation, | Starting methods. | CO2 | | |
|--------------|---|---------------------|-----------------------|---|----------|--|--|
| | Operating cha | aracteristics | of synchronous r | nachines, V- | | | |
| | curves. Salier | <u>t pole mac</u> ł | ine – two reactio | on theory, | | | |
| С | Analysis of ph | asor diagra | m, power angle c | haracteristics. | CO2 | | |
| | Parallel opera | tion of alte | rnators - synchroi | nization and | | | |
| | load division | | | | | | |
| Unit 3 | 3- Phase Induc | tion Machin | es | | 1 | | |
| A | Principle of op | eration, cons | tructional details, | types of rotors, | CO3,CO6 | | |
| | | | ue characteristics. | ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | , | | |
| | | | | | | | |
| В | Condition for r | power, losses | | | | | |
| | and efficiency, | rotor tests, | | | | | |
| | cogging and cr | on of no load | CO3 | | | | |
| | losses. | | | | | | |
| С | Double cage ro | otor, inductio | n generator. | | CO3 | | |
| Unit 4 | Starting and S | peed Contro | of 3-Phase Induct | ion Motor | | | |
| А | Requirements | for starters, | types of starters: st | ator resistance | CO4,CO6 | | |
| | and reactance, | ner and star-delta | | | | | |
| | starters. | | | | | | |
| В | Speed control: | change of vo | oltage, torque, num | nber of poles and | CO4 | | |
| | slip. | | | | CO4 | | |
| С | V/f control method, cascaded connection, slip power recovery | | | | | | |
| | scheme. | | | | | | |
| Unit 5 | Special Electrical Machines | | | | | | |
| А | Single phase induction motor, double revolving field theory and | | | | | | |
| | operation and its type | | | | | | |
| В | Principle of operation and constructional features of universal | | | | | | |
| ~ | and stepper motors | | | | | | |
| C | Principle of operation and constructional features of brushless | | | | | | |
| | DC motor and servomotor | | | | | | |
| | | | | | | | |
| Mode of | Theory/Jury/I | Practical/Vi | Va | | | | |
| examination | <u></u> | | DED | | + | | |
| Weightage | CA | MTE | ETE | | | | |
| Distribution | 30% | 20% | 50% | | <u> </u> | | |
| Text book/s* | Electric Machi Hill Publishers | | grath & D.P. Kotha | ri, Tata Mic Graw – | | | |
| Other | | | | Floatria | | | |
| References | | e | nd C. Kingsley, " | | | | |
| References | | | York, McGraw H | | | | |
| | 2014. | ISBN:9780 | 071326469, 0071 | 326464 | | | |
| | 2. A. I | E. Clayton a | nd N. N. Hancocl | k, "Performance | | | |
| | and de | esign of DC | machines", CBS | Publishers, | | | |
| | | 0 | 852268131, 0852 | | 1 | | |



Course Articulation Matrix:

| Cos | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|----------|------|------|------|------|------|------|-----|------|------|------|------|------|------|------|------|
| EEE213.1 | 3 | 2 | 2 | 1 | 2 | 1 | | 1 | | | | | 2 | 2 | 2 |
| EEE213.2 | 3 | 3 | 2 | 2 | 2 | 2 | | 2 | 1 | 1 | | | 3 | 2 | 3 |
| EEE213.3 | 3 | 3 | 3 | 2 | 3 | 3 | | 2 | 1 | 1 | | | 3 | 3 | 3 |
| EEE213.4 | 3 | 3 | 3 | 3 | 3 | 3 | | 2 | | | | | 3 | 3 | 3 |
| EEE213.5 | 3 | 3 | 3 | 3 | 3 | 2 | | 3 | | 1 | | | 3 | 3 | 2 |
| EEE213.6 | 3 | 3 | 3 | 3 | 3 | 2 | | 3 | | 1 | | | 3 | 2 | 3 |
| | 3.00 | 2.83 | 2.67 | 2.33 | 2.67 | 2.17 | | 2.17 | 1.00 | 1.00 | | | 2.83 | 2.50 | 2.67 |

SU/SET/B. Tech./EEE



| School: SET Program: B. Tech Program: B. Tech Semester: 4 1 Course Code EEP224 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours 0-0-2 (L-T-P) Course Status Compulsory 5 Course Status Compulsory 6 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The capability to conduct testing and experimental procedures on different types of electrical machines. 6 Course CO1: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. C02: Understand the encept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 <th></th> <th></th> <th>Γ</th> <th></th> | | | Γ | | | | | | | |
|---|---------|-------------|--|---------------------------------------|--|--|--|--|--|--|
| Branch: EEE/ZE Semester: 4 1 Course Code EIP224 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours 0-0-2 (L-T-P) Course Status Compulsory 5 Course • The capability to analyze the operation of electric machines under different loading conditions 6 Course • The capability to conduct testing and experimental procedures on different types of electrical machines. 6 Course CO1: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. C04: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. CO Mapping 8 Outline syllabus CO Mapping CO1: CO2 9 Practical based on three-phase induction motor. CO1 10 | | | | | | | | | | |
| 1 Course Code Course Title EEP224 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours Objective 0-0-2 5 Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. C04: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. C05: Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. CO1 | · · · · | 0 | | | | | | | | |
| 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours 0-0-2 (L-T-P) Course Status Compulsory 5 Cospicative • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The capability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes CO1: Experimentally obtain the load characteristics of induction motor. CO3: Experimentally perform speed control of induction motor CO3: Experimentally perform speed control of field current on armature current and power factor of a synchronous motor. CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. CO6 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor . CO1. CO2 generator. 7 To perform load test on three-phase induction motor. CO1. CO2 induction motor 7 To perform load test on three-phase induction motor. CO1. CO2 induction motor. | | | | | | | | | | |
| 3 Credits 1 4 Contact Hours (L-T-P) 0-0-2 5 Course Objective Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes CO1: Experimentally obtain the load characteristics of induction motor. C02: Determination of variation of field current on armature current and power factor of a synchronous motor. CO3: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. CO1, CO2 ignerator. 7 To perform no-load and blocked rotor tests on three-phase induction motor CO1, CO2 ignerator. 8 Outline syllabus CO Apping 10 To perform load test on three-phase induction motor. CO1 10 To perform no-load and blocked rotor tests on three-phase induction motor. CO1 11 Practical related to | | | | | | | | | | |
| 4 Contact Hours (L-T-P) 0-0-2 Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally perform speed control of induction motor. C02: Determination of various performance characteristic of induction motor C03: Experimentally perform speed control of induction motor. C05: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. C05: Understand the concept of parallel operation of alternator. C06 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping 10 To perform no-load and blocked rotor tests on three-phase induction motor C01. C01. C02 11 Practical based on three-phase induction motor. To perform load test on three-phase induction motor. To perform no-load and blocked rotor tests on three-phase induction motor. C01. C01. C02 11 Practical related to single phase induction motor. To perform no-load and blocked rotor tests on single-phase induction motor. C01. C02 11 Practical related to single phase induction motor. To perform no-load and | | | | | | | | | | |
| (L-T-P) Course Status Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. 7 Course Description The course covers practical experiment on three phase induction motor, sinduction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. CO1 7 To perform no-load and blocked rotor tests on three-phase induction motor CO1,CO6 1 To perform load test on three-phase induction motor. CO1,CO2 2 To obtain the characteristic of three-phase induction generator. CO1,CO2 4 To obtain the characteristic of rotation and capacitor and to reverse its direction of rotation To perform load test on single-phase induction motor CO1, CO2 induction motor. 4 | | | - | | | | | | | |
| Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor C03: Experimentally perform speed control of field current on armature current and power factor of a synchronous motor. C05: Understand the concept of parallel operation of alternator. C06 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. To perform load test on three-phase induction motor. C01 7 To perform load test on three-phase induction motor. C01, C02 induction motor C01, C02 8 Outline syllabus CO1, C02 C01, C02 9 To perform load test on three-phase induction motor. C01, C02 9 To perform no-load and blocked rotor tests on three-phase induction motor. C01, C02 9 Practical related to single phase | 4 | | 0-0-2 | | | | | | | |
| 5 Course Objective The capability to analyze the operation of electric machines under different loading conditions The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. CO2: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. CO3: Experimentally perform speed control of induction motor. CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. CO6 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. To perform load test on three-phase induction motor. To obtain the characteristic of three-phase induction generator. CO1, CO2 generator. 1 Practical related to single phase induction motor. To perform load test on single-phase induction motor. To perform load test on single- | | · · · · · | Commulación | | | | | | | |
| Objective different loading conditions number interview of the second of the seco | 5 | | | | | | | | | |
| 6 Course Outcomes CO1: Experimentally obtain the load characteristics of induction motor. CO2: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. CO6: Understand the concept of parallel operation of alternator. CO6: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor CO1, CO6 induction motor 7 To perform no-load and blocked rotor tests on three-phase induction motor CO1, CO2 8 Outline syllabus CO1, CO2 9 To perform load test on three-phase induction motor. CO1 10 To perform load test on three-phase induction motor. CO1, CO2 11 Practical related to single phase induction motor CO1, CO2 12 Practical related to single phase induction motor. CO1, CO2 13 Practical related to single phase induction motor. CO1, CO2 14 To perform load test on single-phase induction motor. CO1 | 3 | | | | | | | | | |
| Outcomes CO2: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping 1 Practical based on three phase induction motor. CO1 7 To perform no-load and blocked rotor tests on three-phase induction motor. CO1 1 To perform load test on three-phase induction motor. CO1 1 To perform load test on three-phase induction motor. CO1, CO2 generator. 1 To start single-phase induction motor CO1, CO2 inductand the concept is direction of rotation 1 To perform no-load and blocked rotor tests on single-phase induction motor. CO1 1 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 induction motor. 2 To start single-phase induction motor. CO1, CO2 induction motor. CO1, CO2 induction motor. 2< | | | | procedures on | | | | | | |
| Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor CO1 1 Operform no-load and blocked rotor tests on three-phase induction motor. CO1 1 To perform load test on three-phase induction motor. CO1 1 Operform load test on three-phase induction motor. CO1 1 Operform load test on three-phase induction motor. CO1 1 Practical related to single phase induction motor CO1, CO2 1 Operform no-load and blocked rotor tests on single-phase induction motor CO1, CO2 1 Operform load test on single phase induction motor CO1, CO2 1 Operform no-load and blocked rotor tests on single-phase CO1, CO2 1 Operform no-load and blocked rotor tests on single-phase CO1, CO2 1 Operform load test on single-phase induction motor. CO1, CO2 1 Operform load test on single-phase induction motor. CO1, CO2 1 Operform load test on single-phase induction motor CO1, CO2 1 Operform speed control of induction motor <td>6</td> <td></td> <td>CO2: Determination of various performance characteristic of i CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on arm and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternato</td> <td>nduction motor ature current r.</td> | 6 | | CO2: Determination of various performance characteristic of i CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on arm and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternato | nduction motor ature current r. | | | | | | |
| Unit 1 Practical based on three phase induction motor CO1,CO6 To perform no-load and blocked rotor tests on three-phase induction motor CO1,CO6 To perform load test on three-phase induction motor. CO1 To obtain the characteristic of three-phase induction motor. CO1,CO2 generator. CO1,CO2 Unit 2 Practical related to single phase induction motor To start single-phase induction motor CO1,CO2 and capacitor and to reverse its direction of rotation CO1,CO2 To perform load test on single-phase induction motor. CO1,CO2 To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1,CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1,CO2 To perform load test on single-phase induction motor. CO1,CO2 Unit 3 Practical related to speed control of induction motor using v/f method. CO3,CO6 To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3 | | Description | phase induction motor and synchronous machines. | - | | | | | | |
| To perform no-load and blocked rotor tests on three-phase induction motorCO1,CO6To perform load test on three-phase induction motor.CO1To obtain the characteristic of three-phase induction generator.CO1, CO2 generator.Unit 2Practical related to single phase induction motorCO1, CO2To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotationCO1, CO2To perform no-load and blocked rotor tests on single-phase induction motor.CO1, CO2To perform no-load and blocked rotor tests on single-phase induction motor.CO1, CO2To perform load test on single-phase induction motor.CO1, CO2To perform load test on single-phase induction motor.CO1, CO2To perform speed control of induction motorCO3,CO6Unit 3Practical related to speed control of induction motor using v/f method.CO3,CO6To perform speed control of three-phase slip-ring induction motor by varying rotor resistanceCO3 | 8 | · · · · · · | | CO Mapping | | | | | | |
| induction motor CO1 To perform load test on three-phase induction motor. CO1 To obtain the characteristic of three-phase induction CO1, CO2 generator. CO1 Unit 2 Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 To perform speed control of induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 using v/f method. To perform speed control of three-phase slip-ring induction motor CO3 To perform speed control of three-phase slip-ring induction | | Unit 1 | · · · · · · · · · · · · · · · · · · · | | | | | | | |
| To perform load test on three-phase induction motor. CO1 To obtain the characteristic of three-phase induction generator. CO1, CO2 Unit 2 Practical related to single phase induction motor CO1, CO2 To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 To perform speed control of induction motor. CO1, CO3, CO6 Unit 3 Practical related to speed control of induction motor To perform speed control of three-phase induction motor CO3, CO6 Unit 3 Practical control of three-phase slip-ring induction motor CO3 CO3 | | | | CO1,CO6 | | | | | | |
| To obtain the characteristic of three-phase induction generator. CO1, CO2 Unit 2 Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Unit 3 Practical related to speed control of three-phase slip-ring induction motor CO3,CO6 To perform speed control of three-phase slip-ring induction | | | | CO1 | | | | | | |
| generator. Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Using v/f method. To perform speed control of three-phase slip-ring induction motor CO3 CO3 | | | | | | | | | | |
| Unit 2 Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor using v/f method. CO3,CO6 To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3 | | | | 01,002 | | | | | | |
| To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Unit 3 To perform speed control of three-phase induction motor To perform speed control of three-phase slip-ring induction CO3 | | Unit 2 | | | | | | | | |
| and capacitor and to reverse its direction of rotation To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 To perform speed control of three-phase slip-ring induction motor CO3 To perform speed control of three-phase slip-ring induction CO3 | | | | CO1. CO2 | | | | | | |
| To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Unit 3 To perform speed control of three-phase slip-ring induction motor CO3,CO6 To perform speed control of three-phase slip-ring induction CO3 CO3 | | | | | | | | | | |
| Unit 3 Practical related to speed control of induction motor CO1, CO2 Unit 3 Practical related to speed control of induction motor CO3,CO6 Unit 3 To perform speed control of single-phase induction motor CO3,CO6 Unit 3 To perform speed control of three-phase slip-ring induction CO3,CO6 Unit 5 To perform speed control of three-phase slip-ring induction CO3 | | | | CO1, CO2 | | | | | | |
| Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor using v/f method. CO3,CO6 To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3 | | | induction motor. | | | | | | | |
| To perform speed control of single-phase induction motor using v/f method.CO3,CO6To perform speed control of three-phase slip-ring induction motor by varying rotor resistanceCO3 | | | To perform load test on single-phase induction motor. | CO1, CO2 | | | | | | |
| using v/f method. To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3 | | Unit 3 | | | | | | | | |
| motor by varying rotor resistance | | | | | | | | | | |
| | | | | CO3 | | | | | | |
| | | Unit 4 | Practical related to Synchronous machine | | | | | | | |



| | | | | | Beyon | | | | | |
|----|--------------------|-----------------------------|---|--|-------|--|--|--|--|--|
| | | | | n of field current on armature synchronous motor. | CO4 | | | | | |
| | | To perform op generator | en-circuit and sh | ort-circuit tests on synchronous | CO4 | | | | | |
| U | nit 5 | Practical rela generator | ated to paralle | l operation of synchronous | | | | | | |
| | | To carry-out pagenerators | To carry-out parallel operation of three-phase synchronous generators | | | | | | | |
| | Iode of xamination | Jury/Practical | | | | | | | | |
| W | Veightage | CA | MTE | ETE | | | | | | |
| D | istribution | 60% | 0% | 40% | | | | | | |
| Te | ext book/s* | | nes by I.J. Nagrat rs ISBN 1259081 | th & D.P. Kothari, Tata Mc Graw 532 2010 | | | | | | |
| 0 | ther | 3. A.E. | Fitzgerald and | C. Kingsley, "Electric | | | | | | |
| R | eferences | Machi | inery", New Yo | ork, McGraw Hill Education, | | | | | | |
| | | 2014. | ISBN:9780071 | 326469, 0071326464 | | | | | | |
| | | 2. A. I | | | | | | | | |
| | | "Perfo | | | | | | | | |
| | | Publis | hers, 2004. ISE | 3N:9780852268131, | | | | | | |
| | | | 68130 | | | | | | | |

Course Articulation Matrix:

