Program and Course Structure

Department of Electrical Electronics and Communication Engineering

B.Tech. Electrical and Electronics Engineering SET0404

2019



1. Standard Structure of the Program at University Level

1.1 Vision, Mission and Core Values of the University

Vision of the University

To serve the society by being a global University of higher learning in pursuit of academic excellence, innovation and nurturing entrepreneurship.

Mission of the University

- 1. Transformative educational experience
- 2. Enrichment by educational initiatives that encourage global outlook
- 3. Develop research, support disruptive innovations and accelerate entrepreneurship

Core Values

4. Seeking beyond boundaries

- Integrity
- Leadership
- Diversity
- Community



1.2 Vision and Mission of the School

Vision of the School

To become a globally acclaimed institution of higher learning in engineering and technology promoting excellence in research, innovation and entrepreneurship

Mission of the School

- 1. To impart quality education with strong industry & academic connectivity in the expanding fields of Engineering and Technology in a conductive and enriching learning environment.
- 2. To product technocrats equipped with technical & soft skills and experiential learning required to stay current with the modern tools in emerging technologies to fulfill professional responsibilities and uphold ethical values.
- 3. To inculcate a culture of interdisciplinary research, innovation and entrepreneurship to provide sustainable solutions to meet the growing challenges and societal needs.
- 4. To foster collaborative learning and to play adaptive leadership role in professional career and pursuit of higher education through effective mentoring and counseling.



1.2.1 Vision and Mission of the Department

Vision of the Department of Electrical and Electronics Engineering

To become an internationally acclaimed destination of academic excellence in the discipline of Electrical, Electronics, and Communication Engineering by promoting research, innovation, and entrepreneurship to serve society.

Mission of the Department Electrical and Electronics Engineering

M1-To provide comprehensive technical knowledge in Electrical, Electronics and Communication Engineering.

M2- To facilitate and foster the industry-academia collaboration to enhance technical skills and employability.

M3- To promote interdisciplinary and multi-disciplinary research, innovations and entrepreneurship to serve society.

M4- To develop core values, professional ethics and lifelong learning skills through interactive support systems.



1.3 Programme Educational Objectives (PEO)

1.3.1 Writing Programme Educational Objectives (PEO)

The Educational Objectives of UG Program in Electrical and Electronics Engineering are:

PEO1: The graduates will achieve a reputation as a source of providing innovative solutions for complex engineering problems.

PEO2: The graduates will demonstrate sound engineering knowledge and managerial decisions based on ethical and professional standards.

PEO3: The graduates will work on global technological and environmental issues as a successful entrepreneur.

PEO4: The graduates will pursue higher studies to become successful academicians and lead researchers.



1.3.2 Map PEOs with School Mission Statements:

No.	PEO statement	School missions			
		Mission statement	Mission statement	Mission	Mission
		1	2	statement 3	statement 4
1	The graduates will	3	2	2	3
	achieve a reputation				
	as a source of				
	providing innovative				
	solutions for complex				
	engineering problems.				
2	PEO2: The graduates	2	3	3	2
	will demonstrate				
	sound engineering				
	knowledge and				
	managerial decisions				
	based on ethical and				
	professional				
	standards.				
3	PEO3: The graduates	2	3	2	3
	will work on global				
	technological and				
	environmental issues				
	as a successful				
	entrepreneur.				
4	PEO4: The graduates	2	3	2	2
	will pursue higher				
	studies to become				
	successful				
	academicians and lead				
	researchers.				



1.3.2.1 Map PEOs with Department Mission Statements:

PEOs MISSION STATEMENTS	PEO1: The graduates will achieve a reputation as a source of providing innovative solutions for complex engineering problems.	PEO2: The graduates will demonstrate sound engineering knowledge and managerial decisions based on ethical and professional standards.	PEO3: The graduates will work on global technological and environmental issues as a successful entrepreneur.	PEO4: The graduates will pursue higher studies to become successful academicians and lead researchers.	
M1- To provide comprehensive technical knowledge in Electrical, Electronics, and Communication Engineering	3	3	3	3	12/12
M2- To facilitate and foster the industry-academia collaboration to enhance technical skills and employability.	3	3	3	3	12/12
M3- To promote interdisciplinary and multi- disciplinary research, innovations, and entrepreneurship to serve society.	3	2	3	3	11/12
M4-To develop core values, professional ethics, and lifelong learning skills through interactive support systems	2	3	2	3	10/12
	11/12	11/12	11/12	12/12	93.75%



1. Slight (Low)2. Moderate (Medium)3. Substantial (High)1.3.3 Program Outcomes (PO's)

- PO1: **Engineering knowledge**: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
- PO2: **Problem analysis**: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- PO3: **Design/development of solutions**: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
- PO4: **Conduct investigations of complex problems**: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- PO5: **Modern tool usage**: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.
- PO6: **The engineer and society**: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
- PO7: **Environment and sustainability**: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
- PO8: **Ethics**: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- PO9: **Individual and team work**: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
- PO10: **Communication**: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.



- PO11: **Project management and finance**: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
- PO12: Life-long learning: Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

1.3.4 Program Specific Outcomes (PSO's)

PSO 1: An ability to apply hardware and software based embedded smart solutions for industrial automation and power system

PSO 2: Accentuate the application of cutting-edge technology on renewable energy systems and smart grid

PSO 3: To utilize the knowledge of power systems, automation, robotics and sustainable technology in multidisciplinary research

Mapping	PEO1	PEO2	PEO3	PEO4
PO1	2	2	1	1
PO2	1	3	1	1
PO3	3	3	2	2
PO4	3	2	2	1
PO5	2	3	1	-
PO6	1	2	3	3
PO7	2	1	1	3
PO8	1	1	3	2
PO9	2	1	3	1
PO10	1	1	2	3
PO11	2	2	3	1
PO12	1	2	2	-
PSO1	3	1	1	2

1.3.5 Mapping of Program Outcome Vs Program Educational Objectives

				SHARDA UNIVERSITY
PSO2	2	1	1	1
PSO3	2	1	1	2

1. Slight (Low)

2. Moderate (Medium) 3.

Substantial

(High)



1.3.6 The components of the curriculum

Course Component	Curriculum Content (% of total number of credits of the program)	Total number of contact hours	Total number of credits		
Basic Sciences	16.25	33	26		
Engineering Sciences	8.125	20	13		
Humanities and Social	11.25	29	18		
Program Core	35	72	56		
Program Electives	11.25	18	18		
Open Electives	6.25	10	10		
Project(s)	11.875	40	19		
272					



Course Structure

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: I

S.	Course Code	Course	Te	eaching	Load		Pre-Requisite/Co			
No.			L	Т	Р	Credits	Requisite			
THEO	THEORY SUBJECTS									
1.	CSE113	Programming for Problem Solving	3	0	0	3				
2.	HMM126	Human Values and Ethics	2	0	0	2				
3.	MTH141	Mathematics I	3	1	0	4				
4.	PHY117	Engineering Physics (Semiconductor Physics)	3	1	0	3				
5.	CHY111	Engineering Chemistry	2	1	0	3				
Practio	cal/Viva-Voce/Jury									
6.	ARP101	Comm. Eng-I	0	0	2	2				
7.	CSP113	Programming for Problem Solving	0	0	2	1				
8.	MEP106	Computer Aided Design & Drafting	0	0	3	1.5				
9.	ECP106	Introduction to Engineering	0	0	2	1				
10.	PHY162	Physics Lab II	0	0	2	1				
11.	CHY161	Engineering Chemistry lab	0	0	2	1				
		22.5								

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: II

S.	Paper ID	Course Code	Course	Teaching Load				Pre-Requisite/Co
No.				L	Т	Р	Credits	Requisite
ГНЕО	RY SUBJEC	TS						1
1.		CSE114	Application based Programming in Python	3	0	0	3	
2.		MTH143	Differential Equations, Spec.Transforms and complex variable	3	1	0	4	
3.		PHY118	Advanced Physics (Electricity and Magnetism)	2	1	0	3	
4.		EEE112	Principles of Electrical and Electronics Engineering	3	0	0	3	
5.		EVS112	Environmental Science	2	0	0	2	
6.		ARP102	Comm. Eng II	1	0	2	2	
Practio	cal/Viva-Voc	e/Jury	·				·	
7.		CSP114	Application based Programming in Python	0	0	2	1	
8.		MEP105	Mechanical Workshop	0	0	3	1.5	
9.		ECP107	Tinkering Lab Electrical	0	0	2	1	
10.		PHY161	Physics Lab	0	0	2	1	
11.		EEP112	Principles of Electrical and Electronics Engineering lab	0	0	2	1	
12.								
	1	1	TOTAL CREDITS			1	22.5	l
		Note: Indu	strial Internship after completion of 2 nd Semester	and will	be evalu	ated in 3 rd	Semester	1

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: III

S.	Course	Course	Т	eaching	Load		Pre-Requisite/Co			
No.	Code		L	Т	Р	Credits	Requisite			
THEO	THEORY SUBJECTS									
1.	HMM305	Management for Engineers	3	0	0	3				
2.	MTH145	Mathematics III (Probability & Statistics)	3	0	0	3				
3.	ECE237	Analog Circuits-I	3	0	0	3				
4.	EEE220	Network Analysis & Synthesis	3	0	0	3				
5.	EEE221	Electrical Machine-I	3	0	0	3				
Practic	al/Viva-Voce/J	ury								
6.	ARP203	Aptitude Reasoning and Business Communication Skills-Basic	0	0	4	2				
7.	MTP145	Mathematics III (Using MATLAB/ Sci Lab)	0	0	2	1				
8.	ECP237	Analog Electronics -1 Lab	0	0	2	1				
9.	EEP221	Electrical Machine-I Lab	0	0	2	1				
10.	EEP251	Project Based Learning (PBL) -1	0	0	2	1				
11.	EEP294	Summer Internship	0	0	2	1				
	TOTAL CREDITS 22									

School of Engineering and Technology B.Tech-Electrical and Electronics Engineering Batch: 2019-2023 TERM: IV

S.	Course	Course	Teach	ing Lo	ad		Pre-Requisite/Co
No.	Code		L	Т	Р	Credits	Requisite
THEORY	SUBJECTS	<u> </u>			<u> </u>		
1.	EEE224	Electrical Macines-II	3	0	0	3	
2.	ECE240	Digital System Design	3	0	0	3	
3.	EEE225	Electrical & Electronic Measurements	3	0	0	3	
4.	ECE245	Microprocessor and Microcontroller with Interfacing	3	0	0	3	
5.	BTY 223	Introduction to Biology for Engineers	2	0	0	2	
6.	MOO211	Wheeled Mobile Robots	2	0	0	2	
Practical/	Viva-Voce/J	ury					
7.	EEP226	Project Based Learning (PBL) -2	0	0	2	1	
8.	EEP224	Electrical Macines-II Lab	0	0	2	1	
9.	ECP240	Digital System Design Lab	0	0	2	1	
10.	EEP225	Electrical & Electronic Measurements Lab	0	0	2	1	
11.	ECP245	Microprocessor and Microcontroller with Interfacing Lab	0	0	2	1	
12.	ARP204	Aptitude Reasoning and Business Communication Skills-Intermediate	0	0	4	2	
			TOTAL	CREI	DITS	23	

School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: V

S.	Course Code	Course	Teaching Load				Pre-	
No.			L	Т	Р	Credits	Requisite/Co Requisite	
Theor	y Subjects		1	1	1	1		
1.	EEE330	Control Systems	3	0	0	3		
2.	EEE331	Power System-I	3	0	0	3		
3.	EEE332	Power Electronics	3	0	0	3		
4.	EEE452	Wind and Solor Energy	3	0	0	3		
5.	ECE932/BTY320/ MEC333/MEC319	IoT in smart application/Microbiology /Industry 4.0/Energy Conservation and Management	3	0	0	3		
Pract	ical/Viva-Voce							
6.	EEP321	Control Systems Lab	0	0	2	1		
7.	EEP331	Power System-I Lab	0	0	2	1		
8	EEP332	Power Electronics Lab	0	0	2	1		
9.	EEP337	Technical Skill Enhancement Course-1	0	0	2	1		
10.	EEP333	Project Based Learning (PBL) -3	0	0	2	1		
11.	ARP301	Quantitative Aptitude Behavioral and Interpersonal Skills	0	0	4	2		
12.	EEP391	Summer Internship	0	0	2	1		
13.	ECC301	Community Connect	0	0	4	2		
		·	TOT	AL CRI	EDITS	25		



School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: VI

S.	Course	Course	Te	eaching	Load		Pre-Requisite/Co				
No.	Code		L	Т	P	Credits	Requisite				
THEO	THEORY SUBJECTS										
1.	EEE334	Switchgear & Protection	3	0	0	3					
2.	EEE335	Power System-II	3	0	0	3					
3.	EEE442	Embedded System and Robotics	3	0	0	3					
4.	EEE463	Optimization Techniques	3	0	0	3					
5.	MOO307	Computer vision and Image processing- Fundamentals and Application	3	0	0	3					
Practi	cal/Viva-Voce	Jury									
6.	ARP302	Higher Order Mathematics and Advanced People Skills	0	0	4	2					
7.	EEP334	Switchgear & Protection Lab	0	0	2	1					
8.	EEP335	Power System-II Lab	0	0	2	1					
9.	EEP336	Project Based Learning (PBL) -4	0	0	2	1					
10.	EEP339	Technical Skill Enhancement Course-2	0	0	2	1					
	TOTAL CREDITS 21										



School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: VII

S.	Course	Course	Т	eaching	Load		Pre-Requisite/Co			
No.	Code		L	Т	Р	Credits	Requisite			
THEO	THEORY SUBJECTS									
1.	EEE444	HVDC and Facts	3	0	0	3				
2.	EEE448	PLC and SCADA	3	0	0	3				
3.	EEE453	Wireless Sensor Networks and Applications	3	0	0	3				
4.	MOO402	Introduction to Smart Grid	2	0	0	2				
Practi	cal/Viva-Voc	e/Jury								
6.	EEP430	Major Project- 1	0	0	6	3				
7.	SC22	Comprehensive Examination	0	0	0	0				
9.	EEE431	Industrial Internship	0	0	2	1				
10.	ARP401	Problem Solving Creative Thinking and Leadership Skills	0	0	2	1				
		16								



School of Engineering and Technology B.Tech. Electrical and Electronics Engineering Batch: 2019-2023 TERM: VIII

S.	Course	Course	T	eaching	Load		Pre-Requisite/Co
No.	Code		L	Т	Р	Credits	Requisite
1.	EEP495	Major Project – 2	0	0	16	8	
	•	•	TO	TAL CR	EDITS	8	



SYLLABUS TERM-I



Programming for problem solving

Sc	hool: SET			
Pr	ogram: B.Tech			
Br	ranch: ECE			
Se	mester:1			
1	Course Code	CSE113	Course Name: Programming for problem solving	
2	Course Title	Programmi	ng for problem solving	
3	Credits	4		
4	Contact Hours (L-T-P)	3-0-2		
	Course Status	Core		
5	Course Objective	str 2. lea	earn basic programming constructs –data types ructures, control structures in C arning logic aptitude programming in c langu eveloping software in c programming	
6	Course Outcomes	CO1: the giv CO2: progra CO3: CO4: strings CO5: CO6: C.	pletion of Course Students will be able to: demonstrate the algorithm, Pseudo-code and to ven problem. develop better understanding of basic concept amming. create and implement logic using array and fu construct and implement the logic based on the s and pointers. apply user-defined data types and I/O operation design and develop solutions to real world pro-	ts of C Inction. The concept of The cons in file. The boblems using
7	Course Description		ng for problem solving gives the Understanding of C p code from flowchart or algorithm	rogramming and
8	Outline syllabus			CO Mapping
	Unit 1	Logic Bui	lding	
	А	output, Bra	Elements, Identifying and understanding input anching and iteration in flowchart	CO1,
	В	Algorithm down/botto	design: Problem solving approach(top om up approach)	CO1
	С		ode : Representation of different construct, seudo-code from algorithm and flowchart	CO1
	Unit 2	Introducti	ion to C Programming	
	A		on to C programming language, Data types, Constants, Identifiers and keywords, Storage	CO2
	В	Assignmer	and expressions, Types of Statements: nt, Control, jumping.	CO2
	С	Control sta	atements: Decisions, Loops, break, continue	CO2
	Unit 3	Arrays an	d Functions	
	А		ne dimensional and multi dimensional arrays: n, Initialization and array manipulation (sorting,	CO3
	В	Functions:	Definition, Declaration/Prototyping and	CO3



 	S 2 B e	yond Boundaries
	Calling, Types of functions, Parameter passing: Call by value, Call by reference.	
С	Passing and Returning Arrays from Functions, Recursive Functions.	CO3
 Unit 4	Pre-processors and Pointers	
A	Pre-processors: Types, Directives, Pre-processors Operators (#,##,\) , Macros: Types, Use, predefined Macros	CO4, CO6
В	Pointer: Introduction, declaration of pointer variables, Operations on pointers: Pointer arithmetic, Arrays and pointers, Dynamic memory allocation.	CO4 , CO6
С	String: Introduction, predefined string functions, Manipulation of text data, Command Line Arguments.	CO4, CO6
Unit 5	User Defined Data Types and File Handling	
A	Structure and Unions: Introduction, Declaration, Difference, Application, Nested structure, self-referential structure, Array of structures, Passing structure in function.	CO5, CO6
В	Files: Introduction, concept of record, I/O Streaming and Buffering, Types of Files: Indexed file, sequential file and random file,	CO5, CO6
С	Creating a data file, Opening and closing a data file, Various I/O operations on data files: Storing data or records in file, adding records, Retrieving, and updating Sequential file/random file.	CO5, CO6
Mode of examination	Theory	
Weightage	CA MTE ETE	
Distribution	30% 20% 50%	
Text book/s*	Kernighan, Brian, and Dennis Ritchie. The C Programming Language	
Other References	 B.S. Gottfried - Programming With C - Schaum's Outline Series - Tata McGraw Hill 3rdEdition .ISBN 9780070145900 E. Balagurusamy - Programming in ANSI C – 8thEdition - Tata McGraw Hill- 2019 	

CO, PO & PSO MAPPING:



Cos	PO1	PO2	PO3	P04	PO5	P06	PO7	PO8	909	PO1 0	PO1 1	PO1 2	PSO 1	PSO 2	PSO 3	
CSE113.1	1	2	1	-	-	1	-	-	-	-	-	-	1	1	-	
CSE113.2	2	-	2	-	-	1	-	-	-	-	1	-	2	2	-	
CSE113.3	1	-	1	-	-	-	-	-	-	-	-	-	-	1	-	
CSE113.4	1	-	1	-	-	-	-	-	-	-	-	-	-	1	-	
CSE113.5	1	-	1	-	-	-	-	-	-	-	-	-	-	1	-	
CSE113.6	2	2	2	-	-	2	-	-	-	-	1	-	2	2	1	
CSE113	1.3	2	1.3			1.3					1		1.6	1.3	1	