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|------|------|-----|-----|------|------|------|------|------|------|
| CO1 | 3 | 2 | 2 | 3 | 3 | 2 | 3 | | | 2 | | | 3 | 3 | 3 |
| CO2 | 3 | 2 | 2 | 2 | 3 | 2 | 3 | | | 2 | | | 2 | 2 | 3 |
| CO3 | 3 | 3 | 2 | 2 | 2 | 2 | 2 | | | 2 | | | 3 | 3 | 2 |
| CO4 | 3 | 2 | 3 | 2 | 3 | 2 | 2 | | | 2 | | | 2 | 3 | 3 |
| CO5 | 3 | 2 | 2 | 2 | 3 | 2 | 2 | | | 2 | | | 2 | 2 | 3 |
| CO6 | 3 | 3 | 2 | 2 | 3 | 2 | 2 | | | 2 | | | 3 | 2 | 2 |
| | 3.00 | 2.33 | 2.17 | 2.17 | 2.83 | 2.00 | 2.33 | | | 2.00 | | | 2.50 | 2.50 | 2.67 |



| Sak | ool: SET | | Beyon | | | | | | | |
|-----|--------------------------|---|-----------------|--|--|--|--|--|--|--|
| | | | | | | | | | | |
| | gram: B.Tech nch: EEE | Semester: IV | | | | | | | | |
| | Course Code | EEE225 | | | | | | | | |
| 1 | | | | | | | | | | |
| 2 | Course Title | ELECTRICAL AND ELECTRONICS MEASUREMENTS | | | | | | | | |
| 3 | Credits | 3 | | | | | | | | |
| 4 | Contact | 3-0-0 | | | | | | | | |
| | Hours | | | | | | | | | |
| | (L-T-P) | Demontració | | | | | | | | |
| 5 | Course Status | | | | | | | | | |
| 5 | Course | • To discuss about basic instrument and measurement system | n | | | | | | | |
| | Objective | • To identify basic structure of electrical meters | | | | | | | | |
| | | • To study techniques of RLC measurement | | | | | | | | |
| | | • To explain different principle of special instruments | | | | | | | | |
| | | • To get knowledge and discuss on basic industry sensors ar | nd transducers | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| 6 | Course | After completion of this course students will be able to: | | | | | | | | |
| | Outcomes | CO1: Getting knowledge of basic instrument and measureme | ent systems | | | | | | | |
| | | CO2: Applying knowledge and concept on construction of d | • | | | | | | | |
| | | electrical meters | | | | | | | | |
| | | CO3: Analyzing concepts of RLC measurements | | | | | | | | |
| | | CO4: Understanding knowledge of construction of CRO wor | rking and | | | | | | | |
| | | other special instruments | | | | | | | | |
| | | CO5: identifying principles and applications of different industry sensors | | | | | | | | |
| | | CO6: Studying applications of instruments in industry Instrumentation field is very important in industry field. Internal details of | | | | | | | | |
| 7 | Course | | | | | | | | | |
| | Description | different types of analog and digital instruments will be discussed | | | | | | | | |
| | | find the suitable instrument for a particular application can be do | | | | | | | | |
| | | student after going through this subject. Some of special instrume | | | | | | | | |
| | | and workbench instrument details will be discussed. Basics of ser | isors and their | | | | | | | |
| 8 | Outline syllabu | applications are explained | CO Mapping | | | | | | | |
| 0 | Unit 1 | Philosophy Of Measurement | CO Mapping | | | | | | | |
| | A | Methods of Measurement, Measurement System, Classification | C01,C06 | | | | | | | |
| | A | of instrument system | 01,000 | | | | | | | |
| | В | Characteristics of instruments & measurement system | CO1 | | | | | | | |
| | C | Errors in measurement & its analysis, Standards. | C01 | | | | | | | |
| | Unit 2 | Analog Measurement of Electrical Quantities | 001 | | | | | | | |
| | A A | Electrodynamic ,Thermocouple, Electrostatic & Rectifier type | | | | | | | | |
| | | Ammeters & Voltmeters | | | | | | | | |
| | В | Different types of wattmeters, measurement of power in single CO2,CO6 | | | | | | | | |
| | | phase and three phase | | | | | | | | |
| | С | Different types of energy meters, measurement of energy in | CO2 | | | | | | | |
| | | single phase and three phase | _ | | | | | | | |



| TL 14 0 | | | | 🥆 🥟 Ве | | | | | |
|--------------|---|---|-----------------------------------|----------|--|--|--|--|--|
| Unit 3 | | | and Instrument transformers | | | | | | |
| А | Measurement I megger | resistance (low, | , medium & high) using bridge and | CO3,CO6 | | | | | |
| В | Measurement of | of inductance 8 | capacitance using AC bridges | CO3 | | | | | |
| С | Instrument trar | nsformers: CT 8 | k PT | CO3 | | | | | |
| Unit 4 | CRO, DSO & Sp | CRO, DSO & Special Instruments | | | | | | | |
| А | CRO, DSO block | CRO, DSO block diagram, working principle, basic | | | | | | | |
| | measurements | , testing of com | ponents using CRO; | | | | | | |
| В | Electronic mult | imeter, digital ı | multimeter; Digital tachometer; | CO4 | | | | | |
| | Digital frequent | Digital frequency meter | | | | | | | |
| С | Harmonic analy | Harmonic analyzer; wave analyzer; distortion analyzer Sensors and Transducers | | | | | | | |
| Unit 5 | Sensors and Tra | | | | | | | | |
| А | Sensors and tra | insducers classi | fication; Temperature sensors | CO5, CO6 | | | | | |
| | types and work | ing principle; | | | | | | | |
| В | Pressure senso | rs types and w | orking principle; Flow sensors | CO5 | | | | | |
| | types and work | ing principle; | | | | | | | |
| С | Displacement s | ensors types ar | nd working principle; Calibration | CO5 | | | | | |
| | of sensors | | | | | | | | |
| Mode of | Theory | | | | | | | | |
| examination | - | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | Ŭ | rument", A.W. 14311, 818561 nd Transdu | acers by <u>D. Patranabi</u> | | | | | | |
| References | W.D.Cooper," I Fechnique "Pre ISBN:9798129 A.K. Sawhney,"El nstrument", Dha | | | | | | | | |



Course Articulation Matrix

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| CO1 | 3 | 3 | 2 | 2 | 2 | 2 | 1 | 1 | | - | - | 2 | 3 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 3 | - | 2 | 2 | | | 2 | 3 | 3 | 3 |
| CO3 | 3 | 3 | 2 | 3 | 3 | 3 | - | 2 | 2 | - | 1 | 2 | 3 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 2 | 3 | 1 | - | 2 | 2 | 1 | - | 3 | 3 | 3 | 3 |
| CO5 | 3 | 3 | 3 | 2 | 3 | - | 1 | 1 | 1 | - | 1 | 3 | 3 | 2 | 3 |
| CO6 | 3 | 2 | 2 | 2 | 2 | | | | | | | 1 | 2 | 2 | 3 |
| | 3.00 | 2.83 | 2.50 | 2.33 | 2.67 | 2.25 | 1.00 | 1.60 | 1.75 | 1.00 | 1.00 | 2.17 | 2.83 | 2.67 | 3.00 |

SU/SET/B. Tech./EEE



| Sch | lool: | | | | | | | | |
|-----|-----------------------|---|------------------------|--|--|--|--|--|--|
| | gram: | | | | | | | | |
| Bra | unch: | Semester:4 | | | | | | | |
| 1 | Course Code | EEP225 | | | | | | | |
| 2 | Course Title | Electrical & Electronics Measurements Lab | | | | | | | |
| 3 | Credits | 1 | | | | | | | |
| 4 | Contact Hours | 0-0-2 | | | | | | | |
| | (L-T-P) | | | | | | | | |
| | Course Status | Compulsory/Elective | | | | | | | |
| 5 | Course Objective | To know calibration and diagnosing problem instruments To measure and read unknown electrical compone meters and bridges To measure electrical parameters like voltage, free CROs | nts value using | | | | | | |
| | | To know characteristics of sensors and transducers | | | | | | | |
| | | To know constructions of analog and digital insturn | nents | | | | | | |
| 6 | Course | CO1: Getting knowledge of basic instrument and measurer | | | | | | | |
| 0 | Outcomes | CO2: Applying knowledge and concept on construction of electrical meters CO3: Analyzing concepts of RLC measurements CO4: Able to select proper sensors to sense a parameter CO5: Understanding knowledge of construction of CRO w other special instruments | different | | | | | | |
| | | CO6: Finding applications of instruments | | | | | | | |
| 7 | Course Description | This course gives idea about how to use different types of r measurements. Some experiments give practice of RLC me using AC & DC bridges. One section gives practice of mea using CRO. The last two sections about sensors and case st | easurement surement | | | | | | |
| 8 | Outline syllabus | | CO Mapping | | | | | | |
| | Unit 1 | Calibration | | | | | | | |
| | А | Calibration of voltmeter and ammeter | CO1,CO6 | | | | | | |
| | В | Measurement of RMS, average and form factor using rectifier and meters | CO1 | | | | | | |
| | С | Calibration of wattmeter and energy meter | CO1 | | | | | | |
| | Unit 2 | RLC Bridges | | | | | | | |
| | A | DC Bridge for R measurement | CO2,CO6 | | | | | | |
| | B | AC Bridge for L measurement | CO2 | | | | | | |
| | C | AC Bridge for C measurement | CO2 | | | | | | |
| | Unit 3 | CRO and DSO | | | | | | | |
| | A | Identifying of controls and functions switches on CRO & DSO | CO3,CO6 | | | | | | |
| | В | Measurements using CRO | CO3 | | | | | | |
| | Ē | Measurements using DSO | CO3 | | | | | | |
| | SETTER Tech./EEE | Sensors Characteristics | + | | | | | | |

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| | | | | | | | | | | | | | | yond Bou | ndaries |
|-----|-----------------------------|------------------------|------|----------|---------|----------|---------|-----------|---------|------|------|------|------|-----------------------------------|------------|
| | А | | C | haracte | ristics | of temp | peratur | e senso | or | | | CO4 | ,CO6 | | |
| | В | | C | haracte | ristics | of force | e senso | or | | | | CO4 | - | | |
| | С | | C | haracte | ristics | of disp | laceme | ent or fl | low ser | isor | | CO4 | - | <u>C</u> | <u>OUR</u> |
| | Unit 5 | 5 | C | ase stu | dy of] | Instrur | nents | | | | | | | SE | E |
| | А | A Digital Energy Meter | | | | | | | | | | CO5 | ,CO6 | | RTI |
| | B Digital Temperature Meter | | | | | | | | | CO5 | i | | ULA | | |
| | | | D | igital N | Iultim | eter | | | | | | | | | ION |
| | Mode | of | P | ractical | & Viv | 'a | | | | | | | | | |
| | exami | nation | | | | | | | | | | | | $-\frac{\mathbf{M}}{\mathbf{IC}}$ | <u>ATR</u> |
| | Weigh | ntage | C | A | l | MTE | | ETE | | | | | | | <u></u> |
| | Distri | bution | 6 |)% | (|)% | | 40% | | | | | | | |
| | Text b | ook/s* | R | efer lab | manu | als | | | | | | | | | |
| | Other | | | | | | | | | | | | | | |
| | Refere | ences | | | | | | | | | | | | | |
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 3 | 3 | 2 | 2 | 2 | 2 | 1 | 1 | | - | - | 2 | 3 | 2 | 2 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 3 | - | 2 | 2 | | | 2 | 3 | 3 | 2 |
| CO3 | 3 | 3 | 2 | 3 | 3 | 3 | - | 2 | 2 | - | 1 | 2 | 3 | 3 | 1 |
| CO4 | 3 | 3 | 3 | 2 | 3 | 1 | - | 2 | 2 | 1 | - | 3 | 3 | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 3 | - | 1 | 1 | 1 | - | 1 | 3 | 3 | 2 | 2 |
| CO6 | 3 | 2 | 2 | 2 | 2 | | | | | | | 1 | 2 | 2 | 1 |
| | 3.00 | 2.83 | 2.50 | 2.33 | 2.67 | 2.25 | 1.00 | 1.60 | 1.75 | 1.00 | 1.00 | 2.17 | 2.83 | 2.50 | 1.67 |



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| C -l | l. CET | | | | | | | | | | |
|------|--|--|----------------|--|--|--|--|--|--|--|--|
| | ool: SET | | | | | | | | | | |
| | gram: B.Tech nch: EEE | Semester:V | | | | | | | | | |
| | | | | | | | | | | | |
| 1 | Course Code | EEE330 | | | | | | | | | |
| 2 | Course Title | Control Systems | | | | | | | | | |
| 3 | Credits | 3 | | | | | | | | | |
| 4 | Contact Hours | 3-0-0 | | | | | | | | | |
| | (L-T-P) | | | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | | |
| 5 | Course | Control Systems is the study of the analysis and regulation | of the output | | | | | | | | |
| 5 | Objective | behaviors of dynamical systems subject to input signals. Th | | | | | | | | | |
| | Objective | tools discussed in this course can be used in a wide | | | | | | | | | |
| | | | | | | | | | | | |
| | | engineering disciplines. The emphasis of this course will and feedback controller design methods for linear | | | | | | | | | |
| | | - | time-invariant | | | | | | | | |
| 6 | Course | systems. CO1:Apply transfer function models, signal flow graphs and | t block | | | | | | | | |
| 0 | Outcomes | diagram algebra to obtain the transfer function of a give | | | | | | | | | |
| | Outcomes | CO2: Obtain system response in time domain | ven system | | | | | | | | |
| | | CO3: Design a closed-loop control system to satisfy dynam | ic performance | | | | | | | | |
| | | specifications using frequency response | | | | | | | | | |
| | | CO4:Analyze closed-loop control systems for stability and steady-state | | | | | | | | | |
| | | performance | | | | | | | | | |
| | | CO5: Design simple feedback controllers and compensators to meet | | | | | | | | | |
| | | desired performance specifications CO6: Apply different types of analysis and explain the nature of stability | | | | | | | | | |
| | | | | | | | | | | | |
| | | of any given linear system | | | | | | | | | |
| 7 | Course | This course shall introduce the fundamentals of modeling | and control of | | | | | | | | |
| | Description | linear time invariant systems. The course will be useful for students from | | | | | | | | | |
| | | major streams of engineering to build foundations of | | | | | | | | | |
| | | analysis of systems as well as the feedback control of such s | ystems. | | | | | | | | |
| | | | | | | | | | | | |
| 8 | Outline syllabu | | CO Mapping | | | | | | | | |
| | Unit 1 | Introduction to Control Problem | | | | | | | | | |
| | А | Feedback Control: open-loop and closed-loop systems, | CO1,CO6 | | | | | | | | |
| | benefits of feedback,block diagram algebra | | | | | | | | | | |
| | В | Mathematical models of physical systems, signal flow | CO1 | | | | | | | | |
| | | graph | | | | | | | | | |
| | C Unit 2 | Transfer function models of linear time-invariant systems | CO1 | | | | | | | | |
| | Unit 2 A | Time Response Analysis Standard tast signals, time response of first order systems CO2 | | | | | | | | | |
| | A | Standard test signals, time response of first order systems CO2 for standard test inputs | | | | | | | | | |
| | В | Time response of second order systems for standard test CO2 | | | | | | | | | |
| | U U | inputs CO2 | | | | | | | | | |
| | С | Design specifications for second-order systems based on | CO2 | | | | | | | | |
| L | | Design specifications for second order systems based on | 0.02 | | | | | | | | |

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| | the time-response | | | | | |
|---------------------|--|------------------------------------|---|---------|--|--|
| Unit 3 | Frequency Resp | oonse Ana | alysis | | | |
| Α | Introduction and | frequency | y domain specifications | CO3 | | |
| В | Correlation betw | een frequ | ency domain and time domain. | CO3 | | |
| С | Polar plot and B | ode plot | | CO3,CO6 | | |
| Unit 4 | Stability of Con | | | | | |
| А | Concept of stabil | lity | | CO4 | | |
| В | Characteristic ec stability, Routh H | CO4 | | | | |
| С | Root-locus techr | CO4 | | | | |
| Unit 5 | Modern Contro | | | | | |
| А | Lag, lead, lag-lea criteria | CO5,CO6 | | | | |
| В | Concepts of state variables and state space model. | | | | | |
| С | Solution of state observability. | CO5 | | | | |
| Mode of examination | Theory | | | | | |
| Weightage | CA N | ITE | ETE | | | |
| Distribution | 30% 2 | 0% | 50% | | | |
| Text book/s* | 1991. ISBN:9 2. M. Gopal, "C | 78013589 ontrol Sys | ntrol Engineering", Prentice Hall, 91285, 0135891280 stems: Principles and Design", n, 1997. ISBN:9780070482890, | | | |
| Other References | Engineering" ISBN:978812 2. B. C. Kuo, "A | , New Ag 22417753, Automatic | opal, "Control Systems e International, 2009 , 8122417752 Control System", Prentice Hall, 34763, 0471134767 | | | |



COURSE ARTICULATION MATRIX:

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|-----|-----|-----|------|------|------|------|------|------|------|
| CO1 | 3 | 3 | 3 | 2 | 2 | - | - | - | 1 | 1 | - | - | 2 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 2 | 3 | - | - | - | 1 | 1 | - | - | 3 | 3 | 3 |
| CO3 | 3 | 3 | 3 | 2 | 3 | - | - | - | 1 | 1 | - | - | 2 | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 3 | - | - | - | 1 | 1 | - | - | 2 | 3 | 3 |
| CO5 | 3 | 3 | 3 | 2 | 3 | | - | - | 1 | 1 | - | - | 2 | 3 | 3 |
| CO6 | 3 | 3 | 3 | 2 | 3 | - | - | - | 1 | 1 | - | - | 3 | 3 | 3 |
| | 3.00 | 3.00 | 3.00 | 2.00 | 2.83 | | | | 1.00 | 1.00 | | | 2.33 | 3.00 | 2.83 |

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| | | | d Boundaries |
| _ | chool: SET rogram: B. | | |
| | ech. | | |
| | ranch: EEE | Semester: 05 | |
| 1 | Course | EEE331 | |
| | Code | | |
| 2 | Course | Power System-I | |
| - | Title | | |
| 3 | Credits | 3 | |
| 4 | Contact Hours | 3-0-0 | |
| | (L-T-P) | | |
| | Course | Compulsory | |
| | Status | | |
| | | To provide students with the ability of: | |
| | | understanding of the basic components of Power System and then analyze | |
| | | the system using the technique of per unit system. Also introducing the | |
| 5 | Course | students to cables, insulators and the corono phenomena which occurs in | |
| 0 | Objective | transmission system | |
| | | representing the transmission system with the help of their equivalent | |
| | | circuits | |
| | | calculating various design parameters of transmission lines | |
| | | On successful completion of this course students will be able to | |
| | | CO1: assimilate necessary fundamental knowledge of different power system elements | |
| | | | |
| | | CO2: Apply concepts from basic electromagnetics to determine the inductance, | |
| | | capacitance, and resistance of three-phase transmission lines, including lines | |
| 6 | Course | with conductor bundling . | |
| 0 | Outcomes | CO3: Derive the model for short, medium and long transmission lines | |
| | | CO4: Analyse the mechanical and electrical design aspects of transmission system | |
| | | CO5: Analyse different types of distribution systems and its design. | |
| | | CO6: Examine the various design features of overhead transmission lines | |
| | | | |
| | | | |
| 7 | Course | This course will cover major topics of power engineering and intended to deliver basic knowledge of fundamentals of power systems including | |
| / | Description | transmission, and distribution of electrical power. Course will guide students to | |
| | | design transmission line having perfect sag and insulator design and minimum | |
| L | | o month and the manual states of the month of the manual states of the manual states of the manual states of the manual states of the states o | l |

| | corona loss. | |
|---------|---|---------------|
| Outline | syllabus | CO Mapping |
| Unit 1 | Fundamentals of Power System | |
| А | Single phase transmission, three phase transmission, basic | CO1,CO6 |
| | components of a power system. | |
| В | Need of EHV Transmission | CO2 |
| С | Types of Distribution System | CO1, CO2 |
| Unit 2 | Transmission Line Constants and Performance | , |
| A | Inductance of solid, stranded and bundled conductors, symmetrical and unsymmetrical spacing and transposition, | CO1, CO3, CO6 |
| | application of self and mutual GMD | |
| В | Capacitance of solid, stranded and bundled conductors, Symmetrical and unsymmetrical spacing and transposition, | CO1, CO3 |
| | application of self and mutual GMD | |
| С | | CO4 |
| | Characteristics and performance of lines - short line, medium line and long line; equivalent circuits, ABCD constants, Ferranti effect. | |
| Unit 3 | Corona, Interference and Insulated Cables | |
| A | Critical disruptive voltage and visible disruptive voltage, corona loss, line design based on corona, advantages and disadvantages of corona. | CO1, CO2, CO5 |
| В | Skin and proximity Effects, Interference with neighbouring communication circuits and Radio Interference. | CO1, CO2, CO5 |
| С | Insulation, Shielding and Armouring of cables, types of cables, EHV cables, insulation resistance, capacitance and loss angle, capacitance grading, heating of cables, current rating | CO1, CO2, CO5 |
| Unit 4 | Mechanical Design of Transmission Lines | |
| A | Catenary curve, sag-tension calculations, supports at different levels | CO1, CO2, CO5 |
| В | Stringing chart, sag template, equivalent span, vibration and vibration dampers. | CO1, CO2, CO5 |
| С | Types, voltage distribution in insulator string and grading, methods of equalizing potentials. | CO1, CO2, CO5 |
| Unit 5 | HVDC Transmission | |
| А | Components of HVDC transmission system, Comparison of AC and DC transmission. | CO5,CO6 |
| В | Application of DC Transmission | CO5 |
| C | Types of HVDC links | CO5 |
| Mode | Theory | |
| of | | |