C -1	al Cal1 C	Beyond Boundari	ies
	ool: School of		
	c Sciences and		
	earch		
	gram: B.TECH .		
Bra		Semester: II	
	C/EC/EEE		
1	Course Code	PHY 117	
2	Course Title	Semiconductor Physics	
3	Credits	4	
4	Contact Hours (L-T-P)	3-1-0	
	Course Status	Compulsory	
5	Course Objective	To make students proverbial with the fundamental concepts of Semicond materials and their real life applications for configuring various elect devices.	
6	Course Outcomes	After the completion of this course,	
		CO1: Students will learn the various fundamental theory of material concept of solid classification.	ls and
		CO2: Students will learn the fundamental concepts of mobility, conduct electrons and holes in an intrinsic semiconductors, Donor and Acc impurities (n-type and p-type semiconductor), Fermi levels etc.	
		CO3: Students will gain knowledge about the formation of depletion rebarrier potential, Zener diode, Characteristics of Zener diode etc.	egion,
		CO4: Students will have a clear understanding of Coherent sources, inter of radiation with matter (spontaneous and stimulated emission), Eins relation, population inversion and pumping, etc.	
		CO5: Students will learn the concept of optical sources: Light emitting (construction, basic working principle), semiconductor laser (constructions basic working principle), and optical detectors.	
		CO6: Student will be familiar with the essential concepts of Semicond materials technology and their applications in industries.	uctors
7	Course Description	This course provides the basic foundation for understanding elect semiconductor devices and their applications and limitations. I introductory elements of various concept of material science. course is essential for students who desire to specialize their engine in Computer Sciences, Electronics, and Electronics and Elec- engineering.	t has This ering
8	Outline Syllabu		CO oping
	Unit 1	Physics of Semiconductor	1 0



	Beyond Bo	undaries
A	Introduction, classical free electron theory (Lorentz-Drude theory and limitations), Quantum theory of free electron	CO1, CO6
В	(Fermi energy, effect of temperature on Fermi-Dirac distribution) (qualitative analysis)	CO1
С	Energy bands, Classification of Solids on the basis of energy band.	CO1
Unit	2 Transport phenomena in semiconductors	
A	Mobility, conductivity, electrons and holes in an intrinsic semiconductors, Donor and Acceptor impurities (n-type and p-type semiconductor)	CO2, CO6
В	Fermi levels, carrier densities in semiconductor	CO2
С	Concentration of electrons in conduction band and holes in valence band, Drift and diffusion current, Hall effect.	CO2
Unit	3 p-n Junction	
A	p-n junction, types of p-n junction (step-graded and Linearly- graded junction)	CO3
В	formation of depletion region, barrier potential, Zener diode, Characteristics of Zener diode	CO3
С	Avalanche and Zener breakdown, comparison of Zener diode and pn junction diode, concept of tunneling, I-V characteristics of tunnel diode.	CO3, CO6
Unit	4 Laser Physics	
A	Coherent sources, interaction of radiation with matter (spontaneous and stimulated emission), Einstein's relation	CO4
В	population inversion and pumping, active components of laser, optical amplification or gain	CO4
С	threshold condition for laser action, three and four level lasers, Ruby and He-Ne lasers.	CO4
Unit	5 Optoelectronic Devices	
A	optical sources: Light emitting diode (construction, basic working principle), semiconductor laser (construction, basic working principle)	CO5
В	optical detectors: photodiode (working principle), p-i-n photodiode (working principle),	CO5, CO6



				oundaries
С	Photovoltaic effect, p-n jun	ction solar cell (basic	working idea).	CO5, CO6
Mode of Examination	Theory			
Weightage	CA	MTE	ETE	
Distribution	30%	20%	50%	
Text books	Integrated Electron Hill	nics- Millman - Halk	cias, Tata McGraw	
Other References		vices Physics and Tec s -ISBN: 978-0-470-5	<i>e.</i>	
	2. Semiconductor De	evice Fundamentals- ongman –ISBN:02015	Robert F. Pierret	

CO, PO & PSO MAPPING:

Cos	PO 1	PO	PO	PO	PO	PO	PO 7	PO	PO	PO1	PO1	PO1	PSO	PSO	PSO 2
	1	2	3	4	5	6	/	8	9	0	1	2	1	2	3
PHY117. 1	3	2	1	1	1	1	1	1	2	1	1	1	-	-	-
PHY117. 2	3	3	2	3	3	2	1	1	1	1	1	1	-	-	
PHY117. 3	3	3	2	3	3	2	1	1	1	1	1	1	-	-	-
PHY117. 4	3	3	3	2	3	2	1	1	1	1	1	1	-	-	
PHY117. 5	3	3	3	2	3	2	1	1	1	1	1	1	-	-	-
PHY117. 6	3	3	3	3	3	2	1	1	1	1	1	1	-	-	
PHY117	3	2.8	2.3	2.3	2.7	1.8	1.0	1.0	1.2	1.0	1.0	1.0	-	-	-



Sch	ool: SET	В	eyond Boundaries
Pro	gram: B.Tech.		
Bra	nch: ME, EC,	Semester: I	
EE,	, CE		
1	Course Code	MTH 141	
2	Course Title	CALCULUS, ANALYSIS AND LINEAR ALGEBRA	
3	Credits	4	
4	Contact Hours (L-T-P)	3-1-0	
	Course Status	Compulsory	
5	Course Objective	The objective of this course is to familiarize the prospect with techniques in calculus, multivariate analysis and lin aims to equip the students with standard concepts an intermediate to advanced level that will serve them tackling more advanced level of mathematics and ap they would find useful in their disciplines.	near algebra. It nd tools at an well towards
6	Course Outcomes	CO1: Explain the concept of differential calcu thecurvature and Maxima, minima and saddle point by of Lagrange. (K2,K3, K4) CO2: Explain the concept of integral calculus,desci Gamma function, calculatemultiple integration and eva volume. (K1, K2, K3, K4, K5)	using Method ibe Beta and
		CO3:Describe the concept of sequence and series;disc convergence to evaluate convergence of series. (K1, K2,	
		CO4: Discuss the basic of vector calculus; illustrate gra divergence. (K1, K3)	dient, curl and
		CO5: Describe and use the concepts line and surface into and vector, explain the Green theorem. (K1,K2,K3, K4)	egral for scalar
		CO6: Explain the basic concepts matrices and determine system of linear equation by using rank and inverse me Eigen values and Eigen vectors; Diagonalization of mat Hamilton Theorem.(K2,K 3,K4, K5)	thod, calculate
7	Course Description	This course is an introduction to the fundamental of Mat primary objective of the course is to develop the basic up of differential and integral calculus, sequence and series, calculus and linear algebra.	nderstanding
8	Outline Syllabu		CO Mapping
	Unit 1	Differential Calculus	
	A	Differentiation, Taylor's and Maclaurin's theorems with remainders; indeterminate forms and L' Hospital's rule;	CO1
	В	Limits and continuity for multivariable and Partial derivatives, Euler's theorem total derivative; Tangent plane and normal line (basic concepts);	CO1
	С	Expansion of functions of several variables, Maxima, minima and saddle points; Method of Lagrange	CO1



		manifications		S 🌽 B	eyond Boundaries
	TL	multipliers.	1. 1.		
	Unit 2	Integral Ca		1.1.	
	А	Beta and Gar	CO2		
				ble integrals (Cartesian),	
				ion in double integrals,	
	В			sian to polar), Applications:	CO2
			lumes, Center		
	С), Simple applications of	CO2
		triple integra			
	Unit 3	Sequences a			
	А		e of sequence a		CO3
	В		vergence: com	parison test, D' Alembert's	CO3
		ratio test,			
	С	· · · · · · · · · · · · · · · · · · ·	2	test; Power series.	CO3
	Unit 4	Vector Calc			
	А	Gradient, cui	rl and diverger	nce, Scalar line integrals,	CO4, CO5
	В	vector line in	ntegrals, scalar	surface integrals,	CO4, CO5
	С	vector surfac	e integrals, Th	neorems of Green's theorem.	CO4, CO5
	Unit 5	Matrices			
	А	Inverse and r	ank of a matri	ix, System of linear	CO6
		equations,		•	
	В	Symmetric, s	skew-symmetr	ric and orthogonal matrices;	CO6
		Determinant	•	C A	
	С	Eigen values	and Eigen ve	ctors; Diagonalization of	CO6
			yley - Hamilto		
	Mode of	Theory			
	examination	5			
	Weightage	CA	MTE	ETE	
	Distribution	30%	20%	50%	
	Text book/s*	1. Krey	szig, E.,	"Advanced Engineering	
		-	-	n Wiley & Sons Inc ISBN	
			-470-45836-5		
				yengar, S.R.K., "Advanced	
		Ū.	-	Mathematics", Narosa	
		Publi	cations 2007		
	Other	1. Simn	nons, G.F., "D	ifferential Equations with	
	References			pplications", Tata McGraw-	
			second editio		
				1ISBN 13: 9780070573758	
			10.001031310		
L	1	l			1



CO, PO & PSO MAPPING:

	PO	PO	РО	РО	РО	РО	РО	РО	РО	PO1	PO1	PO1	PSO	PSO	PSO
	1	2	3	4	5	6	7	8	9	0	1	2	1	2	3
MTH141.	3	3	2	2	2	1	-	-	-	1	1	1	-	-	-
1															
MTH	3	2	3	2	2	2	-	-	-	1	1	2	-	-	-
141.2															
MTH	3	2	2	2	3	1	-	-	-	2	1	1	-	-	-
141.3															
MTH	3	3	2	2	2	1	-	-	-	2	1	1	-	-	-
141.4															
MTH	3	2	2	2	2	1	-	-	-	1	1	2	-	-	-
141.5															
MTH	3	3	2	3	2	2	-	-	-	1	1	2	-	-	-
141.6															
MTH 141	3	2.5	2.2	2.1	2.2	1.3				1.3	1.0	1.5			



FEN101: FUNCTIONAL ENGLISH BEGINNER – I First Year (Odd Semester) SYLLABUS

	1		SYLLABUS		
	Course				
1	number	FEN101			
2	Course Title		nal English Beginner-1		
3	Credits	1			
	Contact				
4	Hours (L-T-P)	0-0-2			
_	Course		=	graduate stude	ents with basic understanding of English
5	Pre-requisite	languag			
		-	e students to hone the basic	communication	on skills: listening, speaking, reading and
		writing.	n students to minimize the line	wistic and soc	io-cultural barriers emerging in a different
	Course	environ	-		
6	Objective			nt accents and	standardise their existing English.
•		i o neip			patterns in pronunciation of the English
			sentences.	- 8	
			C02 : Students will be able to	understand the	e grammatical concepts and use new
			words.		
			C03 : Students will be able to		
					ragraphs and identify parts of speech.
				evaluate and i	nterpret main ideas to differentiate
_	Course		between opinions and facts.		
7	Outcomes				ect sentences and punctuation.
8	Outline syllab	us: Functio	onal English Beginner-1 (FEN103 TOPICS	s) Ref. &	Cos
			TOPICS	Chapter	Cos
	FEN101.A	UNIT A	Sentence Structure	enupter	
					co2
			Activities based on	Ref 1, Ref 2	C02
8.01	FEN101.A1	Topic1	Subject Verb Agreement		-
			Activities based on parts	Ref 1, Ref 2	
8.02	FEN101.A2	Topic2	of speech		
			Writing well-formed	Ref 1, Ref 2	
0.00	FEN101 A2	Tanial	Writing well-formed sentences	Kei I, Kei Z	
8.03	FEN101.A3	Topic3	sentences		
	FEN101.B	UNIT B	VocabularyBuilding and Pu	nctuation	
			Homonyms/	Ref 1, Ref 2	C01, C02, C06
8.04	FEN101.B1	Topic1	homophones		
0.04	TENIOI.DI	торіст	•		-
8.05	FEN101.B2	Topic2	Synonyms/Antonyms	Ref 1, Ref 2	4
8.06	FEN101.B3	Topic3	Punctuation	Ref 1, Ref 2	
		19.000		I -	1
	FEN101.C	UNIT C	ReadingComprehension	r	
8.07	FEN101.C1	Topic1	Scanning based passages	Ref 4	CO4, C05
			Skimming based	Ref 4	
			e e		
8.08	FEN101.C2	Topic2	passages		



					UNIVERSITY Beyond Boundaries					
8.00	FEN101 C2	Topic2	Comprehension and Vocabulary based exercises	Ref 4						
8.09	FEN101.C3	Topic3	exercises							
	FEN101.D		Speaking Skills							
		UNIT D	Speaking Skills							
8.10	FEN101.D1	Topic1	Presentation	Ref 1	C03					
8.11	FEN101.D2	Topic2	Extempore	4						
8.12	FEN101.D3	Topic3	Role-play of different situations							
	FEN101.E	UNIT E	Reading texts							
8.13	FEN101.E1	Topic1	The Thief by Ruskin Bond (short story)		CO4, C05					
8.14	FEN101.E2	Topic2	The Hack Driver By Sinclair Lewis (short story)							
8.15	FEN101.E3	Topic3	Texts based discussions							
0.15		TOPICS								
9	Course Evaluat	tion								
9.1	Course work:	30%								
9.2	Attendance	None								
9.3	Homework		nments, no weight							
9.4	Quizzes	-	uizzes (based on assignments);	20 marks						
9.5	Lab			20 11101 K3						
		Separat	e							
9.6	Presentations	None								
9.7	Any other	None								
9.9	MTE	One, 20%								
9.10	End-term Exam	nination: (Dne, 50%							
10	Reference Boo	ks, Videos	and Internet:							
		1.	Communication Skills by Sanja	y Kumar and I	PushpLata, OUP Publications.					
		2.		by Meenak	shi Raman and Sangeeta Sharma, OUP					
	Touthart	3.	Publications. Functional English Workbook I	Reginner I						
	Text book	 ●			ar and Composition, S.Chand& Company Ltd,					
	Poforance		New Delhi.							
	Reference Books	•	 Murphy's English Grammar with CD, Cambridge University Press. 							
м	apping of Outcome	s vs. Topi	cs							
FI	LENAME: Functiona	l English I	Beginner 1 (FEN101) 2 CO3 CO4 CO5 CO6	7						
	u = 0 = 10			1						

Outcome no. \rightarrow CO1CO2CO3CO4CO5CO6



Syllabus topic↓						
FEN101.A		Х				
FEN101.A1		Х				
FEN101.A2		Х				
FEN101.A3		Х				
FEN101.B	Х	Х				Х
FEN101.B1	Х	Х				Х
FEN101.B2	Х	Х				Х
FEN101.B3	Х	Х				Х
FEN101.C				Х	Х	
FEN101.C1				Х	Х	
FEN101.C2				Х	Х	
FEN101.C3				Х	Х	
FEN101.D			Х			
FEN101.D1			Х			
FEN101.D2			Х			
FEN101.D3			Х			
FEN101.E				Х	Х	
FEN101.E1				Х	Х	
FEN101.E2				Х	Х	
FEN101.E3				Х	Х	



Programming for problem solving lab

	nool: SET ogram: B.Tech.							
	anch: nester: I							
1	Course Code	CSP113						
2	Course Title	Programming for problem solving lab						
3	Credits	1						
4	Contact	0-0-2						
	Hours							
	(L-T-P)							
	Course Status	Compulsory						
5	Course	1. Learn basic programming constructs –data types, d	lecision					
	Objective	structures, control structures in C						
		2. learning logic aptitude programming in c language	2					
		3. Developing software in c programming						
6	Course	After Completion of Course Students will be able to:						
	Outcomes	CO1: demonstrate the algorithm, Pseudo-code and flow	w chart for the					
		given problem.	6.0					
		CO2: develop better understanding of basic concepts of C						
		programming.						
		CO3: create and implement logic using array and function.						
		CO4: construct and implement the logic based on the c	concept of					
		strings and pointers.	in filo					
		CO5: apply user-defined data types and I/O operations in file.CO6: design and develop solutions to real world problems using C.						
7	Course	Programming for problem solving gives the Understanding						
,	Description	programming and implement code from flowchart or algor						
8	Outline syllabu		CO					
Ŭ	outilité sylluoe	5U	Mapping					
	Unit 1	Logic Building						
		Draw flowchart for finding leap year	CO1					
		Write a c Program to Add Two Integers	CO1					
		Write a program to create a calculator	CO1					
	Unit 2	Introduction to C Programming						
		Write a c program to convert length meter to cm	CO2					
		Write a c program to convert temp	CO2					
		Write a c program to swap two numbers	CO2					
ı	1		1					



 			— — — — — — — — — — — — — — — — — — —	eyond Boundaries					
Unit 3	Arrays an	nd Function							
	Write a c	CO3							
	Write a c	CO3							
Unit 4	Pre-proce	essors and l	Pointers						
	Write a c	Write a c program to swap two values using pointers							
	Write a c	program	to find largest number from array	CO4, CO6					
	using poin	nters							
Unit 5	User Defi	ned Data T	ypes and File Handling						
	Write a c	program to	store information of a student using	CO5, CO6					
	structure								
	Write a c	program to	store information of a student using	CO5, CO6					
	union								
Mode of	Practical								
examination									
Weightage	CA	MTE	ETE						
Distribution	60%	0%	40%						
Text book/s*	Kernighar	n, Brian,	and Dennis Ritchie. The C						
	Programm								
Other	1. E.								
References	Tat								
	ISE								
	130								

	РО	РО	РО	РО	РО	РО	РО	РО	РО	РО	РО	РО	PSO1	PSO2	PSO3
	1	2	3	4	5	6	7	8	9	10	11	12			
CSE113.1	1	2	1	-	-	1	-	-	-	-	-	-	1	1	-
CSE113.2	2	-	2	_	-	1	-	_	-	-	1	-	2	2	_
CSE113.3	1	-	1	_	-	-	_	_	-	-	-	-	_	1	_
CSE113.4	1	-	1	-	-	-	_	-	-	-	-	-	-	1	_
CSE113.5	1	-	1	_	-	-	-	-	-	-	-	-	-	1	_
CSE113.6	2	2	2	-	-	2	-	-	-	-	1	-	2	2	1
CSE113	1.3	1	1.3	-	-	1	-	-	-	-	1	-	1	1.3	1