)A



| | | | | Beyon | | | | | | |
|-------------------------|-----|---|--|-------|--|--|--|--|--|--|
| examin ation | | | | | | | | | | |
| Weight | СА | MTE | ETE | | | | | | | |
| age Distrib ution | 30% | 20% | 50% | | | | | | | |
| Text book* | • | J.Nagrath and D.P.Kothari, "Power System Engineering", Tata McGraw- Hill Publishers. ISBN:9789353165123, 1353165121 | | | | | | | | |
| Other Referen ces | | a, "Electrical Powe ISBN:97881224177 | r Systems", New Age International 739, 8122417736 | | | | | | | |

COURSE ARTICULATION MATRIX:

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|-----|-----|-----|------|------|------|------|------|------|------|
| CO1 | 3 | 3 | 1 | 2 | 1 | - | - | - | 1 | 1 | - | - | 3 | 3 | 2 |
| CO2 | 2 | 2 | 1 | 2 | 1 | - | - | - | 1 | 1 | - | - | 3 | 2 | 2 |
| CO3 | 3 | 3 | 1 | 2 | 2 | - | - | - | 1 | 1 | - | - | 3 | 2 | 2 |
| CO4 | 2 | 2 | 1 | 1 | 2 | - | - | - | 1 | 1 | - | - | 3 | 3 | 2 |
| CO5 | 2 | 2 | 1 | 1 | 2 | - | - | - | 1 | 1 | - | - | 3 | 3 | 1 |
| CO6 | 3 | 2 | 1 | 2 | 2 | - | - | - | 1 | 1 | - | - | 3 | 2 | 2 |
| | 2.50 | 2.33 | 1.00 | 1.67 | 1.67 | | | | 1.00 | 1.00 | | | 3.00 | 2.50 | 1.83 |



| | ool: SET | | | | | | | | | | | |
|---|--------------------------|--|--|--|--|--|--|--|--|--|--|--|
| | gram: B. Tech. | | | | | | | | | | | |
| | nch: EEE | Semester: 05 | | | | | | | | | | |
| 1 | Course Code | EEP331 | | | | | | | | | | |
| 2 | Course Title | Power System-1 Lab | | | | | | | | | | |
| 3 | Credits | 1 0-0-2 | | | | | | | | | | |
| 4 | Contact Hours (L-T-P) | | | | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | | | |
| 5 | Course Objective | To provide students with the ability of: understanding of the basic components of Power System analyze the system using the technique of per unit syste introducing the students to cables, insulators and the comphenomena which occurs in transmission system representing the transmission system with the help of the circuits calculating various design parameters of transmission li | m. Also rono eir equivalent | | | | | | | | | |
| 6 | Course Outcomes | On successful completion of this course students will bCO1:design three-phase power system model in PSCAD softwCO2:design of transmission lines of specified parametersCO3:analyse Ferranti Effect in transmission lineCO4:derive the model for short, medium and long transmissiCO5:examine the various design features of overhead transmissionCO6:do fault analysis in transmission and distribution sys | e able to vare on lines nission lines | | | | | | | | | |
| 7 | Course Description | This course will cover major topics of power engineering a deliver basic knowledge of fundamentals of power syst transmission, and distribution of electrical power. Cour students to design transmission line having perfect sag design and minimum corona loss. | ems including rse will guide | | | | | | | | | |
| 8 | Outline syllabus | | | | | | | | | | | |
| | Unit 1 | Practical based on fundamentals of Power System | | | | | | | | | | |
| | A | To design single-phase power system model consisting of generator, transformer, transmission line and motors in PSCAD | CO1,CO6 | | | | | | | | | |
| | В | To design three-phase power system model consisting of generator, transformer, transmission line and motors in PSCAD | CO2 | | | | | | | | | |



| C | To design diff | ferent types | of distribution systems and to | CO1, CO2 |
|---------------------|------------------------|----------------|------------------------------------|----------|
| | measure volta PSCAD | ages and curr | rents at different feeder point in | n |
| Unit 2 | | ed on trans | mission line constants and | |
| | performance | | mission mic constants and | |
| A | - | | f transmission line using line | CO1, |
| | data in MATI | | | CO3,CO6 |
| В | | | of transmission line using line | CO1, CO3 |
| | data in MATI | | C | , |
| С | To determine | ABCD para | meters in transmission line kit | CO4 |
| Unit 3 | | | ona, Interference and | |
| | Insulated Ca | | <i>,</i> | |
| А | To plot a grap | oh between c | ritical disruptive voltage, | CO1, CO2 |
| | | | r radius vs corona loass in | CO5 |
| | MATLAB | | | |
| В | To examine F | Ferranti effec | t in transmission line kit. | CO1, CO2 |
| | | | | CO5 |
| С | | | | CO1, CO2 |
| | To determine | e the location | n of fault in a cable using cable | e CO5 |
| | fault locator. | • | | |
| Unit 4 | | | hanical Design of | |
| | Transmission | | | |
| A | | sag taking re | quired inputs from user in | CO1, CO2 |
| | MATLAB | | | CO5 |
| В | To plot string | ing chart and | d sag template in MATLAB | CO1, CO2 |
| | | 8 | B I III | CO5 |
| С | To determine | the string ef | ficiency of insulating disc | CO1, CO2 |
| - | | 8 | | CO5 |
| Unit 5 | Practical rela | ated to HVI | OC Transmission | |
| Α | To design a re | | | CO5,CO6 |
| В | To design an | | | CO5 |
| С | 0 | | DC system in PSCAD | CO5 |
| Mode of | Practical | 1 | • | |
| examination | | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 60% | 0% | 40% | |
| Text book/s* | I.J.Nagrath ar | nd D.P.Kotha | ari, "Power System | |
| | | | aw- Hill Publishers. | |
| | ISBN:978935 | | | |
| Other References | 2. C.L.Wad | ge | | |
| itereneus | Internatio | 39, | | |
| | 8122417 | 736 | | |
| | 0122 117 | , | | |



COURSE ARTICULATION MATRIX:

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|-----|-----|------|------|-----|-----|------|------|------|------|------|------|------|------|
| CO1 | 3 | 3 | 3 | 2 | 2 | - | - | 1 | 1 | - | - | - | 3 | 3 | 3 |
| CO2 | 2 | 3 | 3 | 2 | 2 | - | - | 1 | 1 | - | - | - | 3 | 3 | 3 |
| CO3 | 3 | 2 | 2 | 2 | 2 | - | - | 1 | 1 | - | - | - | 3 | 3 | 3 |
| CO4 | 2 | 1 | 2 | 2 | 2 | - | - | 1 | 1 | - | - | - | 3 | 3 | 3 |
| CO5 | 2 | 2 | 1 | 2 | 3 | - | - | 1 | 1 | - | - | - | 3 | 3 | 3 |
| CO6 | 3 | 2 | 1 | 2 | 3 | - | - | 1 | 1 | - | - | - | 3 | 3 | 3 |
| | 2.50 | | | 2.00 | 2.33 | | | 1.00 | 1.00 | | | | 3.00 | 3.00 | 3.00 |

SU/SET/B. Tech./EEE



| ~ - | | | Beyon | | | | | | | |
|-----|-----------------------------|---|------------------|--|--|--|--|--|--|--|
| | ool: SET | | | | | | | | | |
| | gram: B.Tech | | | | | | | | | |
| | nch: EEE/EE | Semester: V | | | | | | | | |
| 1 | Course Code Course Title | EEE332 | | | | | | | | |
| 23 | Course Thie Credits | Power Electronics 3 | | | | | | | | |
| 4 | Contact | 3-0-0 | | | | | | | | |
| - | Hours | 5-0-0 | | | | | | | | |
| | (L-T-P) | | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | |
| 5 | Course | 1. Analysis of modern power semiconductor devices, their | strengths, and | | | | | | | |
| | Objective | their switching and protection techniques | | | | | | | | |
| | | 2. Ability to analyze various important topologies of power | converter | | | | | | | |
| | | circuits for specific types of applications including contro | lled and | | | | | | | |
| | | uncontrolled rectifiers, DC-DC converters and inverters | | | | | | | | |
| | | 3. Ability to understand and analyze the qualities of wavefo | rms at input | | | | | | | |
| | | and output ends of these converters | | | | | | | | |
| 6 | Course | On successful completion of this course students will be able | e to | | | | | | | |
| | Outcomes | | | | | | | | | |
| | | CO1: summerise the characteristics and principle of operation | of different | | | | | | | |
| | | types of semiconductor switches | | | | | | | | |
| | | CO2: "analyse the principles of operation of silicon controlled rectifiers. | | | | | | | | |
| | | CO3: Analyse controlled rectifier circuits | | | | | | | | |
| | | CO4: Analyse the operation of DC-DC choppers | | | | | | | | |
| | | CO5: Analyse the operation of voltage source inverters. | | | | | | | | |
| | | CO6: Classification of different type of controller | | | | | | | | |
| 7 | Course | | | | | | | | | |
| | Description | Power electronics is the application of solid-state elect | ronics for the | | | | | | | |
| | _ | control and conversion of electrical power. During the cou | rse it is taught | | | | | | | |
| | | that how in modern system the conversion is pe | | | | | | | | |
| | | semiconductor switching device such as SCR, MOSFET, IG | BT, and GTO. | | | | | | | |
| 8 | Outline syllabu | IS | CO Mapping | | | | | | | |
| | Unit 1 | Power Semiconductor Devices | | | | | | | | |
| | A | Thyristors : Silicon Controlled Rectifiers (SCR's) , BJT, power | CO1 | | | | | | | |
| | | MOSFET, power IGBT, TRIAC and their characteristics | | | | | | | | |
| | B | Gate characteristics of SCR, turn on and turn off methods. | CO1 | | | | | | | |
| | C | Series and parallel operation of SCRs, line commutation and | CO1 | | | | | | | |
| | Unit 2 | forced commutation circuits. Phase Controlled Converters | | | | | | | | |
| | Unit 2 A | Phase Controlled Converters Principle of phase control, circuit, waveform and analysis of | CO2 CO6 | | | | | | | |
| L | A SET/D Toch /EEE | | CO2, CO6 | | | | | | | |



| | | | | | | | | | |
|--------------|------------------|--|---|---------|--|--|--|--|--|
| | single phase ha | If wave and ful | l wave line commutated | | | | | | |
| | converters with | n R, RL, RLE load | 1. | | | | | | |
| В | | | s of three pulse and six pulse | CO2 | | | | | |
| | converters with | | | | | | | | |
| С | Operation of d | ual converter. | | CO2 | | | | | |
| Unit 3 | Choppers | | | | | | | | |
| А | Principle of ope | Principle of operation, time ratio control and current limit | | | | | | | |
| | control strateg | ies | | | | | | | |
| В | Circuit, operati | on and analysis | of Step down and step up | CO3 | | | | | |
| | choppers. | | | | | | | | |
| C | Types of chopp | Types of choppers: A, B, C, D and E choppers. | | | | | | | |
| Unit 4 | Inverters | | | | | | | | |
| А | Principle of ope | eration of single | e phase inverter, basic series | CO4 | | | | | |
| | inverter bridge | | | | | | | | |
| В | Three phase In | verter: 120 ⁰ and | d 180 ⁰ mode, circuit, operation | CO4 | | | | | |
| | and analysis. | | | | | | | | |
| С | Voltage contro | l techniques for | inverters, VSI & CSI and their | CO4 | | | | | |
| | comparison. | | | | | | | | |
| Unit 5 | Other Applic | ations of Pow | er Electronics | | | | | | |
| А | AC voltage con | trollers with R a | and RL loads. | CO5,CO6 | | | | | |
| В | Cycloconverter | S | | CO5 | | | | | |
| С | UPS,SMPS, Ind | uction heating, | HVDC | CO5 | | | | | |
| Mode of | Theory | 0. | | | | | | | |
| examination | 5 | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | | | ics", Pearson Education; Fourth | | | | | | |
| | | | 7658, 0080467652 | | | | | | |
| Other | | | | | | | | | |
| References | 1. Bose B | | | | | | | | |
| | - | | 780310841, 0780310845 | | | | | | |
| | 2. Sen P.C | C., "Power Elect | ronics", Mc.Graw Hill,2016. | | | | | | |
| | 3. Singh N | Л.D., Kanchand | ani K.B., "Power Electronics", | | | | | | |
| | McGra | w-Hill, 2017. ISI | BN:9788126511013, 812651101X | | | | | | |
| | | , | | | | | | | |



COURSE ARTICULATION MATRIX

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|-----|-----|-----|------|------|------|------|------|------|------|
| CO1 | 3 | 3 | 3 | 2 | 3 | - | - | - | 1 | 1 | - | - | 3 | 3 | 3 |
| CO2 | 2 | 2 | 3 | 2 | 3 | - | - | - | 1 | 1 | - | - | 3 | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 2 | - | - | - | 1 | 1 | - | - | 3 | 3 | 3 |
| CO4 | 2 | 2 | 3 | 3 | 2 | - | - | - | 1 | 1 | - | - | 3 | 3 | 2 |
| CO5 | 2 | 2 | 3 | 3 | 2 | - | - | - | 1 | 1 | - | - | 3 | 3 | 1 |
| CO6 | 3 | 2 | 3 | 2 | 2 | - | - | - | 1 | 1 | - | - | 3 | 2 | 2 |
| | 2.50 | 2.33 | 3.00 | 2.33 | 2.33 | | | | 1.00 | 1.00 | | | 3.00 | 2.83 | 2.17 |

SU/SET/B. Tech./EEE



| Sch | ool: SET | | | | | | | | | | | |
|-----------------|--------------------------|--|------------|--|--|--|--|--|--|--|--|--|
| Program: B.Tech | | | | | | | | | | | | |
| Bra | nch:EEE/EE | Semester: V | | | | | | | | | | |
| 1 | Course Code | EEP332 | | | | | | | | | | |
| 2 | Course Title | Power electronics lab | | | | | | | | | | |
| 3 | Credits | 1 | | | | | | | | | | |
| 4 | Contact Hours (L-T-P) | 0-0-2 | | | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | | | |
| 5 | Course Objective | Ability to analyze various important topologies of power converter circlypes of applications including controlled and uncontrolled rectifiers, I and inverters | • | | | | | | | | | |
| 6 | Course Outcomes | On successful completion of this course students will be able to | | | | | | | | | | |
| | | CO1: Analysis of different power electronic devices. | | | | | | | | | | |
| | | CO2: study of characteristics of SCR, BJT, MOSFET and IGBT | | | | | | | | | | |
| | | CO3: eperimental verification of the design and control of rectifiers, inverters. | | | | | | | | | | |
| | | CO4: Experimental study of different communication methods | | | | | | | | | | |
| | | CO5: Experimental verification the DC-DC chopper circuit | | | | | | | | | | |
| | | CO6: Design and Experiment of AC voltage controller and Cyclo Converter | | | | | | | | | | |
| 7 | Course | | | | | | | | | | | |
| | Description | Electronic power conversion is vital in modern electrical energy systems and device The primary goal of the course is to give students an in-depth laboratory experience the design, operation, characterization, and application of electronic circuits for conversion and control of electrical energy. | | | | | | | | | | |
| 8 | Outline syllabus | } | CO Mapping | | | | | | | | | |
| | Unit 1 | Power Semiconductor Devices | | | | | | | | | | |
| | А | To obtain VI Characteristics of SCR. | CO1 | | | | | | | | | |
| | В | To control the thyristor using different gate firing circuits. | CO1 | | | | | | | | | |
| | Unit 2 | Phase Controlled Converters | | | | | | | | | | |
| | A | To observe the output voltage waveforms and to find the average and rms output voltages of a single phase half controlled converter with R load. | | | | | | | | | | |
| | В | To observe the output voltage waveforms and to find the average and rms output voltages of a three-phase half controlled bridge converter with R-load. | CO2 | | | | | | | | | |

| | | | | | * SHARD | | | |
|------------------------|--|--|---------------------|---------|---------|--|--|--|
| С | To observe the of and rms output converter with f | CO2 | | | | | | |
| Unit 3 | Choppers | | | | | | | |
| А | | To observe the output voltage waveforms and to find the average voltage of a voltage commutated chopper. | | | | | | |
| В | Simulation of st | | | | | | | |
| Unit 4 | Inverters | | | | | | | |
| A | To observe the overlapped to observe the overlapped to observe the other strength to observe the | CO4 | | | | | | |
| В | Simulation of th | | CO4 | | | | | |
| Unit 5 | AC voltage cont | | | | | | | |
| А | To observe the overlapped to t | • • | • | CO5,C06 | | | | |
| В | Simulation of A | C voltage contr | ollers with R and R | loads | CO5,CO6 | | | |
| Mode of examination | Viva-voce | | | | | | | |
| Weightage | СА | MTE | ETE | | | | | |
| Distribution | 60% | 00% | 40% | | | | | |
| Text book/s* | Rashid M.D., " P | | | | | | | |
| Other References | 1. Bose B.I ISBN:97 | | | | | | | |
| | 2. Sen P.C. | | | | | | | |
| | 3. Singh M McGraw | | | | | | | |