School: SET Program: B.Tech Branch::EEE Semester: I 1 Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours 0-0-3 (L-T-P) Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the experiment and -able or reation graving and use the software packages for drafting or computer experience is necessary.			Computer Aldeu Design & Dratung Lab	
Branch: EEE Semester: 1 1 Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours (L-T-P) O-0-3 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course Outcomes After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary.				
Semester: I Image: Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours (L-T-P) 0-0-3 (L-T-P) 5 Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing echniques and be able to replicate speci		0		
1 Course Code MEP 106 2 Course Title Computer Aided Design & Drafting Lab 3 Credits 1.5 4 Contact Hours 0-0-3 (L-T-P) Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD. CO3: Choose advance features in the engineering drawing in AutoCAD. CO4: Apply text and dimension features in the engineering drawing in AutoCAD. CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students				
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3 Credits 1.5 4 Contact Hours (L-T-P) 0-0-3 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course Outcomes After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course Description This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO Mapping List of Experiment 1 Intt				
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(L-T-P) Compulsory 5 Course Status Compulsory 5 Course Objective The objective of this introductory course is to make students familiar with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD Software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO 8 <th></th> <th></th> <th></th> <th></th>				
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8 Outline syllabus with computer-aided drafting/ design, introduce them about the basic commands, tools and dimension techniques for creation and presentation of various engineering drawing by using AutoCAD software which helps in visualization and problem solving in engineering disciplines. 6 Course After successful completion of this course the student will be able to: Outcomes 6 Course After successful completion of this course the student will be able to: CO1: Understand the fundamental features of AutoCAD workspace and user interface. CO2: Apply the fundamental tools such as draw, edit, and view for creating two dimensional engineering drawings in AutoCAD. CO3: Choose advance features to present an engineering drawing in AutoCAD CO4: Apply text and dimension features in the engineering drawing CO5: Create different orthographic projections from a pictorial view. CO6: Analyze an engineering drawing and use the software packages for drafting and modeling. 7 Course This introductory course is offered to students to make them proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing in explored. No drafting or computer experience is necessary. 8 Outline syllabus CO 8 Outline syllabus CO 8 Dutline syllabus CO 8 Outline syllabus CO 8 Dutline syllabus				
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Description proficient in design, layout, product development, and other careers that require technical drawing. Using the current version of the AutoCAD software, students will learn a variety of drawing techniques and be able to replicate specific drawings in multiple perspectives. The pinnacle of the class is to empower and enable students to create using the software provided. Career opportunities and 3-D modelling, manufacturing, and engineering will also be explored. No drafting or computer experience is necessary. 8 Outline syllabus CO Mapping List of Experiments CO Experiment 1 Introduction to AutoCAD and its interface with assignment 1 CO1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2	6		 CO1: Understand the fundamental features of AutoCAD and user interface. CO2: Apply the fundamental tools such as draw, edit, ar creating two dimensional engineering drawings in AutoCA CO3: Choose advance features to present an engineering AutoCAD CO4: Apply text and dimension features in the engineering CO5: Create different orthographic projections from a pict CO6: Analyze an engineering drawing and use the softwar 	workspace nd view for AD. drawing in g drawing orial view.
List of Experiments Mapping Experiment 1 Introduction to AutoCAD and its interface with assignment 1 CO1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2		Description	This introductory course is offered to students to r proficient in design, layout, product development, and ot that require technical drawing. Using the current vers AutoCAD software, students will learn a variety of techniques and be able to replicate specific drawings perspectives. The pinnacle of the class is to empower students to create using the software provided. Career of and 3-D modelling, manufacturing, and engineering w	her careers ion of the of drawing in multiple and enable oportunities ill also be
List of Experiments List of Experiments Introduction to AutoCAD and its interface with assignment 1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc,	8	Outline syllabus		
Experiments CO1 Experiment 1 Introduction to AutoCAD and its interface with assignment 1 Experiment 2 Working with coordinates, Drawing ofline, circle, arc,				Mapping
Experiment 1Introduction to AutoCAD and its interface with assignment 1CO1Experiment 2Working with coordinates, Drawing ofline, circle, arc,CO2				
Image: assignment 1 COI Experiment 2 Working with coordinates, Drawing ofline, circle, arc, CO2		-		
Experiment 2 Working with coordinates, Drawing ofline, circle, arc,		Experiment 1		CO1
		Experiment 2		CO2

Computer Aided Design & Drafting Lab



				nd Boundaries
	2			
Experiment 3	Editing of dra tools with ass		g editing Tools and Power	CO2
Experiment 4	Creating of a	advanced feat	ure like fillet, chamfer, hatch	CO3,
_	and using of	reusable items	with assignment 4	CO6
Experiment 5	Representing assignment 5		nensioning in AutoCADwith	CO4
Experiment 6	Creating the	drawing of the	e given assignment 6 by using	CO2,
_	AutoCAD fea	atures.		CO3
Experiment 7	Creating the AutoCAD.	drawing of	the given assignment 7 in	CO2,CO6
Experiment 8	Creating the	drawing of t	he given diagram and giving	CO2,
_	dimensions in	n AutoCAD.		CO4
Experiment 9	Creating the	drawing of Ta	jMahal in Autocad 2D	СОЗ,
				CO6
Experiment 10	Creating of o	rthographic pi	rojections from a 3D figure	CO5,
_				CO6
Mode of	Practical			
examination				
Weightage	CA	MTE	ETE	
Distribution	60%	0%	40%	
Text book/s*	1. Ibrahi	im Zaid,"CAD	/CAM- Theory and Practice", N	McGraw
	Hill, I	International E	Edition. ISBN 0-07-072857-7	
Software	AutoCAD			

$\overline{00,10}$														
COs	PO	PO	PO	PO	PO	PO	PO	PO	РО	PO1	PO1	PO1	PSO	PSO
	1	2	3	4	5	6	7	8	9	0	1	2	1	2
MEP10	2	2	2	-	3	-	-	-	-	-	-	3	3	3
6.1														
MEP	2	-	-	-	-	-	-	-	-	-	-	3	3	3
106.2														
MEP	2	-	-	-	-	-	-	-	-	-	-	3	3	3
106.3														
MEP	2	-	-	-	-	-	-	-	2	2	-	3	3	3
106.4														
MEP	2	-	-	-	-	-	-	-	2	2	-	3	3	3
106.5														
MEP	-	2	3	3	-	-	-	-	-	-	-	-	-	-
106.6														
MEP						-	-	-						
106	2	2	2.5	3	3				2	2	-	3	3	3



Sel	hool: SET		
	ogram: B.Tech		
	anch:EEE		
	mester:1		
	1	ECD100	
$\frac{1}{2}$	Course Code	ECP109	
	Course Title	Introduction to Electronics Engineering	
3	Credits	1	
4	Contact	0-0-2	
	Hours		
	(L-T-P)		
	Course	Compulsory	
~	Status		
5	Course	To be acquainted with few recent technologies in	the field of
-	Objective	Engineering.	
6	Course	After successful completion of this course the student will be able	to:
	Outcomes	CO1: Explain and classify few sensors	
		CO2: Understand the importance of AI	
		CO3: Describe the working of basic IoT system	1
		CO4: Demonstrate and Identify the components of drone and	a practice of
		indoor pilot	
		CO5: Interpret the working of basic robot	
7	Comme	CO6: Apply the concept in various hardware based applicati	ons
/	Course	This course is an active introduction to developing	a addad ta
	Description	an engineering mindset by teaching the necessary skills to be	
		your engineering toolbox. You will learn to identify opportu	
		imagine new solutions, model your creations, make decision prototypes, and showcase your ideas that impact the world.	is, build
8	Outline syllabi		СО
0	Outille syllab	13	Mapping
	Unit 1	Sensors	Mapping
	A	Different type of Sensors	CO1
	B	Application of Sensors	C01
	C	Case study	C01,C06
	Unit 2	Artificial Intelligence	01,000
	A A	What is Artificial Intelligence? History of Artificial	CO2
		Intelligence	
	В	Applications	CO2
	C	Case study	CO2,CO6
	Unit 3		
	A	Basics of IoT	CO3
	B	Applications Of IoT	CO3
	С	Case study	CO3,CO6

Introduction to Electronics Engineering



				🥿 🎾 Beyond Boundaries
Unit 4	Drone			
А	Basics	of Drone Te	echnology	CO4
В	Applica	ations		CO4,CO6
С	Practic	ing of indoo	or pilot system/Case study	CO4,CO6
Unit 5	Roboti	CS		
Α	Basics	of Robotics		CO5
В	Applica	ations		CO5,CO6
С	Case st	udy of fire b	pird robot	CO5,CO6
Mode of	Practic	al & Viva		
examination				
Weightage	CA	MTE	ETE	
Distribution	60%	0%	40%	
Text book/s*	Refer n	nanuals		
Other				
References				

CO's	P01	P02	PO3	P04	P05	P06	P07	PO8	P09	PO10	P011	P012	PS01	PSO2	PSO3
ECP106.1	3	2	2	1	1	2	-	-	-	-	-	1	2	1	2
ECP106.2	2	2	2	-	2	2	-	-	-	-	-	3	1	1	1
ECP106.3	2	1	1	1	2	1	-	-	-	-	-	2	3	1	2
ECP106.4	2	3	3	1	1	1	-	-	-	-	-	2	-	2	1
ECP106.5	3	2	2	-	-	-	-	-	-	-	-	2	-	2	1
ECP106.6	3	3	3	2	1	1	2	-	-	-	-	3	3	3	3



TERM-II

Principles of Electrical and Electronics Engineering



Sch	ool: SET	S 🖉 Beyo	nd Boundaries
Bat			
Pro	gram: B.Tech		
Bra	nch: ECE		
Sem	nester: II		
1	Course Code	EEE112	
2	Course Title	Principles of Electrical and Electronics Engineering	
3	Credits	3	
4	Contact	2-1-0	
	Hours		
	(L-T-P)		
	Course Status	Compulsory	
5	Course	To provide the students with an introductory concept in t	he field of
c .	Objective	electrical and electronics engineering to facilitate better under	
	5		engineering
		applications.	ingineering
6	Course	After completion of Course Students will be able to:	
6	Outcomes	CO1: To analyze and solve basic electrical circuits	
	Outcomes	CO3: To understand the working principle of transformer and	identify its
		applications.	identify its
		CO3: To understand the working principle of dc and ac motors	s and
		identify the starting methods of single-phase induction motor	
		CO4: To apply the basics of diode to describe the working of r	rectifier
		circuits such as half and full wave rectifiers	
		CO5: To apply the concepts of basic electronic devices to desi	gn various
		circuits	
		CO6:Apply the basic concepts in Electrical and Electronics En	gineering
7	9	for multi-disciplinary tasks	6 1 4 1 1
7	Course	This initial course introduces the concepts and fundamentals of and electronic circuits and devices. Topics include basic circuits	
	Description	and electronic circuits and devices. Topics include basic circu diode and transistor fundamentals and applications. This of	-
		introduces working principle and applications of dc/ac r	
		transformers.	notors and
8	Outline syllab		СО
	5		Mapping
	Unit 1	DC & AC Circuits (6 lectures)	
Ī	А	Electrical circuit elements (R, L and C), series and parallel	CO1
		circuits, concept of equivalent resistance, Kirchhoff current	
_		and voltage laws, star-delta conversion	
	В	Analysis of simple circuits with dc excitation and	CO1
		Superposition Theorem, Representation of sinusoidal	
		waveforms, peak and rms values, real power, reactive power,	
	~	apparent power, power factor	<u> </u>
	С	Introduction to three phase system, relationship between	CO1
	TI:4 2	phase voltages and line voltages,	
-	Unit 2	Transformer(4 lectures)	CO2
	А	Working principle and construction of transformer, EMF equation	002
		Quanon	