COURSE ARTICULATION MATRIX

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|------|------|-----|-----|------|------|------|------|------|------|
| CO1 | 3 | 2 | 1 | 1 | 1 | 2 | 1 | | | 1 | | | 1 | 1 | 2 |
| CO2 | 3 | 2 | 1 | 1 | 2 | 1 | 2 | | | 1 | | | 1 | 1 | 2 |
| CO3 | 2 | 3 | 3 | 2 | 2 | 2 | 2 | | | 1 | | | 3 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 3 | 2 | 1 | | | | 1 | | | 3 | 3 | 2 |
| CO5 | 3 | 3 | 3 | 3 | 2 | 2 | 2 | | | 1 | | | 3 | 3 | 3 |
| CO6 | 3 | 3 | 3 | 2 | 2 | 2 | 2 | | | 1 | | | 3 | 3 | 3 |
| | 2.83 | 2.67 | 2.33 | 2.00 | 1.83 | 1.67 | 1.80 | | | 1.00 | | | 2.33 | 2.33 | 2.50 |



VI TERM

SU/SET/B. Tech./EEE



| Bra | anch:EEE | Semester:VI | |
|-----|-----------------------------|--|--|
| 1 | Course Code | EEE334 | |
| 2 | Course Title | Switchgear and Protection | |
| 3 | Credits | 3 | |
| 4 | Contact Hours (L-T-P) | 3-0-0 | |
| | Course Status | Compulsory | |
| 5 | Course Objective | The objective of the course is to expose students to the tech protecting the various subsystems of a power system during operation and also under fault condition. The students will a acquainted with the techniques to coordinate these protectin systems | g their normal also be |
| 6 | Course Outcomes | CO1:Understand the basic terminologies related to power system faults for balanced and conditions. CO2: compare the protection techniques used for protection power system components CO3:Identify, apply, and calculate settings for transformers and transmission line protection schemes. CO4: discuss the theory of circuit interruption and physical phe CO5: Identify the challenges and solutions to industrial por protection problems. CO6 An ability to develop protection schemes/algorithms components of power system. | d unbalanced n of different , generators nomena of arc wer system s for all |
| 7 | Course Description | Reliability of electrical energy systems to a large extent is of the reliability of its protection system. Basic building protection system are fuses, over current and distar differential protection schemes. In this course, we will principles and applications to apparatus and system protection | g blocks of the nee relays and introduce their |
| 8 | Outline syllabu | 15 | CO Mapping |
| | Unit 1 | Introduction to Power System Protection | |
| | A | Nature and causes of faults on power system elements need of protection. | CO1,CO6 |
| | В | Zones of protection, essential qualities of protection, primary and backup protection | CO1 |
| | С | CTs and VTs and their applications in protection. | CO1 |
| | Unit 2 | Operating Principles and Construction of Relays | |
| | A | Principle of various Electromagnetic relays and their constructions. | CO2 |
| | В | over-current, directional, differential and distance relays and their operating characteristics | CO2 |
| | С | Introduction to digital/numerical relays and Intelligent | CO2 |



| | Electronic Dev | vice (IED) rela | lys | | | |
|------------------------|---|--|---|---------|--|--|
| Unit 3 | Protection of | | - | | | |
| A | Faults on trar againstextern protection ag | asformers and a al faults, prote a a faults, prote | its protection: protection ection against internal faults, inrush, concept of lightning | CO3,CO6 | | |
| В | Faults on Ger Stator protect stator-overhe protection,los | nerator and its tion, protection ating, Rotor pr as of excitation | against inter-turn faults, rotection, field ground-fault protection, overvoltage | CO3 | | |
| С | protection, overspeed protection.CFaults on transmission lines and its protection: wire pilot protection, carrier current protection | | | | | |
| Unit 4 | Theory of Circu | it Interruption | | | | |
| А | Physics of arc | phenomena ar | nd arc interruption. | CO4 | | |
| В | Restriking vol recovery volta | - | ry voltage, rate of rise of | CO4 | | |
| С | Resistance swi capacitive curr | • | t chopping, interruption of | CO4 | | |
| Unit 5 | Circuit Break | xers | | | | |
| А | Types of circu | it breakers, | | CO5,CO6 | | |
| В | | and vacuum c | onstruction of air-break, air ircuit breakers, their merits and | CO5 | | |
| С | Concept of HV | | eaker. | CO5 | | |
| Mode of examination | Theory | | | | | |
| Weightage | CA | MTE | ETE | | | |
| Distribution | 30% | 20% | 50% | | | |
| Text book/s* | Badri Ran Protection publishin ISBN:978 C.L Wadl | n & Switchgea g company ltd 30071077743, hwa, 'Electrica nal (p) limited | | | | |
| Other References | Bhavesh Bhalj "Protection an ISBN:9780199 | d Switchgear" | | | | |



Course Articulation Matrix:

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|-----|-----|------|-----|-----|------|------|------|------|------|------|
| CO1 | 3 | 3 | 3 | 1 | | | 3 | | | 3 | | | 1 | 1 | 1 |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 3 | | | 1 | 2 | 1 |
| CO3 | 3 | 3 | 3 | 2 | | | | | | 3 | | | 3 | 3 | 2 |
| CO4 | 3 | 3 | 3 | | | | 3 | | | 3 | | | 2 | 2 | 1 |
| CO5 | 3 | 3 | 3 | | | | | | | 3 | | | 2 | 3 | 2 |
| CO6 | 3 | 3 | 2 | 2 | | | 3 | | | 3 | | | 1 | 1 | 2 |
| | 3.00 | 3.00 | 2.83 | 1.75 | | | 2.75 | | | 3.00 | | | 1.67 | 2.00 | 1.50 |

SU/SET/B. Tech./EEE



| Sch | nool: SET | | | | | | | | | |
|-----|--|---|--|--|--|--|--|--|--|--|
| Pro | ogram: B.Tech | | | | | | | | | |
| Bra | anch: EEE | Semester: VI: | | | | | | | | |
| 1 | Course Code | EEP335 | | | | | | | | |
| 2 | Course Title | Power System-II Lab | | | | | | | | |
| 3 | Credits | 1 | | | | | | | | |
| 4 | Contact Hours (L-T-P) | 0-0-2 | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | |
| 5 | 5 Course Objective The objective of the course is to expose students to the techniques of protecting the various subsystems of a power system during their norm operation and also under fault condition. The students will also be acquainted with the techniques to coordinate these protecting devices a systems | | | | | | | | | |
| 6 | Course Outcomes | CO1: Exposure to the modeling of individual power system contransmission lines and generators CO2: Formulate the load flow problems using various methods CO3: Perform the numerical and phasor analysis of fault occur power system and calculate current and voltages in faulted power CO4: Perform stability analysis using various methods CO5: Identify and employ the methods to control real and real | ds irrences in ver system. | | | | | | | |
| | | and frequency and voltage of power system CO6: Analyse of stability, security and control of power system | m | | | | | | | |
| 7 | Course Description | Reliability of electrical energy systems to a large extent is of the reliability of its protection system. Basic building protection system are fuses, over current and distant differential protection schemes. In this course, we will is principles and applications to apparatus and system protection | a consequence blocks of the ce relays and introduce their | | | | | | | |
| 8 | Outline syllabus | 3 | CO Mapping | | | | | | | |
| | Unit 1 | Practical based on Power System Protection | | | | | | | | |
| | | To analyse the single-phase fault on a power system network using MATLAB/PSCAD | CO1 | | | | | | | |
| | | To analyse the Line-Line fault on a power system network using MATLAB/PSCAD | CO1 | | | | | | | |
| | | To analyse the three-phase fault on a power system network using MATLAB/PSCAD | CO1 | | | | | | | |
| | Unit 1I | Practical based on Relays | | | | | | | | |
| | | To determine the operating characteristics of over-current relay. | CO2 | | | | | | | |
| | | To determine the operating characteristics of over-voltage relay. | CO2 | | | | | | | |



| Unit III | Practical bas | sed on Pow | er Apparatus | | | | | |
|---------------------|---|--|-----------------------|--------------|-----|--|--|--|
| | | | ng characteristics of | inverse | CO2 | | | |
| | definite mean | - | 0 | | | | | |
| | | | ng characteristics of | bimetallic | CO2 | | | |
| | Thermal relay | - | 0 | | | | | |
| UniT IV | Practical bas | sed on Circ | uit Interruption | | | | | |
| | To obtain the characteristics of a circuit breaker during | | | | | | | |
| | circuit interru | circuit interruption in a power system using | | | | | | |
| | MATLAB/PS | SCAD | | | | | | |
| UNIT V | Practical bas | | | | | | | |
| | To study the working and application of ac circuit breaker | | | | | | | |
| | and dc circuit breaker | | | | | | | |
| Mode of | Practical | | | | | | | |
| examination | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | |
| Distribution | 60% | 0% | 40% | | | | | |
| Text book/s* | Badri Ram, D.N.Vishwakarma, 'Power System Protection & Switchgear', TataMcGraw –hill publishing company ltd, New Delhi. ISBN:9780071077743, 007107774X C.L Wadhwa, 'Electrical Power Systems', New Age International (p) limited. ISBN:9788122417739, 8122417736 | | | | | | | |
| Other References | Bhavesh Bha "Protection a ISBN:978019 | nd Switchg | | G. Chothani, | | | | |

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----|------|------|------|------|------|-----|-----|-----|-----|------|------|------|------|------|------|
| CO1 | 3 | 1 | | | | | | | | 3 | | | 3 | 3 | 3 |
| CO2 | 3 | 3 | 1 | 3 | | | | | | 3 | | | 2 | 3 | 3 |
| CO3 | 2 | 3 | 1 | 2 | | | | | | 3 | | | 2 | 3 | 3 |
| CO4 | 2 | 3 | 1 | 2 | | | | | | 3 | | | 2 | 3 | 3 |
| CO5 | 2 | 2 | 3 | | 3 | | | | | 3 | | | 2 | 3 | 3 |
| CO6 | 3 | 3 | 3 | 3 | 3 | | | | | 3 | | | 3 | 3 | 3 |
| | 2.50 | 2.50 | 1.80 | 2.50 | 3.00 | | | | | 3.00 | | | 2.33 | 3.00 | 3.00 |



| | ool: SET | | | | | | | | | |
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| | gram: B. Tech. | | | | | | | | | |
| Bra | nch: EEE | Semester: VI | | | | | | | | |
| 1 | Course Code | EEE335 | | | | | | | | |
| 2 | Course Title | Power System-II | | | | | | | | |
| 3 | Credits | 3 | | | | | | | | |
| 4 | Contact Hours | 3-0-0 | | | | | | | | |
| | (L-T-P) | | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | |
| | Course | To acquaint the students with the tools for performing p | ower flow | | | | | | | |
| 5 | Course | and fault analysis in power system and modern method | for control of | | | | | | | |
| | Objective | power flow through existing lines. | | | | | | | | |
| | | On successful completion of this course students will be able | e to | | | | | | | |
| | | CO1: Exposure to the modeling of individual power system cor | | | | | | | | |
| | | transmission lines and generators | | | | | | | | |
| | | CO2: Formulate the load flow problems using various methods | | | | | | | | |
| | | CO3: Perform the numerical and phasor analysis of fault occur | | | | | | | | |
| 6 | Course | power system and calculate current and voltages in faulted power | er system. | | | | | | | |
| U | Outcomes | CO4: Perform stability analysis using various methods | | | | | | | | |
| | | CO5: Identify and employ the methods to control real and reactive power | | | | | | | | |
| | | and frequency and voltage of power system | | | | | | | | |
| | | CO6: Analyse of stability, security and control of power system | 1 | | | | | | | |
| | | | | | | | | | | |
| 7 | Course Description | This course will introduce and explain the fundamental of field of electrical power system engineering. The basic co- unit system will be introduced along with their application applications. Basic load flow algorithms will be cover in with short circuit analysis and the method of symmetrica Unbalanced fault analysis and basic power system stability also be covered in these lecture series. By the end of the students should be able to gather high quality knowledge power system components, its operation strategies, and stability | oncepts of per ons in circuit details along l components y analysis will ne course, the e of electrica | | | | | | | |
| 8 | Outline syllabus | | CO Mapping | | | | | | | |
| | Unit 1 | Review of Basic Concept | | | | | | | | |
| | A | Representation of synchronous machine and transformer in | CO3, CO4 | | | | | | | |
| | | power system | <i>,</i> | | | | | | | |
| | В | Single line diagram, Impedance and Reactance Diagram | CO3, CO4 | | | | | | | |
| | С | Per-unit system and its significance, change of base | CO3, CO4 | | | | | | | |
| | Unit 2 | Power Flow Analysis | | | | | | | | |
| | А | Formation of bus admittance matrix (YBUS) using | CO1 | | | | | | | |
| | | inspection method and singular transformation method | | | | | | | | |
| | В | Bus classifications, Solution of non-linear algebraic | CO1, CO2 | | | | | | | |
| | | equations | , - | | | | | | | |
| CI1 /0 | ET/B. Tech./EEE | Gauss Seidel method, Newton Raphson method and Fast- | CO1, CO2 | | | | | | | |
| 30/3 | EI/D. IECH./EEE | decoupled method (Algorithms and flow-charts), | , | | | | | | | |

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| | UNIVEDCITY |
| | Beyond Boundaries |

| | comparison o | f the three me | hods | |
|---------------------|-----------------|------------------|---|----------|
| Unit 3 | Fault Analys | sis | | |
| А | Types of faul | ts, Short circui | t capacity | CO1, CO3 |
| В | Symmetrical | components of | f unsymmetrical phasor, | CO1, CO3 |
| | Sequence imp | pedances, Sequ | ence networks | |
| С | Fault analysis | s of L-G, L-L | and L-L-G faults | CO1, CO3 |
| Unit 4 | Power System | m Stability | | |
| A | rotor angle st | ability and vol | ons, Classification of stability, tage stability, Comparison of nic stability and transient | CO1, CO4 |
| В | | | g equation, Equal area criteria, by step by step method | CO1, CO4 |
| С | Factors influe | | t stability, Techniques for | CO1, CO4 |
| Unit 5 | | m Control and | | |
| A | Concept of lo | ad frequency of | control | CO5 |
| В | Methods of v | oltage control | | CO5 |
| С | Introduction t | | | CO5 |
| Mode of examination | Theory | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 30% | 20% | 50% | |
| Text book/s* | | | J., 'Modern Power System l Publishing Company Limited | |
| Other | 1. Grainer J.J. | and Stevenso | n W.D., 'Power System | |
| References | Analysis' McC | | - | |
| | | | n Analysis' McGraw Hill. | |



| COs | PO | PO | PO3 | PO | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 | PSO |
|-------------|-----|-----|------|-----|------|-----|-----|-----|-----|------|------|------|------|------|------|------|
| | 1 | 2 | | 4 | | | | | | | | | | | | |
| CO335. 1 | 3 | 1 | | | | | | | | | | | 3 | | | 3 |
| CO335. 2 | 3 | 3 | 1 | 3 | | | | | | | | | 2 | | | 3 |
| CO335. 3 | 2 | 3 | 1 | 2 | | | | | | | | | 2 | | | 2 |
| CO335. 4 | 2 | 3 | 1 | 2 | | | | | | | | | 2 | | | 2 |
| CO335. 5 | 2 | 2 | 3 | | 3 | | | | | | | | 2 | 3 | 2 | 2 |
| CO335. 6 | 3 | 3 | 3 | 3 | 3 | | | | | | | | 3 | 3 | | 3 |
| | 2.5 | 2.5 | | 2.5 | | | | | | | | | | | | |
| | 0 | 0 | 1.80 | 0 | 3.00 | | | | | | | | 2.33 | 3.00 | 2.00 | 2.50 |

SU/SET/B. Tech./EEE





PROGRAM ELECTIVES

SU/SET/B. Tech./EEE



| SE | Т | | | | | | | | |
|---|---------------|---|------------------|--|--|--|--|--|--|
| Pro | gram: B.Tech | | | | | | | | |
| | nch: EEE/EE | Semester: | | | | | | | |
| 1 | Course Code | EEE444 | | | | | | | |
| 2 | Course Title | HVDC and FACTS | | | | | | | |
| 3 | Credits | 3 | | | | | | | |
| 4 | Contact Hours | 3-0-0 | | | | | | | |
| | (L-T-P) | | | | | | | | |
| | Course Status | Department Elective | | | | | | | |
| 5 | Course | To provide students with the ability of: | | | | | | | |
| | Objective | 1. Comprehend the concept behind planning of HVDC transmis | ssion and | | | | | | |
| | | comparison with AC power transmission. | | | | | | | |
| | | Implementing control strategies for the power flow control Systems. | in AC-DC | | | | | | |
| | | | | | | | | | |
| | | 3. An thoughtful on the fundamentals of power flow control | | | | | | | |
| | | 4. An indulgent on the fundamentals of FACTS controllers | | | | | | | |
| 6 | Course | On successful completion of this course students will be able t | :0 | | | | | | |
| | Outcomes | | _ | | | | | | |
| | | CO1: Explain the objective and functions of different components of | • | | | | | | |
| | | CO2: Differentiate between different controls schemes for the control of DC link. | | | | | | | |
| | | CO3: Analyzed the process of commutation failure and also understand the | | | | | | | |
| | | techniques to protect the HVDC system against over-voltage and o | ver-currents. | | | | | | |
| | | CO4: Summarized the benefits of FACTS devices. | | | | | | | |
| | | CO5: Describe principle of operation and configuration of FACTS de | vices | | | | | | |
| | | Acquire the knowledge of FACTS and HVDC system concept and general | | | | | | | |
| | | CO6 Acquire the knowledge of FACTS and HVDC system concep system considerations | 80.00 | | | | | | |
| | | system considerations | | | | | | | |
| 7 | Course | This subject deals with the importance of HVDC transmission, analy | sis of HVDC | | | | | | |
| | Description | Converters, Harmonics and Filters, Reactive power control and Pov | ver factor | | | | | | |
| | 1 | improvements of the system. It also deals with basic FACTS concep | ts, static shunt | | | | | | |
| | | and series compensation and combined compensation techniques | | | | | | | |
| 8 | | | | | | | | | |
| | Unit 1 | HVDC System Configuration and Components | | | | | | | |
| A Classification of HVDC links, components of HVDC transmission CO1 system. | | | | | | | | | |
| | В | Comparison of AC and DC Transmission, application of DC | C01,C06 | | | | | | |
| | U | Transmission. | | | | | | | |
| | С | Graetz Bridge, Choice of converter configuration, characteristics | CO1 | | | | | | |
| | | of a twelve pulse converter. | | | | | | | |
| | Unit 2 | HVDC System Control | | | | | | | |
| | | | | | | | | | |



| - | - | | | K Bey | | | | |
|------------------------|--|--|---------------------------------------|---------|--|--|--|--|
| Α | | | trol implementation. | CO2,CO6 | | | | |
| В | - | | nk, firing angle control, current and | CO2 | | | | |
| | extinction angle | | | | | | | |
| С | Harmonics and | | | CO2 | | | | |
| Unit 3 | Converter Fault | onverter Faults and Protection | | | | | | |
| А | Types of conver | pes of converter faults, commutation failure. | | | | | | |
| В | DC line fault, AC | C system fault | | CO3 | | | | |
| С | - | | kers, surge arresters. | CO3 | | | | |
| Unit 4 | Introduction to | introduction to FACTS | | | | | | |
| А | Introduction to | power flow co | ontrol, loading capability. | CO4,CO6 | | | | |
| В | Steady state an | d dynamic lim | its of power transmission. | CO4 | | | | |
| С | Applications of | FACTS and it | s benefits. | CO4 | | | | |
| Unit 5 | Types of FACTS | | | | | | | |
| А | | Shunt controllers: Principle of operation, configuration and control of SVC and STATCOM | | | | | | |
| В | | rs : Principle o | f operation, configuration and | CO5 | | | | |
| С | Hybrid controlle | • | f operation, configuration and | CO5 | | | | |
| Mode of examination | Theory | | | | | | | |
| Weightage | СА | MTE | ETE | | | | | |
| Distribution | 30% | 20% | 50% | | | | | |
| Text book/s* | International, 2 2G. Hingorar and technology | 1. Padiyar K.R., HVDC Transmission Systems, New Age International, 2011 ISBN:9781906574772, 1906574774 2G. Hingorani and L. Gyugi, "Understanding FACTS: concepts and technology of Flexible AC Transmission systems", 1999, Wiley-IEEE Press ISBN:9780780334557, 0780334558 | | | | | | |
| Other References | - | EEE Power Ser | | | | | | |

| | PO | РО | | | | | | | | | | | | | |
|-----|----|-----|------|------|------|------|-----|-----|------|------|------|------|------|------|------|
| | 1 | 2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 3 | 2 | 2 | 3 | 3 | 1 | | | 1 | 2 | | | 2 | 3 | 2 |
| CO2 | 3 | 2 | 2 | 2 | 3 | 2 | | | 1 | 2 | | | 2 | 3 | 3 |
| CO3 | 3 | 3 | 3 | 2 | 3 | 1 | | | 1 | 2 | | | 3 | 3 | 3 |
| CO4 | 3 | 3 | 2 | 3 | 3 | 3 | | | 1 | 2 | | | 3 | 3 | 3 |
| CO5 | 3 | 3 | 2 | 2 | 2 | 2 | | | 1 | 2 | | | 2 | 2 | 2 |
| CO6 | 3 | 3 | 2 | 2 | 2 | 2 | | | 1 | 2 | | | 2 | 2 | 3 |
| | 3. | 2.6 | 2.17 | 2.33 | 2.67 | 1.83 | | | 1.00 | 2.00 | | | 2.33 | 2.67 | 2.67 |

SU/SET/B. Tech./EEE

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| | 00 7 | | Beyond Boundaries |
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| Scho | ool: SET | | |
| | gram: B.Tech | | |
| | nch:EEE/EE/ECE | Semester: | |
| 1 | Course Code | EEE448 | |
| 2 | Course Title | PLC and SCADA | |
| 3 | Credits | 3 | |
| 4 | Contact Hours | 3-0-0 | |
| | (L-T-P) Course Status | Commulsomy /Elective/Open Elective | |
| 5 | Course Status Course Objective | Compulsory /Elective/Open Elective To provide students with: | |
| 5 | Course Objective | 1. The conceptual as well as practical knowledge of the Industrial | Automation & |
| | | latest technologies being used to achieve Industrial Automation. | |
| 6 | Course Outcomes | CO1: inerpret basic components and their symbols used in convent | tional control |
| | | boards | |
| | | CO2: apply the concept of electrical ladder logic in programming of | PLC instruction |
| | | CO3: indentify various input output components and design wiring | circuit for a PLC |
| | | | |
| | | CO4: implement the input-output and programming techniques for | · interfacing PLC |
| | | | - |
| | | CO5: design monitoring and control schemes for industrial applicati | ions |
| | Course Description | CO6: apply PLC based automation in indusrial applications | |
| 7 | Course Description | This course is aimed at equipping students with appropriate knowledg | and skills |
| | | required in configuring, programming and operating Industrial automa | - |
| | | with the use of Industrial Field Instruments, PLCs, SCADA/ HMI and DC | - |
| | | | |
| | | | |
| | | | |
| 8 | Outline syllabus | | CO Mapping |
| 0 | Unit 1 | Computer Based Industrial Control | |
| | A | Microprocessor/microcontroller based industrial controller: concept | CO1 |
| | | and configuration | |
| | B | Computer based industrial controller: concept and configuration | CO1 |
| | С | Introduction to direct digital control (DDC), distributed control system (DCS) and supervisory control and data acquisition (SCADA) | CO1 |
| | Unit 2 | PLC Basics | + |
| | A | Introduction to PLC, PLC versus | CO2 |
| | | microprocessor/microcontroller/computer; Advantages and | |
| | | disadvantages of PLC | |



| | | | | Beyond Boundaries | | | | | |
|------------------|---------------|--|--|-------------------|--|--|--|--|--|
| В | | | re and physical forms of PLC; Digital | CO3 | | | | | |
| | | its; Analog inputs | | | | | | | |
| C | PLC program | nming: ladder pr | ogramming, function blocks, Instruction | n CO2 | | | | | |
| | | | t, mnemonic programming | | | | | | |
| Unit 3 | PLC Function | | | | | | | | |
| А | | | output registers; Timers and timer | CO4 | | | | | |
| | | ounters and count | | | | | | | |
| В | | g functions; Bit f | | CO4 | | | | | |
| С | Advanced fu | inctions; PLC pro | gramming using various functions | CO4 | | | | | |
| Unit 4 | SCADA Basic | s, Layout and Fu | nctions | | | | | | |
| А | Introduction: | ; Definition and p | ourpose; Controlled / uncontrolled | CO5 | | | | | |
| | variables and | a remotely / local | ly controlled objects in controlled plant | | | | | | |
| В | • | | system; Detailed block schematic of | CO5 | | | | | |
| | SCADA syst | | | | | | | | |
| C | | | data acquisition and transmission, | CO5 | | | | | |
| | | | ection and storage, data processing and | | | | | | |
| | | report generation | | | | | | | |
| | SCADA Hard | dware and Softw | are | | | | | | |
| Unit 5 | | | | | | | | | |
| А | | | : functions, single processor and | CO5 | | | | | |
| | * | or MTU, single a | and dual computer configurations of | | | | | | |
| P | MTU | | for the product of the start of | 005 | | | | | |
| В | | | : functions, architecture / layout; RTU | CO5 | | | | | |
| С | programming | | nd RTU-field device communication | CO5 | | | | | |
| | | | | 005 | | | | | |
| Mode of | Theory/Jury | y/Practical/Viva | | | | | | | |
| examination | | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | | | Programmable Logic Controllers, | | | | | | |
| | Prentice-Hall | | | | | | | | |
| | | | ory Control and Data Acquisition | | | | | | |
| | | | onal Society of Automation, 2010. | | | | | | |
| Other References | | | worth, Programmable Logic | | | | | | |
| | | Controllers, Pearson Edition | | | | | | | |
| | 2. W. Boston | 2. W. Boston, Programmable Logic Controllers, Newnes, (Elsevier) | | | | | | | |
| | 3. H.K. Verm | a, SCADA, e-mon | ograph at www.profhkverma.info, | | | | | | |
| | | | Chapter 2: Functions of SCADA System, | | | | | | |
| | Chapter 3: H | ardware of SCAD | PA System. | | | | | | |



| | | | | | | | | | | | | | | 🚺 веу | | DII I ndaries |
|-------------|----------|----------|----------|----------|----------|----------|----|----|----|-----|-----|------|------|-------|------|------------------|
| COs | PO | PO | PO | PO | PO | PO | PO | PO | PO | PO1 | PO1 | PO1 | PSO | PSO | PSO | PSO |
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 1 | 2 | 1 | 2 | 3 | 4 |
| | | | | | | | | | | | | | | | | |
| CO448 .1 | 3 | 2 | 1 | - | 1 | 2 | - | - | - | - | - | 2 | 2 | 2 | 2 | 3 |
| CO448 .2 | 3 | 3 | 3 | 1 | 3 | 1 | - | - | - | - | - | 2 | 2 | 2 | 2 | 3 |
| CO448 .3 | 3 | 3 | 3 | 3 | 3 | 2 | - | - | - | - | - | 2 | 2 | 2 | 2 | 3 |
| CO448 .4 | 3 | 2 | 1 | 1 | 3 | 1 | - | - | - | - | - | 2 | 2 | 2 | 2 | 3 |
| CO448 .5 | 3 | 3 | 3 | 3 | 3 | 2 | - | - | - | - | - | 2 | 2 | 2 | 2 | 3 |
| CO448 .6 | 3 | 1 | 1 | 1 | 1 | 1 | - | - | - | - | - | 1 | 2 | 2 | 2 | 3 |
| | 3.0 0 | 2.3 3 | 2.0 0 | 1.8 0 | 2.3 3 | 1.5 0 | | | | | | 1.83 | 2.00 | 2.00 | 2.00 | 3.00 |



| Sch | ool: SET | |
|-----|--------------------------|--|
| Pro | gram: | |
| Bra | nch: EEE | Semester: |
| 1 | Course Code | MOO402 |
| 2 | Course Title | Introduction to smart grid |
| 3 | Credits | 2 |
| 4 | Contact Hours (L-T-P) | 2-0-0 |
| | Course Status | |
| 5 | Course Objective | • To introduce the concept of demand-side management for residential, commercial and industrial energy users. |
| | | To give an overview of the different types of demand-side measures. To describe energy auditing and routine data collection and monitoring, andto indicate their benefits. |
| | | To outline information dissemination on demand-side management. To provide an overview of the major implementation challenges for DSM programmes |
| 6 | Course Outcomes | CO1 : To be able to define demand-side management. CO2: To understand the different types of demand-side management measures and their suitability to various energy users. CO3: To be aware of the benefits of good reliable data collection for regular performance analysis, and as an essential part of energy auditing CO4: To appreciate the need for effective information dissemination. CO5: To understand the challenges facing the implementation of demand-side management CO 6: To be able to design housekeeping and preventative maintenance in commerce and industry can be used to reduce energy demand. |
| 7 | Course Description | Demand-side management (DSM) has been traditionally seen as a means of reducing peak electricity demand so that utilities can delay building further capacity. In fact, by reducing the overall load on an electricity network, DSM has various beneficial effects, including mitigating electrical system emergencies, reducing the number of blackouts and increasing system reliability. Possible benefits can also include reducing dependency on expensive imports of fuel, reducing energy prices, and reducing harmful emissions to the environment. Finally, DSM has a major role to play in deferring high investments in generation, transmission and distribution networks. Thus DSM applied to electricity |



| | 7 1 | ies significant | economic, reliability and environmenta | | | | | | |
|------------------------|--------------------------------------|--|--|-----------------|--|--|--|--|--|
| \$ Outline syllab | | | | CO Mappin | | | | | |
| Unit 1 | Energy Scenario | | | CO1 | | | | | |
| Α | | | udit, Energy Scenarios, | CO1 | | | | | |
| В | Energy Consum | | • | CO1 | | | | | |
| C | Energy Strategy | , Clean Develop | oment Mechanism | CO1 | | | | | |
| Unit 2 | Energy Audit | | | | | | | | |
| А | Definition of En | ergy Audit, Plac | ce of Audit, | CO2 | | | | | |
| В | Energy – Audit M Project Financin | | inancial Analysis, Sensitivity Analysis, | CO2 | | | | | |
| С | Energy Monitor | ing and Training | g Solar power plant | CO2 | | | | | |
| Unit 3 | Electrical-Load | Management | | CO3 | | | | | |
| А | Electrical Basics | , Electrical Load | Management, | CO3 | | | | | |
| В | Variable- Freque | ency Drives, Ha | rmonics and its Effects, | CO3 | | | | | |
| С | | | Transmission and Distribution Losses | CO3 | | | | | |
| Unit 4 | Demand side M | anagement | | CO4, CO6 | | | | | |
| А | Scope of DSM, E Implementation | | M concept, DSM planning and | CO4, CO6 | | | | | |
| В | Load manageme | CO4, CO6 | | | | | | | |
| С | Tariff options fo | CO4, CO6 | | | | | | | |
| Unit 5 | Energy Conserv | CO5,CO6 | | | | | | | |
| А | | Motivation of energy conservation, Principles of Energy conservation, Energy conservation planning, | | | | | | | |
| В | Energy conserva | CO5, CO6 | | | | | | | |
| С | | and commerci | al sectors, EC in transport, EC in | CO5, CO6 | | | | | |
| Mode of examination | Theory | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | 1. Renewa | | wer for a sustainable future, third edition, le, Oxford University Press, 2013. | | | | | | |
| Other References | 1. Microgr Chowdł Technol | | | | | | | | |



| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | _ | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | - |

SU/SET/B. Tech./EEE



| <mark>Sch</mark> | ool: SET | | |
|------------------|---------------------------|---|---|
| Pro | <mark>gram: B.Tech</mark> | | |
| Bra | nch: EEE | | |
| 1 | Course Code | | |
| 2 | Course Title | Advanced Control Engineering and Controllers | |
| <mark>3</mark> | Credits | 3 | |
| <mark>4</mark> | Contact Hours (L-T-P) | 3-0-0 | |
| | Course Status | | |
| <mark>5</mark> | Course Objective | To provide students with: 1. some advanced concepts in Control Systems Engineering and their a 2. A theoretical understanding of advanced linear control systems and s including the principles of digital control. 3 understanding of performing stability analysis of digital control system 4. knowledge of Analog controller, computer based controller and inte | strategies, ns. |
| <mark>6</mark> | Course Outcomes | After completion of this course students will be able to: CO1: Understand advanced concepts and approaches to control system CO2: Understand industrial controllers of continuous and discontinuou advanced control concepts of cascaded and feed forward controls. CO 3design, develop and operate analog controllers, both electronic an types. CO4: Design develop and operate computer based control systems. CO5Understand simulate and design artificial intelligence based control CO 6: Industrial experiences in control engineering | n designs s types and d pneumatic |
| 7 | Course Description | This course introduces systematic approaches to the design and analysic control systems for industrial applications. | is of advance |
| 8 | Outline syllabus | | CO Mapping |
| <u>,</u> | Unit 1 | Overview of Control System | |
| | A | Elements of control systems; Concept of open loop and closed loop systems; Examples and application of open loop and closed loop systems | CO1 |
| | B | Brief idea of multivariable control systems; Concept of stability and necessary conditions, Routh-Hurwitz criteria and limitations. Correlation between time and frequency responses | CO1 |
| | C | State variable modelling of linear discrete systems, controllability and observability; Nonlinear control systems; Fundamentals- common nonlinearities (saturation, dead-zone, relay, on-off nonlinearity, backlash, hysteresis | CO1 |
| | Unit 2 | Controller Principles | |



| | | | | Beyond Bounda | | | | | |
|---------------------|--------------------------|--|--|----------------------|--|--|--|--|--|
| A | Process Ch | naracteristics; Cor | trol system parameters: error, v | ariable CO2 | | | | | |
| | range, con | trol parameter rai | nge, control lag, dead time, cyclir | ng | | | | | |
| <mark>B</mark> | Discontinu | ious controller mo | odes: two-position mode, multi- | CO2 | | | | | |
| | <mark>position m</mark> | ode; Continuous o | controller modes | | | | | | |
| C | proportion | al, integral and de | erivative control modes; Compos | ite CO2 | | | | | |
| | Control mo | odes: proportiona | l-integral (PI), proportional-deriv | <mark>ative</mark> | | | | | |
| | <mark>(PD) and th</mark> | n <mark>ree mode contro</mark> | <pre>ller (PID); Cascaded and feed-for</pre> | ward | | | | | |
| | <mark>controls</mark> | | | | | | | | |
| <mark>Unit 3</mark> | Analog Col | | | | | | | | |
| A | | on; General featur | | CO3 | | | | | |
| <mark>B</mark> | | | r detector, single mode and com | posite CO3 | | | | | |
| | <mark>mode cont</mark> | <u> </u> | | | | | | | |
| C | | | ortional, proportional-integral (P | <mark>I),</mark> CO3 | | | | | |
| | | | and PID controller. | | | | | | |
| <mark>Unit 4</mark> | | Based Control | | | | | | | |
| A | Introduction (1977) | on; Digital applicat | tions: alarms, two-position contro | | | | | | |
| <mark>B</mark> | Computer | <mark>based controller</mark> | | CO4,CO6 | | | | | |
| C | | | <mark>ftware requirements</mark> | CO4,CO6 | | | | | |
| <mark>Unit 5</mark> | Intelligent | Control Systems | | | | | | | |
| A | Fuzzy-logic | control system: F | uzzy set theory, basic fuzzy set | CO5,CO6 | | | | | |
| | | | uzzy logic controller, methods of | | | | | | |
| _ | | tion of membersh | · · · · · · · · · · · · · · · · · · · | ogic CO5,CO6 | | | | | |
| B | | Methods of defuzzification, fuzzy rule base, design of fuzzy logic control system. | | | | | | | |
| <u>a</u> | | | | | | | | | |
| C | | | em :Artificial neural networks, | CO5,CO6 | | | | | |
| | | | I neuron, network architecture, | | | | | | |
| | learning in | neural networks, | back-propagation, Neurofuzzy co | ontrol | | | | | |
| Mada af | | D | | | | | | | |
| Mode of examination | Theory/Ju | ry/Practical/Viva | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | <u>CA</u> 30% | 20% | 50% | | | | | | |
| Text book/s* | <u>30%</u> | 20% | <mark>30%</mark> | | | | | | |
| ICAL DOOK/S | 1 Curtic D | Johnson "Proces | s Control Instrumentation | | | | | | |
| | | y,"8th Edition Pear | | | | | | | |
| | | | "Control Systems Engineering," | 1+h | | | | | |
| | | w Age Internatio | | 4 | | | | | |
| Other References | | | | | | | | | |
| Suler References | | nandam and S.N. | Deepa, "Principles of soft compu | iting " | | | | | |
| | | Pvt. Limited. | | <u>·····δ</u> | | | | | |
| | , | | | | | | | | |
| | | | 'ijayalakshmi Pai, " Neural | had | | | | | |
| | NWTWORKS | FUZZY LOGIC, and (- | enetic Algorithms," PHI Pvt. Limi | led. | | | | | |