			Bev	ond Boundaries
В	Efficient transform	•	nsformer, Power and distribution rence between them	CO2
С	Transfor electrica		ions in transmission and distribution of	CO2
Unit		al Motors ((6 lectures)	
A		(g principle, torque-speed characteristic	СОЗ,
		lications of do		CO6
В	11		g principle and applications of a three-	CO3,
			or, significance of torque-slip	CO6
	characte		-,8	
С			arting methods and applications of	СОЗ,
		hase induction		CO6
Unit			le and Rectifier (5 lectures)	
A		tion and its b		CO4,
	i i quite	fion and its of	lusing	CO6
В	Semicor	ductor diode	, ideal versus practical diode, VI	CO4,
D		ristics of diod	-	CO4, CO6
С			ave rectifiers with and without filters.	CO4,
C	I all wa		ave rectifiers with and without filters.	CO4, CO6
Unit	5 Transis	tors (5 lectu	roc)	000
A			nsistor (BJT) –Construction, working	CO5,
А			utput characteristics	CO3, CO6
В			and as a switch	CO5,
D	DJI as (and as a switch	CO5, CO6
С	Introduc	tion to JFET		CO5,
C	introduc			CO5, CO6
Mode of	Theory			
examina	-			
Weighta		MTE	ETE	
Distribut		20%	50%	
Text boo			and I. J. Nagrath, "Basic Electrical	
1CAL 000			_	
		0 0 /	, Tata McGraw Hill, 2010- ISBN:	
		-	9781259081538	
			harya, "Basic Electrical and Electronics	
	I	Engineering",	, Pearson Publication,2011	
	I	SBN-813175	4561, 9788131754566	
	3. I	Robert L Boy	lestad, "Electronic Devices and Circuit	
		5	son Education, 2013	
		1^{th} edition	Son Education, 2015	
			2000 1000	
		SBN- 978013	30004033	
Other	1	. V.D. Tor	o. "Electrical Engineering	
Reference			ntals", Prentice Hall India, 2003	
	1	i unuamer.	10110 , 1 10111100 11011 111010, 2000	
Other	1	. V. D. Tor	o, "Electrical Engineering	
Reference			· · · · · ·	



Cos	P01	P02	PO3	P04	PO5	P06	PO7	PO8	60d	P01	P01	۲01 ۲	PSO	PSO 2	PSO 3
EEE112.1	3	3	2	2	-	-	-	-	-	-	-	-	2		1
EEE112.2	1	1	2	-	-	-	-	-	-	-	-	-	-	2	-
EEE112.3	2	2	1	-	-	-	-	-		-	-	-		1	2
EEE112.4	2	1	2	-	-	-	-	-	-	-	1	-	-	2	-
EEE112.5	3	2	1	-	-	-	-	-	-	-	1	-	1	-	1
EEE112.6	2	2	3	1	-	-	-	-	-	-	1	-	-	-	-
EEE112	2.1	1.8	1.8	1	-	-	-	-	-	-	1	-	1	1	1



Principles of Electrical and Electronics Engineering Lab

School: SET Program: B.Tech

Pro	gram: B.Tech		
	nch: EEE		
	nester: II	EED110	
1	Course Code	EEP112	
2	Course Title	Principles of Electrical and Electronics Engineering Lab	
3	Credits	1	
4	Contact Hours (L-T-P)	0-0-2	
	Course Status	Compulsory	
5	Course	To provide the students with an introductory concept in the field of e	lectrical and
	Objective	electronics engineering to facilitate better understanding of the devices, tea equipment's used in engineering applications.	chniques and
6	Course	After successful completion of this course the student will be able to:	
Ũ	Outcomes	CO1: To configure and analyze any given circuit.	
		CO2: To inspect the working of transformer and calculate its efficiency	
		CO3: To understand the working of dc and ac motors and measure its vario	us operating
		parameters.	
		CO4: To design rectifier circuits such as half and full wave rectifiers and of	bserve its
		output waveforms.	
		CO5: To obtain the characteristics of BJT.	
		CO6: Apply the basic concepts in Electrical and Electronics Engineering fo	r multi-
		disciplinary tasks.	
7	Course	This initial course introduces the concepts and fundamentals of electrical a	
	Description	circuits and devices. Topics include basic circuit analysis, diode an	
		fundamentals and applications. This course also introduces working p	rinciple and
		applications of dc/ac motors and transformers.	
8	Outline syllabus		CO
			Mapping
	Unit 1	Practical based on DC & AC Circuits	CO1
		To configure a dc circuit on breadboard, and measure voltage/current	CO1
		across/through each element	001
		To verify Kirchhoff's Laws	CO1
		To verify Superposition Theorem	CO1
		To find the real power, reactive power, apparent power and power factor	C01
		of RL & RC load	COI
	Unit 2	Practical related to Transformers	
		To find the efficiency of transformer by obtaining its losses.	CO2,
			CO6
	Unit 3	Practical related to Electrical Motors	000
	Olift 5		002
			CO3,
		To study cut-section of DC motor and induction motor.	CO6
			CO3,
		To start the DC motor and reverse its direction of rotation.	CO6
			CO3,
			CO3, CO6
	TT 14 4	To start an induction motor and reverse its direction of rotation.	000
	Unit 4	Practical related to Diode and Rectifier	
			CO4,
		To determine voltage-current characteristic of diode	CO6
		To assemble and test half wave and full wave rectifier circuits for their	CO4,
		input and output waveform	CO6
	Unit 5		
	Unit 5	Practical related to Transistors	



			Beyon	d Boundaries
				CO5,
	To determin	e input and ou	tput characteristics of BJT	CO6
				CO5,
	Validation of	of BJT as a sw	itch	CO6
Mode of examination	Practical			
Weightage	CA	MTE	ETE	
Distribution	60%	0%	40%	
Text book/s*	McGraw Hi 2. S. K. B Pearson Put	ll, 2010-ISBN hattacharya, "I blication.ISBN: Boylestad, "E 2009	 Nagrath, "Basic Electrical Engineering", Tata 9780070146112 Basic Electrical and Electronics Engineering", 9789332586505 lectronic Devices and Circuit Theory" Pearson 	
Other References	На	D. Toro, "Elec ll India, 1989. N:978013247		

Cos															
	P01	P02	P03	P04	P05	P06	P07	P08	P09	P010	P011	P012	PS01	PSO2	PSO3
EEP112.1	3	3	3	1	1	-	-	-	-	-	-	-	2	-	-
EEP112.2	2	2	2	-	-	-	-	-	-	-	-	-	-	-	1
EEP112.3	2	1	1	-	-	-	-	-	-	-	-	-	-	-	-
EEP112.4	2	1	3	-	-	-	-	-	-	-	-	-	2	-	-
EEP112.5	2	1	1	-	-	-	-	-	-	-	-	-	2	-	-
EEP112.6	2	2	2	2	2				2		2	-	1	1	-
EEP112	2.1	1.6	2	1	1	-	-	-	1	-	1	-	1.1	1	1



5	haal SET		Beyond Boundaries
	chool: SET	,	
	ogram: B.Teo	ch	
	ranch: EEE		
	mester: II		
1	Course	CSE114 Course Name	
-	Code		
2	Course	Application Based Programming in Python	
	Title		
3	Credits	3	
4	Contact	3-0-0	
	Hours		
	(L-T-P)		
	Course	Compulsory	
	Status		
5	Course	Emphasis is placed on procedural programming, algorithm desi	0 0 0
	Objective	constructs common to most high-level languages through Python	ů ů
6	Course	Upon successful completion of this course, the student will be ab	
	Outcomes	CO1. Apply decision and repetition structures in program design	
		CO2. Demonstrate the use of Python lists, tuples and dictionaries	
		CO3. Implement methods and functions to improve readability o CO4. Describe and apply object-oriented programming methodo	
		CO5. Apply top-down concepts in algorithm design.	logy.
		CO6. Write Python programs to illustrate concise and efficient al	gorithms
7	Course	Python is a language with a simple syntax, and a powerful set	•
'	Description	widely used in many scientific areas for data exploration. T	
	Description	introduction to the Python programming language for stude	
		programming experience. We cover data types, control flow	
		programming.	
8	Outline sylla	bus	CO Mapping
	Unit 1	Introduction	
	А	History, Python Environment, Variables, Data Types, Operators.	CO1
	В	Conditional Statements: If, If- else, Nested if-else.	CO1
	_	Looping: For, While, Nested loops.	
	С	Control Statements: Break, Continue, And Pass.	CO1, CO6
	-	Comments	,
	Unit 2	List, Tuple and Dictionaries	
	A A	Lists and Nested List: Introduction, Accessing list,	CO2
	1	Operations, Working with lists, Library Function and	002
		Methods with Lists.	
	В	Tuple: Introduction, Accessing tuples, Operations,	CO2
	D	Working, Library Functions and Methods with Tuples.	02
	С	Dictionaries :Introduction, Accessing values in	CO2
		dictionaries, Working with dictionaries, Library Functions	
	Unit 3	Functions and Exception Handling	
	A A	· · ·	CO3,CO6
	A	Functions: Defining a function, Calling a function, Typesoffunctions,FunctionArguments	03,000
	В	Anonymous functions, Global and local variables	CO3,CO6
	С	Exception Handling : Definition Exception, Exception	C03,C06
	1 N .	LACEPHON HANDING. DEIMINON LACEPHON, EACEPHON	



r				Beyond Boundari					
	handling								
	Except cla	ause, Ti	ry? finally clause						
Unit 4	OOP and	File H	landling						
А	OOPs con	ncept :	Class and object, Attributes, Abstraction,	CO4					
	Encapsula	tion, P	olymorphism and Inheritance						
В	Static ar	al Keyword, Access Modifiers and	CO4						
	specifiers								
С	User Defi	CO4							
Unit 5	Module a								
А			rting module, Math module, Random	CO5,					
	module	1	5	,					
В	Matplotlil	o, Packa	ages	CO5,					
С		-	ching Linear Search, Binary Search. Sorting:	CO5, CO6					
	Bubble So	,							
Mode of	Theory								
examination									
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text	The Comple	te Refer	ence Python, Martin C. Brown, McGrwHill						
book/s*									
	ISBN:97800								
Other			n to computing in problem solving using Python,						
References			samy, McGrwHill- ISBN:9789352604173						
		2. Introduction to programming using Python, Y. Daniel Liang							
1	Pea	Pearson-ISBN:9780132747189							