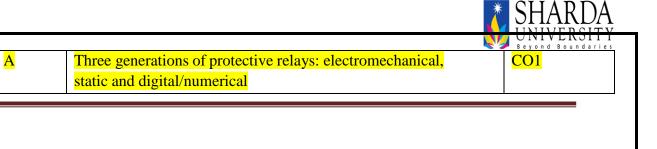


| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|----------------|----------------|----------------|----------------|-----|-----|-----|-----|-----|------|------|------|----------------|----------------|------|
| CO.1 | <mark>3</mark> | 2 | 2 | <mark>1</mark> | - | - | - | - | - | - | - | - | 2 | <mark>1</mark> | 2 |
| CO.2 | <mark>3</mark> | <mark>1</mark> | 2 | <mark>2</mark> | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | <mark>3</mark> | 2 | <mark>2</mark> | 2 | - | - | - | - | - | - | - | - | 2 | <mark>3</mark> | 2 |
| CO.4 | <mark>3</mark> | 1 | <mark>2</mark> | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | <mark>2</mark> | <mark>2</mark> | 1 | - | - | - | - | - | | - | - | <mark>3</mark> | 2 | 2 |
| CO.6 | <mark>3</mark> | <mark>3</mark> | <mark>3</mark> | <mark>2</mark> | - | - | - | - | - | - | - | - | <mark>2</mark> | - | - |

SU/SET/B. Tech./EEE



| | ool: SET | |
|----------------|----------------------|--|
| | gram: B.Tech | Current Academic Year: |
| _ | nch: EEE | Semester: |
| 1 | Course Code | |
| <mark>2</mark> | Course Title | Digital Relaying for Power Systems |
| <mark>3</mark> | Credits | <mark>3</mark> |
| <mark>4</mark> | Contact | 3-0-0 |
| | Hours | |
| | <mark>(L-T-P)</mark> | |
| | Course Status | Compulsory |
| <mark>5</mark> | Course | 1. to understand the concept of digital protection and computer relaying forpower |
| | Objective | system. |
| | | 2. to acquire an in-depth knowledge on different generations of protectiverelays |
| | | 3. to identify different components of a numerical relay |
| | | 4. to apply discrete Fourier transform technique in Power System |
| | | Protection |
| | | 5. to design and develop relay algorithms for protection of power system |
| | | apparatus |
| | | |
| | | |
| <mark>6</mark> | Course | CO1: to compare, analyse the advantages and disadvantages of all the three |
| | Outcomes | generations of protective relay and also identify the different components of a |
| | | numerical relay |
| | | CO2: to develop relay algorithms based on relaying signals |
| | | CO3: to develop algorithm for digital protection of generator |
| | | CO4: to develop algorithm for digital protection of transformer |
| | | CO5: to apply ANN for protection of transmission line and power |
| | | transformer |
| | | CO6: to design and evaluate protection algorithms for protection of anypower |
| _ | | system component |
| <mark>7</mark> | Course | The first and foremost driving force for advances in relaying systems is the need |
| | Description | improve reliability. In turn, this implies increase in dependability as well a |
| | | security. This need to improve reliability propelled the development of digit |
| | | relaying. In this course, the students will have an exposure to the three generation |
| | | of protective relays. |
| | | Throughout the course, students will have an opportunity to be exposed to |
| | | different numerical techniques for protection of generators, transformers and |
| | | transmission lines. |
| <mark>8</mark> | Outline syllabus | CO Mapping |
| <mark>v</mark> | Unit 1 | Introduction and Architecture of Digital Relay |
| | | indoduction and Architecture of Digital Actay |





| B | architecture and elements of a digital relay | CO1 |
|---------------------|--|-----------|
| C | Multifunctional relays, management relays and IED Relays | CO1 |
| Unit 2 | Relay Algorithms and Mathematical Basis | |
| A | Relay Algorithms based on pure sinusoidal relaying | CO2 & CO6 |
| | signals, distorted relaying signals and differential equation | |
| | representation of system; | |
| B | Z transform, sine and cosine Fourier series, Fourier | CO2 & CO6 |
| | Transform and DFT | |
| C | Walsh functions, digital filters, windows and windowing. | CO2 & CO6 |
| Unit 3 | Digital Relaying for Generator | |
| A | Various protection functions: differential, stator earth fault, | CO3 & CO6 |
| | loss of excitation and reverse power protection | |
| B | Abnormal frequency and voltage protection: over and under | CO3 & CO6 |
| | frequency protection, over and under voltage | |
| C | protection | |
| | Numerical differential protection of generator | CO3 & CO6 |
| Unit 4 | Digital Relaying for Transformer | |
| A | Types of faults encountered in transformer, basic | CO4 |
| | considerations for transformer differential protection, | |
| B | stabilizing of differential protection during magnetizing inrush current | CO4 |
| C | Numerical protection of transformer | CO4 |
| Unit 5 | Artificial Intelligence Based Numerical Protection | CO5 |
| A | Types of Neural Network Models, Artificial Neural | CO5 |
| _ | Network, Design Procedure and Consideration | |
| <mark>B</mark> | Application of ANN to transmission line protection | CO5 |
| C | ANN based power transformer protection | |
| Mode of | Theory | |
| examination | | |
| Weightage | CA MTE ETE | |
| Distribution | 30% 20% 50% | |
| Text book/s* | 1. Arun G Phadke and James S. Thorp, "Computer Relaying | |
| | for Power Systems", John Wiley and SonsInc, New York. | |
| | 2. Badri ram, D.N. Vishwakarma, 'Power System | |
| | Protection & Switchgear', Tata McGraw –hill | |
| | publishing company ltd, New Delhi. | |
| Other | 1. Bhavesh Bhalja, R.P. Maheswari and Nilesh G. | |
| References | Chothani, "Protection and Switchgear", Oxford. | |
| IXCICICITUES | Chomani, Trotection and Switchgear, Oxford. | 1 |

| | | | | | | | | | | | | | | UNIV Beyond | LILL |
|-------------------|----------------|----------------|----------------|----------------|-----|-----|-----|-----|-----|------|------|------|----------------|----------------|------|
| <mark>COs</mark> | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSC |
| <mark>CO.1</mark> | <mark>3</mark> | <mark>2</mark> | <mark>2</mark> | <mark>1</mark> | - | - | - | - | - | - | - | - | <mark>2</mark> | <mark>1</mark> | 2 |
| <mark>CO.2</mark> | <mark>3</mark> | 1 | <mark>2</mark> | <mark>2</mark> | - | - | - | - | - | - | - | - | - | - | 2 |
| <mark>CO.3</mark> | <mark>3</mark> | <mark>2</mark> | <mark>2</mark> | <mark>2</mark> | | - | - | - | - | - | - | - | 2 | <mark>3</mark> | 2 |
| <mark>CO.4</mark> | <mark>3</mark> | 1 | <mark>2</mark> | <mark>2</mark> | | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | <mark>2</mark> | <mark>1</mark> | | - | - | - | - | | - | - | <mark>3</mark> | 2 | 2 |
| CO.6 | <mark>3</mark> | 3 | <mark>3</mark> | 2 | _ | _ | _ | _ | _ | _ | _ | _ | 2 | _ | - |



| | lool: SET | | |
|------------|--|---|---|
| | ogram: M.Tech | | |
| | nch: EEE | Somoston | |
| <u>БГа</u> | | Semester: | |
| 1 | Course Code | Distributed Conception Technologie | |
| 2 | Course Title | Distributed Generation Technology | |
| 3 | Credits | 3 | |
| 4 | Contact Hours | 3-0-0 | |
| | (L-T-P) | | |
| | Course Status | | |
| 5 | Course | To introduce the concept of distributed generation, microgrids, electric ve | ehicles and |
| | Objective | energy storage. | |
| | | To familiarize the students with renewable generation system modelling, | and their grid |
| | | integration issues. | |
| | | To impart an understanding of economics, policies and technical regulation | ons for DG |
| 6 | Course | integration CO1 : Analyse the concept and importance of distributed generation. | |
| 0 | Outcomes | CO2: Understand different renewable energy sources, micro-grid and sto | r200 |
| | Outcomes | Devices. | age |
| | | CO3: Evaluate the technical impact of DG in power system | |
| | | CO4: Analyze the operation and control strategies for grid connected and | l off-grid |
| | | System. | |
| | | • | |
| | | 1 CO5. Evaluate the effect of DG placement in the existing system | |
| | | CO5: Evaluate the effect of DG placement in the existing system | |
| 7 | Course | CO 6: Industrial experiences in renewable energy integration | ovoltaic systems |
| 7 | Course | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot | • |
| 7 | Course Description | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi | ples of control of |
| 7 | | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution system | ples of control of ms, installation, |
| 7 | | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi | ples of control of ms, installation, |
| 7 | | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distributed | ples of control of ms, installation, puted generation, |
| 7 8 | Description Outline syllabu | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. | ples of control of ms, installation, puted generation, CO Mapping |
| | Description | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation | ples of control of ms, installation, outed generation, CO Mapping CO1 |
| | Description Outline syllabu | CO 6: Industrial experiences in renewable energy integrationThis syllabus gives an overview of distributed energy resources, photsmall hydro, fuel cells, energy storage technologies; wind turbines, Princidistributed generation systems; Electric power distribution systeinterconnection and integration; Economic and financial aspects of distributethe regulatory environment and standards.Introduction to Distributed GenerationConcept of DG and, its definition, Current scenario in distributed | ples of control of ms, installation, outed generation, CO Mapping CO1 |
| | Description Outline syllabu Unit 1 | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distributed the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation | ples of control of ms, installation, outed generation, CO Mapping CO1 |
| | Description Outline syllabu Unit 1 A B | CO 6: Industrial experiences in renewable energy integrationThis syllabus gives an overview of distributed energy resources, photsmall hydro, fuel cells, energy storage technologies; wind turbines, Princidistributed generation systems; Electric power distribution systeinterconnection and integration; Economic and financial aspects of distributethe regulatory environment and standards.Introduction to Distributed GenerationConcept of DG and, its definition, Current scenario in distributed | ples of control of ms, installation, outed generation, CO Mapping CO1 |
| | Description Outline syllabu Unit 1 A | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distributed the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation | ples of control of ms, installation, outed generation, CO Mapping CO1 CO1 |
| | Description Outline syllabu Unit 1 A B C | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distribute the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG | ples of control of ms, installation, outed generation, CO Mapping CO1 CO1 CO1 |
| | Description Outline syllabu Unit 1 A B C Unit 2 | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distribute the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation | ples of control of ms, installation, outed generation, CO Mapping CO1 CO1 CO1 CO1 |
| | Description Outline syllabu Unit 1 A B C Unit 2 A | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant | iples of control of ms, installation, outed generation, CO1 CO1 CO1 CO1 CO1 CO1 CO1 CO1 |
| | Description Description Outline syllabu Unit 1 A B C Unit 2 A B | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distribute the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant | CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO2 CO2 |
| | Description Outline syllabut Unit 1 A B C Unit 2 A B C | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG | CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 |
| | Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG | CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 |
| | Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 A | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG Transmission systems, Distribution systems | CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 CO3 |
| | Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 A B | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG Impact of DGs upon protective relaying | CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 CO3 CO3 |
| | Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 A | CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG Transmission systems, Distribution systems | CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 CO3 |



| Unit 4 | Onoration and | - Feanami | c aspects of DGs | CO4, CO6 | | | |
|---------------------|----------------|-------------|--|----------|--|--|--|
| | | | * | / | | | |
| A | De-regulation | 1 / | es, Reactive power control, Harmonics, | CO4, CO6 | | | |
| В | Ū. | CO4, CO6 | | | | | |
| | · · · | | ability of DG based systems | | | | |
| С | Economic imp | oacts: Mark | tet facts, issues and challenges | CO4, CO6 | | | |
| Unit 5 | Grid integrati | on of DGs | | CO5,CO6 | | | |
| A | Optimal placer | nent of DG | sources in distribution systems | CO5, CO6 | | | |
| В | • 1 | | ces , Inverter based DGs and rotating , Aggregation of multiple DG units | CO5, CO6 | | | |
| С | Energy storage | CO5, CO6 | | | | | |
| Mode of examination | Theory | | | | | | |
| Weightage | CA | MTE | ETE | | | | |
| Distribution | 30% | 20% | 50% | | | | |
| Text book/s* | 2. Renewa | ble Energy- | Power for a sustainable future, third edition, | | | | |
| | | 0, | Boyle, Oxford University Press, 2013. | | | | |
| Other References | Chowdh | | ve Distribution Networks, S. Chowdhury, S.P. Crossley, The Institution of Engineering and n, U.K, 2009 | | | | |

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | - |



| - | nool: SET | | | | | | | | |
|-----|--|--|---|--|--|--|--|--|--|
| | ogram: B.Tech | Current Academic Year: | | | | | | | |
| Bra | anch: EEE | Semester : | | | | | | | |
| 1 | Course Code | | | | | | | | |
| 2 | Course Title | Intelligent Actuators and Mechatronics | | | | | | | |
| 3 | Credits | 3 | | | | | | | |
| 4 | Contact | 3-0-0 | | | | | | | |
| | Hours | | | | | | | | |
| | (L-T-P) | | | | | | | | |
| | Course Status | | | | | | | | |
| 5 | Course | • Discussing of basic components of actuators and mechatr | onics | | | | | | |
| | Objective | • Discussing of electronics and digital circuits concepts of t | he subject | | | | | | |
| | | | | | | | | | |
| | | Explaining concept of intelligent and smart system Discussing of interfacing concepts of mask stranges systems | | | | | | | |
| | | • Discussing of interfacing concepts of mechatronics system | | | | | | | |
| | | • Giving case studies and exploring knowledge on designing | g | | | | | | |
| 6 | Course | CO 1. Cotting browledge on basis services of the t | and | | | | | | |
| 6 | Course | CO 1: Getting knowledge on basic components of actuators | and | | | | | | |
| | Outcomes | mechatronics | | | | | | | |
| | | CO 2: Exploring knowledge and getting design concepts of a | | | | | | | |
| | | CO 3: Identifying concepts smart and intelligent on mechatronics systems $CO(4)$. Able to design of interfacing circuits for the subject | | | | | | | |
| | | CO 4: Able to design of interfacing circuits for the subject | | | | | | | |
| | | CO 5: Able to design of tailor-made systems | | | | | | | |
| | | | | | | | | | |
| 7 | Comme | CO 6: Industrial experiences in mechatronics systems | 1.4 1 6 1 4 | | | | | | |
| 7 | Course | The field of mechatronics has braddened the scope of the tra | | | | | | | |
| 7 | Course Description | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre | ends on | | | | | | |
| 7 | | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand | ends on | | | | | | |
| - | Description | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. | ends on l alone | | | | | | |
| - | Description Outline syllabutic | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. | ends on l alone | | | | | | |
| - | Description Outline syllabu Unit 1 | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. | ends on l alone CO Mappin | | | | | | |
| - | Description Outline syllabutic | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. | ends on l alone | | | | | | |
| - | Description Outline syllabu Unit 1 A | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding | ends on l alone CO Mappin CO1 | | | | | | |
| - | Description Outline syllabu Unit 1 A B | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators | CO Mappin CO Mappin CO1 CO1 | | | | | | |
| - | Description Outline syllabu Unit 1 A | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of | ends on l alone CO Mappin CO1 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course | CO Mappin CO Mappin CO1 CO1 CO1 CO1 | | | | | | |
| 7 8 | Description Outline syllabu Unit 1 A B C Unit 2 | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics | CO Mappin CO Mappin CO1 CO1 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation | CO Mappin CO Mappin CO1 CO1 CO1 CO1 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers | co Mappin CO Mappin CO1 CO1 CO1 CO1 CO2 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A B | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration | cnds on alone CO Mappin CO1 CO1 CO1 CO1 CO2 CO2 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their | cnds on l alone CO Mappin CO1 CO1 CO1 CO1 CO2 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A B C C | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts | cnds on alone CO Mappin CO1 CO1 CO1 CO1 CO2 CO2 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A B C Unit 2 Unit 3 | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. INTRODUCTION Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts Smart and Intelligent Actuators | ends on l alone CO Mappin CO1 CO1 CO1 CO2 CO2 CO2 CO2 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A B C C | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts Smart and Intelligent Actuators Definitions: Smart and intelligent actuators; Architecture and | cnds on alone CO Mappin CO1 CO1 CO1 CO1 CO2 CO2 | | | | | | |
| - | Description Outline syllabu Unit 1 A B C Unit 2 A B C Unit 2 Unit 3 | The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. INTRODUCTION Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts Smart and Intelligent Actuators | ends on l alone CO Mappin CO1 CO1 CO1 CO2 CO2 CO2 CO2 | | | | | | |



| | | | | 👟 🌽 Beyond Boun | | | | | |
|--------------|------------------|--|--|-----------------|--|--|--|--|--|
| Unit 4 | Mechanical-Ele | ectronic Interfac | ing | | | | | | |
| А | Concept of three | ee-state (tri-stat | e) outputs; Interfacing of | CO4,CO6 | | | | | |
| | pushbutton, ke | ushbutton, keyboard and sensors | | | | | | | |
| В | Interfacing of r | nterfacing of relays, solenoids, DC, AC motors and special | | | | | | | |
| | motors to micr | Interfacing of relays, solenoids, DC, AC motors and special motors to microcontroller Selecting of motor for actuators Case studies & Design Exercise Case study 1: Mechatronic design of a coin counter; Case study | | | | | | | |
| С | Selecting of mo | | | | | | | | |
| Unit 5 | Case studies & | | | | | | | | |
| А | Case study 1: N | | | | | | | | |
| В | Case study 2: N | Case study 2: Mechatronics for conveyor based material | | | | | | | |
| | handling syster | n | | | | | | | |
| С | Design exercise | on mechatroni | c system | CO5,CO6 | | | | | |
| Mode of | Theory | | | | | | | | |
| examination | | | | | | | | | |
| Weightage | СА | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | David G, Alcia | tore et al., "In | troduction to Mechatronics and | | | | | | |
| | | Measurement Systems", Tata McGraw Hill, 2003 | | | | | | | |
| Other | | | | | | | | | |
| References | 2. Godfre | v C. Onwubolu. | "Mechatronics", Elsevier, 2005 | | | | | | |
| | | , | ······································ | | | | | | |

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | - |



| Sch | ool: SET | | Beyond Boundaries |
|-----|------------------------------------|--|--|
| | gram: B.Tech | Current Academic Year: | |
| | nch:EEE | Semester: | |
| 1 | Course Code | | |
| 2 | Course Title | Operation and Control of smart grid | |
| 3 | Credits | 3 | |
| 4 | Contact Hours | 3-0-0 | |
| | (L-T-P) | | |
| | Course Status | | |
| 5 | Course Objective | The objective of the subject on smart grid technologies is to interest optimize distributed energy resources to achieve a more efficient grid, enable active participation of consumers with more environ constraints | and reliable |
| 6 7 | Course Outcomes Course Description | The students should be able to CO1: Identify different tools and approaches to modelling a Smat CO2: Apply Optimal Power Flow (OPF) solutions to evaluate the of a power system with renewable energy sources. CO3: Analyze power system dynamics (frequency stability) to achieve balance. CO3: To familiarize the students with modelling of smart grids compered CO5. Identify control-room technologies for system-wide remote management of smart grid cyber security CO 6: Able to design, implementation, evaluation and management electricity infrastructure. | ne performance ve active power onents. onitoring, c of smart pics in the field of |
| | | storage, vehicle-to-grid systems, wide area measurement, smart gretc | id cyber security, |
| 8 | Outline syllabus | | CO Mapping |
| _ | Unit 1 | Modeling of Smart Grids | |
| | А | Operating principles and models of smart gird components,;. | CO1 |
| | В | Key technologies for generation, networks, loads and their control capabilities decision-making tools | CO1 |
| | С | Hardware, Software, Communication. Approaches to estimation, | CO1 |
| | | scheduling, management and control of next generation smart grid | |
| | Unit 2 | Smart Grid Communications | |
| | А | Two-way Digital Communications Paradigm, Network Architectures | CO2 |
| | В | IP-based Systems, Power Line Communications | CO3 |
| | С | Advanced Metering Infrastructure, | CO2 |
| | Unit 3 | Security and Privacy | |
| | А | Cyber Security Challenges in Smart Grid,Load Altering Attacks | CO4 |
| | В | False Data Injection Attacks, Defense Mechanisms | CO4 |



| | | | | Beyond Boundaries | | | |
|------------------------|---|---|---|-------------------|--|--|--|
| C | Privacy Challen | ges Data hand | lling functions; Bit functions | CO4 | | | |
| Unit 4 | IoT for power sy | ystems | | | | | |
| Α | Internet of thing management. | gs for electrici | ty infrastructure and energy | CO5,CO6 | | | |
| В | SCADA, Demand | l response, Al | ∕II, IoT aided smart grid, | CO5,CO6 | | | |
| С | Big data for pow | ver system an | d introduction to data analytic | cs. CO5,CO6 | | | |
| Unit 5 | Flexible AC tran | | | | | | |
| А | Congestion man power compens | - | loadability enhancement, rea | ctive CO5,CO6 | | | |
| В | concept of serie working principl | • | on, shunt compensation, FACT | -s: CO5,CO6 | | | |
| C | Classification, se | Classification, series controllers, shunt controllers, series-series controllers, series-series | | | | | |
| Mode of examination | Theory/Jury/Pt | | | | | | |
| Weightage | CA | MTE | ETE | | | | |
| Distribution | 30% | 20% | 50% | | | | |
| Text book/s* | Wu, Akihiko Yo Applications", 2 James Mom | okoyama, "Sr John Wiley & oh, "Smart Gr | Jenkins, Kithsiri Liyanage, Jia nart Grid: Technology and a sons inc, 2015. id: Fundamentals of design an nc, IEEE press 2012 | | | | |
| Other References | 1.Fereidoon P. Distributed & I 2.Clark W.Gelli and demand re | Sioshansi, " Efficient Ene Ings, "The sn esponse", Fa | Smart Grid: Integrating Renergy", Academic Press, 2012. art grid: Enabling energy ef irmont Press Inc, 2009. ograph at ww.profhkverma.in | ficiency | | | |

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | - |



| Sch | ool: SET | | |
|-----|--------------------------|--|--|
| Pro | gram: B. Tech. | | |
| | nch: EEE | | |
| 1 | Course Code | | |
| 2 | Course Title | Operation and Control of smart grid Lab | |
| 3 | Credits | 2 | |
| 4 | Contact Hours (L-T-P) | 0-0-4 | |
| | Course Status | | |
| 5 | Course Objective | Learn modern numerical techniques and analytical method with and solving operation and protection related probled power systems | - |
| 6 | Course Outcomes | After the completion of course student will be able to CO1: explore the concept of automatic generation control. CO2: apply the modes of excitation systems and exercises control. CO3: employ incremental cost curve and penalty factor for operation. CO4: plan unit commitment for optimal operation. CO5: evaluate power system security and methods of impri CO6: compare the protection techniques used for protection power system components | voltage or economic rovement. |
| 7 | Course Description | This course aims to convince the student that constancy of voltage are the primary health indicator of the power maintaining the real and reactive power balance in systems of economic load dispatch and unit commitment are also course. The concept of close coordination between there power plant to meet the load demand has been included in t | er system for 5. The concepts 50 given in the mal and hydro |
| 8 | | | |
| | Unit 1 | Practical related to economic load dispatch and Unit Commitment | |
| | А | To perform economic load dispatch without considering losses using MATLAB | CO3 |
| | В | To perform economic load dispatch with considering losses using MATLAB | CO3 |
| | С | To solve unit commitment method using priority list scheme in MATLAB | CO4 |
| | Unit 2 | Practical related to load frequency control and voltage | |





| | control | | | |
|--------------|-----------------------------------|--------------------|--|------------|
| А | To design load | frequency co | ntrol model in MATLAB | CO1 |
| В | | | n most optimal location and | CO2 |
| | | | tage profile using | |
| | MATLAB/PS | | | |
| C | | | n most optimal location and | CO2 |
| | | | ver transfer capability using | |
| II:4 2 | MATLAB/PS | | system security and | |
| Unit 3 | excitation cor | | | |
| A | | | control model in PSCAD. | CO2 |
| B | - | | ontrol model in PSCAD. | CO2 CO2 |
| C | 0 | | f a system using contingency | CO2 |
| C | analysis in MA | 005 | | |
| Unit 4 | Practical rela | | | |
| А | To simulate si | CO6 | | |
| | measure volta | | | |
| В | To simulate li | CO6 | | |
| | and current at | | | |
| C | To simulate de | CO6 | | |
| | measure voltag | | | |
| Unit 5 | Practical rela | | | |
| А | Principle of va constructions. | CO6 | | |
| В | | | ferential and distance relays | CO6 |
| | and their operation | | | 000 |
| C | • | s: introduction | to static and essor based) relays and | CO6 |
| | Intelligent Ele | · • | , . | |
| Mode of | Practical | | (ILD) Iciayo | |
| examination | - raction | | | |
| Weightage | CA | MTE | ETE | |
| Distribution | 60% | 1 | | |
| Text book/s* | Allen. J. Woo | Wollenberg, "Power | | |
| | | | ontrol", John Wiley & Sons, | |
| | Inc., 2003. | | - | |

| | SHARDA | |
|---------------------|---|--|
| Other References | P.Kundur, "Power System Stability and Control"MC Craw Hill Publisher, USA, 1994. Olle.I.Elgerd, "Electric Energy Systems Theory An Introduction" Tata McGraw Hill Publishing Company Ltd. New Delhi, Second Edition 2003 | |
| | | |

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | _ | - | - | 2 | - | - |

SU/SET/B. Tech./EEE



| Sch | nool: SET | | | | | | | |
|-----|--------------------------|--|------------|--|--|--|--|--|
| Pro | gram: B.Tech | | | | | | | |
| | anch: EEE | Semester: | | | | | | |
| 1 | Course Code | EEE448 | | | | | | |
| 2 | Course Title | PLC and SCADA | | | | | | |
| 3 | Credits | 3 | | | | | | |
| 4 | Contact Hours (L-T-P) | 3-0-0 | | | | | | |
| | Course Status | | | | | | | |
| 5 | Course Objective | To provide students with: 1. The conceptual as well as practical knowledge of the Industrial Automation & latest technologies being used to achieve Industrial Automation. | | | | | | |
| 6 | Course Outcomes | The students should be able to CO1: understand the concepts of computer based Industrial Control, including PLC, DCS and SCADA. CO2: understand hardware of PLC and ladder programming for PLC CO3: use various PLC functions and develop PLC programs for | | | | | | |
| | | industrial control and automation applications. CO4: understand the purpose, layout, components and functions of SCADA systems and use the knowledge for the operation of SCADA systems in Industry CO5.design SCADA system including layout, communication system and software. CO 6: Industrial experiences in PLC and SCADA. | | | | | | |
| 7 | Course Description | This course is aimed at equipping students with appropriate knowledge skills required in configuring, programming and operating Industrial automation systems with the use of Industrial Field Instruments, PLC and SCADA systems. | | | | | | |
| 8 | Outline syllabus | | CO Mapping | | | | | |
| | Unit 1 | Computer Based Industrial Control | | | | | | |
| | A | Microprocessor/microcontroller based industrial controller: concept and configuration | CO1 | | | | | |
| | В | Computer based industrial controller: concept and configuration | CO1 | | | | | |
| | С | Introduction to direct digital control (DDC), distributed control system (DCS) and supervisory control and data acquisition (SCADA) | CO1 | | | | | |
| | Unit 2 | PLC Basics | | | | | | |
| | A | Introduction to PLC, PLC versus microprocessor/microcontroller/computer; Advantages and disadvantages of PLC | CO2 | | | | | |
| | В | Hardware, internal architecture and physical forms of PLC; Digital inputs/ outputs; Analog inputs/ outputs | CO3 | | | | | |



| | | | | Beyond | | |
|------------------------|---|------------------|---|--------|--|--|
| С | | ists, Sequential | programming, function blocks, function chart, mnemonic | CO2 | | |
| Unit 3 | PLC Function | | | | | |
| А | Registers: holding, input and output registers; Timers and timer functions; Counters and counter functionsData handling functions; Bit functions; | | | | | |
| В | | | | | | |
| С | Advanced fu functions | CO4 | | | | |
| Unit 4 | SCADA Basic | s, Layout and | Functions | | | |
| A | A Introduction; Definition and purpose; Controlled / uncontrolled variables and remotely / locally controlled objects in controlled plant B Layout and parts of SCADA system; Detailed block schematic of SCADA system C Functions of SCADA system: data acquisition and transmission, monitoring, control, data collection and storage, data processing and calculation, report generation | | | | | |
| В | | | | | | |
| С | | | | | | |
| Unit 5 | SCADA Desi | | | | | |
| A | Master Terminal Unit (MTU): functions, single processor and multiprocessor MTU, single and dual computer configurations of MTU; Remote Terminal Unit (RTU): functions, architecture / layout; RTU programming | | | | | |
| В | MTU-RTU o communicat | CO5,CO6 | | | | |
| С | Design of SC Software. | CO5,CO6 | | | | |
| Mode of examination | Theory/Jury | | | | | |
| Weightage | CA | MTE | ETE | | | |
| Distribution | 30% | 20% | 50% | | | |
| Text book/s* | 1. J.W. Web Prentice-Hal 2 Stuart A. (SCADA), 4th 2010. | | | | | |
| Other References | Dther ReferencesJ.R. Hackworth and F.D. Hackworth, Programmable Logic Controllers, Pearson Edition 2. W. Boston, Programmable Logic Controllers, Newnes,(Elsevier). 3. H.K. Verma, SCADA, e-monograph at www.profhkverma.info, Chapter 1: Basics of SCADA, Chapter 2: Functions of SCADA System, Chapter 3: Hardware of SCADA System. | | | | | |



| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | 2 | 2 |

SU/SET/B. Tech./EEE

Page 115



| Sch | ool: | | | | | | | | | | | |
|-----|------------------|--|--------------------------|--|--|--|--|--|--|--|--|--|
| Pro | gram: B.Tech | | | | | | | | | | | |
| | nch: EEE | Semester: II | | | | | | | | | | |
| 1 | Course Code | | | | | | | | | | | |
| 2 | Course Title | PLC and SCADA Lab | | | | | | | | | | |
| 3 | Credits | 2 | | | | | | | | | | |
| 4 | Contact Hours | 0-0-4 | | | | | | | | | | |
| - | (L-T-P) | | | | | | | | | | | |
| | Course Status | Compulsory | | | | | | | | | | |
| 5 | Course | To equip students with the working knowledge abo | ut the PLC based process | | | | | | | | | |
| | Objective | control and SCADA functions. | ×. | | | | | | | | | |
| | 5 | | | | | | | | | | | |
| 6 | Course | CO1: To study and perform basic experiments on PLC | • | | | | | | | | | |
| | Outcomes | CO2: To perform process control using PLC. | | | | | | | | | | |
| 1 | | CO3: To perform motor control using PLC. | | | | | | | | | | |
| | | CO4: To implement basic SCADA functions. | | | | | | | | | | |
| | | CO5: To implement advanced SCADA functions | | | | | | | | | | |
| | | CO6: Industrial experiences in PLC and SCADA. | | | | | | | | | | |
| 7 | Course | The contents of this course covers the implementation of | of basic and advanced | | | | | | | | | |
| | Description | functions of PLC and SCADA and their applications in | | | | | | | | | | |
| 8 | Outline syllabus | | CO Mapping | | | | | | | | | |
| | Unit 1 | PLC based basic experiments | | | | | | | | | | |
| | А | 1.To study and use of NO and NC bit | CO1 | | | | | | | | | |
| | | 2.To study and use of S (Set) and R (Reset) bit | | | | | | | | | | |
| | В | 1.To study and use of Timer instruction | CO1 | | | | | | | | | |
| | | 2. To study and use of Cumulative timer instruction | | | | | | | | | | |
| | С | 1.To study and use of Counter instruction | CO1 | | | | | | | | | |
| | | 2. To study logic gates in PLC. | | | | | | | | | | |
| | Unit 2 | PLC based process control | | | | | | | | | | |
| | А | Water Level Control using PLC | CO2 | | | | | | | | | |
| | В | Conveyor Belt Control Module using PLC | CO2 | | | | | | | | | |
| | С | Traffic control using PLC | | | | | | | | | | |
| | Unit 3 | PLC based Motor Control | | | | | | | | | | |
| | A-B | Ac motor speed control module using PLC. | CO3 | | | | | | | | | |
| | С | Dc motor speed control module using PLC | CO3 | | | | | | | | | |
| | Unit 4 | Basic SCADA functions | | | | | | | | | | |
| | А | Parameter reading of PLC in SCADA. | CO4 | | | | | | | | | |
| | B-C | Alarm annunciation using SCADA. | CO4 | | | | | | | | | |
| | Unit 5 | Advanced SCADA functions | | | | | | | | | | |
| | А | SCADA communication with PLC | CO5, CO6 | | | | | | | | | |
| | В | Trend Monitoring on SCADA | CO4, CO6 | | | | | | | | | |
| | C | Reporting on SCADA | CO6 | | | | | | | | | |
| | Mode of | Practical & Viva | | | | | | | | | | |
| | examination | | | | | | | | | | | |
| 1 | Weightage | CA MTE ETE | | | | | | | | | | |
| | | | | | | | | | | | | |



| | | _ | | | 👟 🎾 Beyond Bound |
|--------------|----------------------|---|--|---------|------------------|
| Distribution | 60% | 0% | 40% | | |
| Text book/s* | Controlle 2 Stuar | rs, Prentice-H t A. Boyer, Sup on (SCADA), 4t | Reis, Programmabl all India pervisory Control ar hEdition, Internatio | nd Data | |
| Other | Refer lab | manuals | | | |
| References | | | | | |