COs	P01	P02	P03	P04	PO5	P06	P07	PO8	P09	P010	P011	P012	PS01	PSO2	PSO3
CSE114.1	1	3	2	2	1	-	-	-	1	-	1	-	2	2	1
CSE114.2	3	3	3	3	3	-	-	-	3	-	3	-	3	3	3
CSE114.3	3	3	3	3	2	-	-	-	3	-	2	-	3	3	2
CSE114.4	2	2	2	1	2	-		-	2	-	1	-	2	1	1
CSE114.5	2	3	2	1	2				1		2		1	2	2
CSE114.6	1	2	1	2	1				1		1		3	2	2
CSE114	2	2.7	2.2	2	1.8				1.8		1.7		2.3	2.2	1.8

Application Based Programming in Python Lab



Sc	hool: SET		Beyond Boundaries
	ogram:		
	Tech		
Br	anch:All	Semester: II	
1	Course	CSP114	
	Code		
2	Course	Application Based Programming in Python Lab	
	Title		
3	Credits	1	
4	Contact	0-0-2	
	Hours		
	(L-T-P)		
	Course	Compulsory	
	Status		
5	Course	Emphasis is placed on procedural programming, algo	
	Objective	constructs common to most high level languages thro	
6	Course	Upon successful completion of this course, the studer	
	Outcomes	CO1. Apply decision and repetition structures in prog	
		CO2. Demonstrate the use of Python lists, tuples and CO3. Implement methods and functions to improve re	
		CO4. Describe and apply object-oriented programmi	
		CO5. Apply top-down concepts in algorithm design.	ng methodology.
		CO6. Write Python programs to illustrate concise and	d efficient algorithms
7	Course	Python is a language with a simple syntax, and a pow	
	Description	widely used in many scientific areas for data explorat	
		introduction to the Python programming language for	
		programming experience. We cover data types, controprogramming.	of flow, object-oriented
8	Outline sylla		CO Mapping
0	Outline syna	545	
	Unit 1	Practical based on conditional statements	
		and control structures	
		1. Program to implement all conditional	C01
		statements	
		2. Program to implement different control	
	I I · / C	structures	
	Unit 2	Practical related to List, Tuples and	
		dictionaries	
		 Program to implement operations on lists Program to implement operations on 	CO2
		2. Program to implement operations on Dictionary	
		3. Program to implement operations on Tuple	
	Unit 3	Practical related to Functions and Exception	
		Handling	
		1. Program to implement Exception Handling	CO3
		2. Program to use different functions	
	Unit 4	Practical related to Object Oriented	
		Programming	
		1. Program to use object oriented concepts	CO4,CO6



_					🥿 🥟 Beyond Boundaries
			like inh	eritance, overloading polymorphism	
			etc.		
		2.	Program	n for file handling	
		_			
	Unit 5			ated to Modules and	
		Appli	cations		
		1.	Progra	m to use modules and package	CO5,CO6
		2.	Progra	m to implement searching and	
			sorting		
	Mode of	Practi	cal/Viva	1	
	examination				
	Weightage	CA	MTE	ETE	
	Distribution	60%	0%	40%	
	Text			Reference Python, Martin C. Brown,	
	book/s*	McGra	aw Hill,2	010-ISBN:9780072127188	
	Other	• I	ntroduct	ion to computing in problem solving	
	References	τ	using Pyt	hon, E Balagurusamy, McGraw Hill	
		Ι	SBN-97	89353160920	
		• I	introduct	ion to programming using Python, Y.	
		Ι	Daniel Li	ang, Pearson	
				80132747189	

COs	P01	P02	PO3	P04	PO5	P06	P07	PO8	P09	P01 0	P01 1	P01	PSO 1	PSO 2	PSO 3	
CSP114.1	1	3	2	2	1	-	-	-	1	-	1	-	2	2	1	
CSP114.2	3	3	3	3	3	-	-	-	3	-	3	-	3	3	3	
CSP114.3	3	3	3	3	2	-	-	-	3	-	2	-	3	3	2	
CSP114.4	2	2	2	1	2	-		-	2	-	1	-	2	1	1	
CSP114.5	2	3	2	1	2				1		2		1	2	2	
CSP114.6	1	2	1	2	1				1		1		3	2	2	
CSP114	2	2.7	2.2	2	1.8				1.8		1.7		2.3	2.2	1.8	



Calculus and Abstract Algebra

Sch	ool: SET		
Prog	gram: B.Tech.		
	nch: ALL	Semester: <u>1/2</u>	
1	Course Code	MTH 142	
2	Course Title	Calculus and Abstract Algebra	
3	Credits	4	
4	Contact	3-1-0	
	Hours		
	(L-T-P)		
	Course	Compulsory	
	Status		
5	Course	The objective of this course is to familiarize the prospec	
	Objective	with techniques in basic calculus and linear algebra. It ain	
		students with standard concepts and tools at an in advanced level that will serve them well towards t	
		advanced level of mathematics and applications that the useful in their disciplines.	cy would find
6	Course	CO1: Explain the concept of differential calculus, illustrat	e thecurvature
	Outcomes	and Maxima, minima and saddle point. (K2, K3, K4)	
		CO2: Explain the basic concepts matrices and determi	nate, evaluate
		system of linear equation by using rank and inverse met	hod. (K2, K3,
		K5)	
		CO3: Explain the basic concept of sets, relation, fund	ctions, groups
		Rings and Field. (K2, K4)	
		CO4: Discuss the basic of Vector spaces. (K1, K3)	
		CO5: Describe and use the linear transformation and evand kernel. (K1, K2, K3, K5)	valuate nullity
		CO6:Explain the concept of Eigen values and Eigen vec the diagonalization of matrices,explain the basic introdu product spaces.(K2, K3, K4, K5)	
7	Course	This course is an introduction to the fundamental of Mathe	ematics. The
	Description	primary objective of the course is to develop the basic und	lerstanding of
		differential and integral calculus, linear Algebra and Abstr	act Algebra.
8	Outline gullah	Nuclearly and Abstract Algebra	СО
0	Outline synab	ous:Calculus and Abstract Algebra	CO Mapping
	Unit 1	Calculus	mapping
	A		CO1
		Differentiation, Taylor's and Maclaurin theorems with remainders; indeterminate forms, L' Hospital's rule.	
	В	Maxima and minima, Partial derivatives, Euler's theorem.	CO1
	C	Total derivative. Evaluation of double integration.	CO1
		Applications of double integral (to calculate area).	



				Beyond Boundar					
Unit 2	Matrices								
A	Matrices, vect matrix multip		and scalar multiplication,	CO2					
В			s, linear Independence, rank Cramer's Rule	CO2					
С			elimination and Gauss-Jorda	n CO2					
Unit 3	Basic Algebr	a							
A		Sets, relations and functions. Basics of groups, cyclic groups.							
В	,								
С	Subgroups, basics of Rings and Field.								
Unit 4		Vector spaces Vector Space, linear dependence of vectors, basis,							
А	Vector Space, dimension.								
В	Linear transfo	Linear transformations (maps), range and kernel of a linear map, rank and nullity. Inverse of a linear transformation, Matrix associated with a linear map.							
С	Inverse of a li								
Unit 5	Vector space Module-4 Ve								
А	Eigenvalues,	CO6							
В	Symmetric, sl Diagonalizati		ic, and orthogonal Matrices,	CO6					
С		ction of Inner	product spaces, Gram-	CO6					
Mode of examination	Theory	0							
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*	geometry, 9th ISBN:9788177 2. Erwin Krey 10th Edition,	30%20%50%1. G.B. Thomas and R.L. Finney, Calculus and Analytic geometry, 9th Edition, Pearson, Reprint, 2002- ISBN:9788177583250.2. Erwin Kreyszig, Advanced Engineering Mathematics, 10th Edition, John Wiley & Sons, 2011- ISBN: 97804704583651. D. Poole, Linear Algebra: A Modern Introduction, 2nd Edition, Brooks/Cole, 2011-ISBN: 97805387354522. Veerarajan T., Engineering Mathematics for first year, Tata McGraw-Hill, New Delhi, 2008- ISBN:97800704948243. Ramana B.V., Higher Engineering Mathematics, Tata McGraw Hill New Delhi, 11th Reprint, 2010- ISBN:9780230345980							
Other References	 D. Poole, L 2nd Edition, I Veerarajan Tata McGraw ISBN:9780070 Ramana E Tata McGraw 								