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | 2 | 2 |

SU/SET/B. Tech./EEE

Page 117



| | School: SET | | | | | | | | | |
|------|--|--|--|--|--|--|--|--|--|--|
| Prog | gram: B.Tech | | | | | | | | | |
| Brai | nch:EEE | Semester: | | | | | | | | |
| 1 | Course Code | | | | | | | | | |
| 2 | Course Title | Robotics and Industrial Robots | | | | | | | | |
| 3 | Credits | 3 | | | | | | | | |
| 4 | Contact Hours | 3-0-0 | | | | | | | | |
| | (L-T-P) | | | | | | | | | |
| | Course Status | | | | | | | | | |
| 5 | Course | 1.To understand the construction industrial robotics | | | | | | | | |
| | Objective | 2.To explore knowledge on selection of end-effectors of robotics | | | | | | | | |
| | | 3.To get knowledge of electrical drive systems of industrial robot | | | | | | | | |
| | | | | | | | | | | |
| | | 4.To know types of sensors of industrial robotics | | | | | | | | |
| | | 5. To understand of electrical and electronics interfacings | | | | | | | | |
| 6 | Carrier | 6.To study about applications of industrial robots | | | | | | | | |
| 6 | Course Outcomes | CO1: Basic construction of robot and robotics components | | | | | | | | |
| | Outcomes | CO2: Understanding interfacing & building techniques of robots CO3: Knowing different types of actuators of robotics | | | | | | | | |
| | | CO4: Getting knowledge of robotics sensors and transducers | | | | | | | | |
| | | CO5: Developing interfacing circuits for robotics applications | | | | | | | | |
| | | CO 6: Industrial experiences in Robotics | | | | | | | | |
| | | co o. muusunai experiences in Kobolies | | | | | | | | |
| 7 | 0 | | | | | | | | | |
| | Course | This course gives coverage of robotics components, architecture. | and electronics | | | | | | | |
| / | Course Description | This course gives coverage of robotics components, architecture, interfacing circuits knowledge. Students can also practice program | | | | | | | | |
| , | Description | interfacing circuits knowledge. Students can also practice program | mming of robotics | | | | | | | |
| , | | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the statement of the statement o | mming of robotics his subject. Finally | | | | | | | |
| | Description | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering | mming of robotics his subject. Finally | | | | | | | |
| | | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering. | mming of robotics his subject. Finally ng | | | | | | | |
| | Description Outline syllabus Unit 1 | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis | mming of robotics his subject. Finally ng CO Mapping | | | | | | | |
| | Description Outline syllabus | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; | mming of robotics his subject. Finally ng | | | | | | | |
| 8 | Description Outline syllabus Unit 1 A | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis | mming of robotics his subject. Finally ng CO Mapping CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic | mming of robotics his subject. Finally ng CO Mapping CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 A | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 A B B | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 A | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO1 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 A B B | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3 | | | | | | | |
| | Description Outline syllabus Unit 1 A B C Unit 2 A B C Unit 2 A C C C C C C | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and harmonic drive. | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3 | | | | | | | |
| 8 | Description Outline syllabus Unit 1 A B C Unit 2 A B C Unit 2 A B C Unit 2 A B C Unit 3 A | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and harmonic drive. Sensors of Robotic System | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3 CO2 | | | | | | | |
| 8 | Description Outline syllabus Unit 1 A B C Unit 2 A B C Unit 3 | interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering. Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and harmonic drive. Sensors of Robotic System Uses of sensors in robotics; Shaft Encoders (linear and rotational); | mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO2 CO2,CO3 CO2 CO2 CO2 | | | | | | | |



| | | | | Beyond Boundaries | | | | | |
|--------------|---------------------|---|------------------------|-------------------|--|--|--|--|--|
| A | Basics of PC inter | facings | | CO5 | | | | | |
| В | Microcontroller i | nterfacings | | CO5 | | | | | |
| С | Robot languages | Robot languages and classification; Robot software. | | | | | | | |
| Unit 5 | Industrial Robot | Applications | | | | | | | |
| А | Material handling | g robots | | CO6 | | | | | |
| В | Welding Robots | | | CO6 | | | | | |
| С | Assembling robo | ts | | CO6 | | | | | |
| Mode of | Theory | | | | | | | | |
| examination | | | | | | | | | |
| Weightage | CA | MTE | ETE | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | |
| Text book/s* | 1.S.R. Deb and S. | Deb. "Robotics T | echnology and Flexible | | | | | | |
| | Automation", Se | | | | | | | | |
| Other | 2. Mikell P Groo | . Mikell P Groover et al., "Industrial Robotics", fifth print, McGraw | | | | | | | |
| References | Hill, Special India | n Edition, 2013 | | | | | | | |

Course Articulation Matrix

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | P07 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | _ | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | 2 | 2 |



| | ool: SET | | | | | | | | | | |
|-----|------------------|---|----------------|--|--|--|--|--|--|--|--|
| | gram: B.Tech | | | | | | | | | | |
| Bra | nch: EEE | Semester: | | | | | | | | | |
| 1 | Course Code | | | | | | | | | | |
| 2 | Course Title | Smart Power Grid and Micro-Grid | | | | | | | | | |
| 3 | Credits | 3 | | | | | | | | | |
| 4 | Contact Hours | 3-0-0 | | | | | | | | | |
| | (L-T-P) | | | | | | | | | | |
| | Course Status | | | | | | | | | | |
| 5 | Course | 1. To understand the concepts of smart power grid and micro grid | | | | | | | | | |
| - | Objective | 2. To acquire in depth knowledge of smart distribution, distribution | | | | | | | | | |
| | - J | automation, smart transmission and substation automation | | | | | | | | | |
| | | 3. To identify various components of smart grid and micro grid | | | | | | | | | |
| | | | | | | | | | | | |
| | | 4. To apply principles of automation to transmission and distribution | | | | | | | | | |
| | | 5. To design smart micro grid for a given application | | | | | | | | | |
| 6 | Course | CO1: To understand concept, motivation and benefits of Smart Power Grid | | | | | | | | | |
| | Outcomes | CO2: To develop knowledge of demand-side management as a tool of | | | | | | | | | |
| | | smart distribution | | | | | | | | | |
| | | CO3: to design advanced metering infrastructure for Distribu | tion | | | | | | | | |
| | | Automation | | | | | | | | | |
| | | CO4: To design AC, DC and hybrid micro grids | | | | | | | | | |
| | | CO5: To design phasor measurement and develop wide area | monitoring | | | | | | | | |
| | | system using PMU | | | | | | | | | |
| | | CO6: Industrial experiences in renewable energy integration in distribution | | | | | | | | | |
| | | system | | | | | | | | | |
| 7 | Course | The course deals with the concept of smart power grid an | d includes inv | | | | | | | | |
| | Description | depth study of its its various components, namely smar | | | | | | | | | |
| | 1 | distribution automation and management, advanced metering | | | | | | | | | |
| | | , smart micro grid, smart transmission and substation automa | | | | | | | | | |
| 8 | Outline syllabu | | CO Mapping | | | | | | | | |
| | Unit 1 | Introduction to Smart Power Grid (4 hours) | | | | | | | | | |
| | А | Traditional power grid, Smart power grid (or smart grid) concept and objectives | CO1 | | | | | | | | |
| | В | Benefits of smart power grid, traditional-grid and smart- | CO1 | | | | | | | | |
| | | grid comparison | | | | | | | | | |
| | С | Stake-holders in smart-grid development, Smart grid solutions. | CO1 | | | | | | | | |
| | Unit 2 | Smart Distribution | | | | | | | | | |
| | A | Demand-side management: Energy efficiency, time of use and spinning reserve | CO2 | | | | | | | | |
| | В | Demand response: Market driven DR and operation-driven DR, incentive-based DR and TOU-based rates DR | CO2 | | | | | | | | |





| С | Distributed ge | neration, Ener | gy storage, Use of plugged | CO2 | | | | |
|---------------------|--|---|--|---------|--|--|--|--|
| | | brid electric ve | | | | | | |
| Unit 3 | Distribution | Automation ar | nd Management | | | | | |
| A | customer autor | mation, feeder | eem, Components of DA: automation and substation trol centre (DCC) | CO3 | | | | |
| В | Distribution management system (DMS), Outage management system (OMS)- unplanned and planned outages, Asset management system (AMS), Customer information system (CIS) | | | | | | | |
| С | C Meaning and benefits of advanced metering, Structure and components of AMI, AMI integration with DA, DMS and OMS. | | | | | | | |
| Unit 4 | Smart Micros | | | | | | | |
| А | Definition, con | CO4,CO6 | | | | | | |
| В | | | and hybrid, Modes of disland modes | CO4,CO6 | | | | |
| С | Meaning of sn control | nart micro grid | , Micro grid operation and | CO4,CO6 | | | | |
| Unit 5 | Smart Transı | nission and Su | ubstation Automation | | | | | |
| А | Meaning and o | challenges of si | nart transmission | CO5,CO6 | | | | |
| В | | Vide area moni | ncept, layout, components and toring system: concept and | CO5,CO6 | | | | |
| С | | ation automatio | n (SA), Technical issues of ction. | CO5,CO6 | | | | |
| Mode of examination | Theory | | | | | | | |
| Weightage | CA | | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | |
| Text book/s* | | 1. Mini S. Thomas and John D. McDonald, Power System SCADA and Smart Grids, CRC Press, | | | | | | |



| | 🥆 🌽 B e | eyond Boundari |
|------------|--|----------------|
| Other | 1. Janak Eknayake at el., Smart Grid: Technology and | |
| References | Applications, John Wiley and Sons, 2012 | |
| | 2. H. K. Verma, e-Monograph on "Smart – Grid", | |
| | www.profhkverma.info | |
| | | |

| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO.1 | 3 | 2 | 2 | 1 | - | - | _ | _ | - | - | - | - | 2 | 1 | 2 |
| CO.2 | 3 | 1 | 2 | 2 | - | - | - | - | - | - | - | - | - | - | 2 |
| CO.3 | 3 | 2 | 2 | 2 | - | - | - | - | - | - | - | - | 2 | 3 | 2 |
| CO.4 | 3 | 1 | 2 | 2 | - | - | - | - | - | _ | - | - | 2 | - | 2 |
| CO.5 | 1 | 2 | 2 | 1 | - | - | - | - | - | | - | - | 3 | 2 | 2 |
| CO.6 | 3 | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | - |



| | ool: | School of Engineering and Technology |
|-----|---------------------|---|
| Pro | gram: | |
| Bra | unch: EEE | |
| 1 | Course Code | |
| 2 | Course Title | Virtual Instrumentation |
| 3 | Credits | 3 |
| 4 | Contact | 3-0-0 |
| | Hours | |
| | (L-T-P) | |
| | Course | |
| | Status | |
| 5 | Course Objective | Introduction to the various models of Virtual Instruments, their comparison with traditional instruments and major application areas of VI. Introduction to basics of LabVIEW VI Programming techniques like loops, arrays, clusters, plotting and Strings and files. Basics of signal conditioning techniques along with DAQ hardware and software and various signal processing techniques available in LABVIEW. Advanced concepts in LabVIEW with main concepts of real time applications in Image acquisition and Motion control. Building of Virtual Instruments with various types of controls and indicators. Configuring DAQ card and acquisition of real time signals from sources and sensors. Simulate a signal in LabVIEW and generate a virtual source using DAQ cards. |
| 6 | Course Outcomes | CO1: Understand various models and areas of application of Virtual Instrumentation. CO2: Understand various components of LabVIEW required for the development of VI. CO3: Understand and apply various programming functions of LabVIEW like loops, arrays, clusters and file I/Os for building of simple Virtual instruments. CO4: Understand the concepts of Data acquisition hardware and software and to apply basic signal processing techniques available in LabVIEW. CO5: Understand the real time applications of LabVIEW in motion control and Image acquisition. |
| 7 | Course | CO6: Able to build VI for simulated and real time applications. |
| 1 | Description | The course content of this subject includes an introduction to graphical |
| | | |



| | | | Beyond Bounda | | | | | | |
|---|---------------------|--|----------------|--|--|--|--|--|--|
| | | to LabVIEW g language .In ttc. have been n this course. ques are also on control and orated in this | | | | | | | |
| 8 | Outline syllabus | | | | | | | | |
| | Unit 1 | Introduction | Mapping CO1 | | | | | | |
| | A | Graphical system design model - design model, prototype model, deployment model | | | | | | | |
| | В | Building blocks of VI; Virtual instrument versus traditional instrument, Hardware and software in VI | | | | | | | |
| | С | Graphical system Design using LabVIEW; Graphical programming and Textual programming | | | | | | | |
| | Unit 2 | Graphical system Design using LabVIEW | CO2,CO6 | | | | | | |
| | A | Advantages of LabVIEW; Components of VI Software - Front panel windows, Block diagram windows, Icon /connector pane | | | | | | | |
| | В | Creating and saving a VI; Toolbars, Palettes, Front panel controls and indicators, Block diagram – terminals, nodes, functions | | | | | | | |
| | С | Sub VIs, Express VIs and VIs, wires; Data types, Data flow program | | | | | | | |
| | Unit 3 | Programming Techniques | CO3,CO6 | | | | | | |
| | А | Modular Programming in Lab View; Building VI front panel and block diagram | | | | | | | |
| | В | Loops – for and while loops, Local and Global variables in LabVIEW, Arrays in LabVIEW, | | | | | | | |
| | C | Clusters in LabVIEW; Conversion between arrays and clusters, Plotting data in LabVIEW, Strings and File I/O in LabVIEW | | | | | | | |
| | Unit 4 | Data Acquisition and Signal Processing in LabVIEW | CO4,CO6 | | | | | | |
| | А | Transducers and Signal conditioning ,sampling and aliasing | | | | | | | |
| | В | Basics of DAQ hardware and software, DAQ modules and drivers for building virtual instruments | | | | | | | |
| | C | Fourier transforms; Power spectrum, Correlation methods; Windowing & filtering | | | | | | | |
| | Unit 5 | Advanced concepts in LabVIEW | CO5, CO6 | | | | | | |
| | Α | Data Socket, TCP/IP VI's synchronization | | | | | | | |
| | В | Serial interface buses - RS 232, RS485,USB | | | | | | | |
| | С | Concepts of real time systems; Image acquisition; Motion control | | | | | | | |
| | Mode of examination | Theory/Jury/Practical/Viva | | | | | | | |



| | | | | 🥆 🥟 Beyond Bounda | | | | | | | |
|---------------------|-------------------------------|--|-----|-------------------|--|--|--|--|--|--|--|
| Weightage | CA | MTE | ETE | | | | | | | | |
| Distribution | 30% | 20% | 50% | | | | | | | | |
| Text book/s* | | 1. Jovitha Jerome, "Virtual Instrumentation and LABVIEW", PHI Learning | | | | | | | | | |
| Other References | 1. C.L. Clar TMH Publishir | ıg", | | | | | | | | | |
| | 2. Techn and Na | ntech | | | | | | | | | |
| | 3. <u>www.p</u> Protoce | gies/ | | | | | | | | | |
| | 4. NI USI http://v | | | | | | | | | | |
| | 5. www.n | | | | | | | | | | |

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO 008.1 | 1 | 2 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 2 | - | 2 | 2 | 2 | 1 |
| CO008.2 | 3 | 2 | 1 | 2 | 3 | 1 | 2 | 2 | 1 | 1 | - | 2 | 2 | 2 | 2 |
| CO008.3 | 3 | 2 | 3 | 2 | 3 | 2 | 2 | 2 | 1 | 2 | - | 2 | 2 | 2 | 2 |
| CO008.4 | 2 | 2 | 2 | 2 | 1 | 2 | 2 | 2 | 2 | 2 | - | 3 | 3 | 2 | 2 |
| CO008.5 | 2 | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | - | 3 | 3 | 2 | 2 |
| CO008.6 | 2 | 3 | 3 | 2 | 3 | 2 | 2 | 2 | 2 | 3 | 2 | 3 | 3 | 2 | 3 |



| Sch | ool: SET | | 🥟 Beyond Boundari |
|-----|------------------|---|-------------------|
| Pro | gram: B.Tech | | |
| | nch:EEE | Semester: | |
| 1 | Course Code | | |
| 2 | Course Title | Virtual Instrumentation Lab | |
| 3 | Credits | 2 | |
| 4 | Contact Hours | 0-0-4 | |
| | (L-T-P) | | |
| | Course Status | Compulsory/Elective | |
| 5 | Course | • To understand the basic concepts of Lab VIEW. | |
| | Objective | • To build VI using Lab VIEW. | |
| | | • To acquire data using data acquisition card. | |
| | | • To build real time applications using Lab VIEW. | |
| 6 | Course | CO1: To implement simple arithmetic and Boolean systems | s using Lab |
| | Outcomes | VIEW. | - |
| | | CO2: To create VI using arrays. | |
| | | CO3: To build VI using clusters operations of LabVIEW. | |
| | | CO4: To acquire and generate a signal using DAQ cards. | |
| | | CO5: To develop real time application of a VI. | |
| 7 | Course | CO6: Able to build VI for simulated and real time application | ons. |
| | | the Lab VIEW platform for the designing of VI. This cours the use of loops, arrays, clusters and various programming Lab VIEW for building the Virtual instruments. | |
| 8 | Outline syllabus | | CO Mapping |
| 0 | Unit 2 | Practical related to | CO1 |
| | | 1. To study various types of Boolean controls and | |
| | | Indicators. Also study various Boolean programming | |
| | | functions available in function palate. | |
| | | 2. Create a VI to compute the Boolean expression (A*B) | |
| | | +(C*D*E). | |
| | | 3. Create a front panel and block diagram to implement | |
| | | half ladder and full adder. | |
| | | 4. To study various types of numeric controls and | |
| | | indicators and numeric programming functions available | |
| | | in function palate. | |
| | | 5. Create the front panel and block diagram of VI to show | |
| | | the trigonometric values Of sine and cosine of a given | |
| | Unit 3 | angle in degrees. Practical related to | CO2 |
| | | 6. Create a VI to create 2D numeric arrays & add them. | |
| | | 7. Create a VI consisting of two clusters of LEDs Perform | |
| | | the AND operation between the clusters and display the | |
| | 1 | and raise operation between the elusions and display the | |

| | · · · | <i>(</i> 1 1 <i>i</i> | | k. | Beyond | | | |
|---------------------|--|--|---|---|--------|--|--|--|
| | | 'I using clus e, age, statu | s of LEDs. ster to display in is, marks. Use B | | | | | |
| Unit 4 | Practical rel | lated to | | | CO4 | | | |
| | volts in steps using a DAQ 10. Create a using USB60 | s of 0.5 volt card. VI to acqui: 008. Also ex | e voltage output s. View the sam re an analog sign stract the inform meters and frequ | e on the CRO nal from a source ation related to | | | | |
| Unit 5 | Practical rel | | CO5 | | | | | |
| | temperature 12. Design a 13. Design a | Create a VI to acquire an analog signal of LM35 temperature sensor on a DAQ signal accessory Design a Virtual Resistance Meter. Design a Virtual Sinusoidal Voltage Source. Design a Virtual CRO. | | | | | | |
| Mode of examination | Jury/Practica | | | | | | | |
| Weightage | СА | MTE | ETE | | | | | |
| Distribution | 60% | 0% | 40% | | | | | |
| Text book/s* | 1.Jovitha Jerome, "Virtual Instrumentation and LABVIEW", PHI Learning | | | | | | | |
| Other References | 2. Technical Manuals for DAQ Modules, Advantech and National Instruments | | | | | | | |
| | | ER MANUAL | m/pdf/manuals/3 | 76445b.pdf | | | | |

| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO 008.1 | 1 | 2 | 2 | 2 | 2 | 1 | 1 | 2 | 1 | 2 | - | 2 | 2 | 2 | 1 |
| CO008.2 | 3 | 2 | 1 | 2 | 3 | 1 | 2 | 2 | 1 | 1 | - | 2 | 2 | 2 | 2 |
| CO008.3 | 3 | 2 | 3 | 2 | 3 | 2 | 2 | 2 | 1 | 2 | - | 2 | 2 | 2 | 2 |
| CO008.4 | 2 | 2 | 2 | 2 | 1 | 2 | 2 | 2 | 2 | 2 | - | 3 | 3 | 2 | 2 |
| CO008.5 | 2 | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | - | 3 | 3 | 2 | 2 |
| CO008.6 | 2 | 3 | 3 | 2 | 3 | 2 | 2 | 2 | 2 | 3 | 2 | 3 | 3 | 2 | 3 |