	РО	РО	РО	PO4	PO	5 P	PO	PO	РО	PO1	PO1	PO1	PSO	PSO	PSO
	1	2	3			0	7	8	9	0	1	2	1	2	3
						6									
MTH142.	3	3	2	2	3	1	-	-	-	1	1	1	-	-	-
1															
MTH142.	3	3	3	2	2	2	-	-	-	1	1	2	-	-	-
2															
MTH142.	3	3	2	2	2	1	-	-	-	1	1	1	-	-	-
3															
MTH142.	3	3	2	2	2	1	-	-	-	1	1	1	-	-	-
4															
MTH142.	3	3	2	2	2	1	-	-	-	1	1	2	-	-	-
5															
MTH142.	3	3	2	3	2	2	-	-	-	1	1	2	-	-	-
6															
MTH142	3	3	2.2	2.1 7	2.2	1.3				1.0		1.5			



	Cabaal									
C I	School:									
	ol of Basic									
	ces and									
Resea										
<u> </u>	ram: B.TECH.									
Bran CSE	cn: EC/EEE	Semester: II								
1	Course Code	PHY 118								
2	Course Title	Electricity and Magnetism								
3	Credits	3								
4	Contact Hours	2-1-0								
4	(L-T-P)	2-1-0								
	Course Status	Compulsory								
5	Course	To make students familiar with the concepts of ele	etrostatics							
5	Objective	magnetostatics and electromagnetism and to utilize th								
	Objective	electromagnetism on various problems.								
6	Course	At the end of the course, the student will be able to:								
Ŭ	Outcomes									
		CO1: learn the basic concepts of electrostatics.								
		CO2: learn the fundamental concepts of electric potentials.								
		CO3: gain knowledge about the principle of capacitor, dielectrics								
		materials and electric polarization.								
		CO4: have a clear understanding of fundamentals of magn	etic effects							
		of								
		current and magnetism								
		CO5: learn the concept of Maxwell's Equations in differen	tial and							
		integral form and their physical significance.								
	<u> </u>	CO6: learn the fundamental concept of electricity and mag								
7	Course	Today, life without electromagnetic technologies is almost unth								
	Description	this reason, it is critically significant to understand the basic fun this paper. This course is able to explain the required basic								
		Both electricity and magnetism may be understood as force								
		balance and students learn to understand such concepts as cl								
		voltage, potential, current, resistance, and power within this fram								
7	Outline Syllabu	s	СО							
			Mapping							
	Unit 1	Electrostatics								
	А	Introduction to the course and prerequisites required	CO1							
		Coulomb's law-force between two point charges, forces								
		between multiple charges; superposition principle and								
		continuous charge distribution.								
	В	Electric field, electric field due to a point charge, electric	CO1							



 T	1		K Beyond	Boundaries
	flux.			
С	Gauss's theorem and its an infinitely long straight win plane sheet and uniformly (field inside and outside), c	re, uniformly / charged thin	charged infinite spherical shell	CO1
Unit 2	Potential			
A	Electric potential, potentia due to a point charge,	l difference, o	electric potential	CO2
В	a dipole and system of char	ges; equipote	ential surfaces,	CO2
С	Electrical potential energy charges and of electric dipo			CO2
Unit 3	Capacitance			
A	Conductors and insulator charges inside a conduc polarization.		-	CO3
В	Capacitors and capacitance plate, Cylindrical and spher	CO3		
С	Capacitance with and withe the plates of capacitor, ener		CO3	
Unit 4	Magnetic Effects of Curre	ent and Magr	netism	
А	Biot-Savart law and its aj circular loop,	~		CO4, CO6
В	Ampere's law and its ap straight wire.	oplications to	infinitely long	CO4, CO6
С	Ampere's law and its applie	cations to torc	idal solenoids.	CO4
Unit 5	Electromagnetism			
A	Electromagnetic induction	; Faraday's la	w, induced emf	CO5
В	Lenz's Law, displacement	current.		CO5
С	Maxwell's Equations in dif and their physical significat	ntegral form	CO5, CO6	
Mode of Examination	Theory			
Weightage	CA	MTE	ETE	



Distribution	30%	20%	50%	id Boundaries
Text books	-	Magnetism, K.K. ni. ISBN:9788121900		
Other References	Walker, John V 2. Electricity and	of Physics, Hallic Wiley,2014 ISBN I Magnetism, J. Ya ersity Tutorial Pres	: 9781118230749 arwood and J. H.	

Cos	PO	PO	PO	PO	РО	РО	PO	РО	РО	PO1	PO1	PO1	PSO	PSO	PSO
	1	2	3	4	5	6	7	8	9	0	1	2	1	2	3
PHY118.	3	2	2	2	2	1	1	1	1	1	2	1	-	-	-
1															
PHY118.	3	3	2	3	3	2	1	1	1	1	1	1	-	-	
2															
PHY118.	3	3	3	3	3	1	1	1	1	1	1	1	-	-	-
3															
PHY118.	3	3	3	2	2	1	1	1	1	1	1	1	-	-	
4															
PHY118.	2	2	2	2	2	1	1	1	1	1	1	1	-	-	-
5															
PHY118.	3	3	3	3	2	1	1	1	1	1	1	1	-	-	
6															
PHY118	2.8	2.7	2.5	2.5 0	2.3	1.2	1.0	1.0	1.0	1.0		1.0	-	-	-



ENGINEERING CHEMISTRY (CHY 111) (TERM I/II)

Sch	ool: SET	
Pro	gram: B.Tech.	
Bra	nch:	Semester:2
CS/	EC/IT/EEE	
1	Course Code	CHY 111
2	Course Title	Chemistry for engineers
3	Credits	4
4	Contact Hours	3-1-0
	(L-T-P)	
	Course Status	Compulsory
5	Course	1. Make it comprehended the importance of clean water.
	Objective	 Describe to the basic concepts of spectroscopy as described in the module content and is to teach getting of valuable information from the same to apply in various engineering applications. To provide an introduction to the basic concepts in Electrochemistry and apply them to understand batteries and corrosion. To equip the students with the knowledge of modern technologies i.e. nanotechnology and its various engineering applications.
6	Course Outcomes	 Students will be able to understand : Realize the importance of clean and healthy water by giving knowledge about water quality parameters and cleaning measures. In sighting the structural features of material by having the knowledge of spectroscopic techniques. State the main cause of corrosion and prevention measures. Name the components of galvanic cell and applies these to the understand the batteries and corrosion of a metal.

			HARDA
		4. Able to apply the basic information of eng materials and their applications.	gineering
		 Able to have a basic knowledge of technology in days i.e. Nanotechnology and its various applicat 	
		 Have a thorough grounding in chemistry and a worknowledge of advanced chemistry. 	king
7	Course Description	The course includes the fundamentals of The Electrochemistry and batteries, corrosion, in Chemistry of Materials, water technology and na This course satisfies the requirements of the program.	troduction to notechnology.
8	Outline syllabu	CO Mapping	
	Unit 1	Water: Analysis and its treatment	
	A	Water and water treatment: Drinking water standards, Water quality parameters and their measurement: pH (alkalinity and acidity –determination by titrimetry), Turbidity, Dissolved Oxygen (DO), biological oxygen demand (BOD), chemical oxygen demand (COD), chloride, fluoride, oil and fats,	CO1
	В	hardness (definition and expression, estimation of hardness (EDTA method), nutrients (N, P, etc.), nitrate, dissolved metals.	CO1
	С	Municipal water treatment process - screening, sedimentation, flocculation;Coagulation, Filtration (Slow sand and rapid sand), disinfaction-chlorination.	CO1
	Unit 2	Spectroscopic studies of materials	
	A	Principles of spectroscopy and selection rules. Electronic spectroscopy: basic principle, 'Lamberts Beer's law,	CO2
	В	chromophore, effect of conjugation on chromophore and applications, Fluorescence and its applications in medicine.	CO2
	С	Basic principle and applications of Nuclear magnetic	CO2



	resonance and magnetic resonance imaging spectroscopy.	evond Boundari
Unit 3	Electrochemistry, energy storage devices and corrosion	
A	Electrochemistry: Redox reactions, Nernst Equation, relation of e.m.f. with thermodynamic functions (Δ H, Δ F and Δ S). Electrochemical cells-	CO3
В	Galvanic cells and Concentration cell, electrode potentials and its relevance to oxidation and reduction, measurement of EMF under standard conditions, determination of pH using Hydrogen electrode,	CO3
С	primary battery: dry cells, secondary battery: Lead acid accumulator and Li Ion, fuel cells: H 2- O 2 .Corrosion: Types of corrosion, mechanism of Electrochemical corrosion, galvanic corrosion and protection against electrochemicalcorrosion.	CO3, CO6
Unit 4	Chemistry of materials	
A	:Structure, properties and application of carbon materials such as diamond, graphite, fullerenes, graphene. Liquid crystals: classification, Molecular ordering, identification, polymeric liquid crystals, and application of liquid crystals: displays and thermography.	CO4
В	Organic and inorganic semiconductors.Basic concepts of Conducting polymer, types,p-doping, n-doping, comparison with metallic conductors, examples and applications.	CO4
С	Biodegradable polymers: Basic information with common examplesPolyglycolic acid (PGA), Polyhydroxy butyrate (PHB), Polyhydroxybutyrates-co-beta hydroxyl valerate(PHBV), Polycaprolactone(pcl).	CO4, CO6
Unit 5	Nano science and technology	
A	Introduction to nanoscience and technology, bio- nanoinformation,	CO5, CO6

				SHARDA				
В	lithograp CNT's	hy, soft lithograpl	ny, Dip pen nanolithography,	CO5, CO6				
С		Application of nanotechnology in microelectronics and in memory devices.						
Mode of examination	Theory							
Weightage	CA	MTE	ETE					
Distribution	30%	20%	50%					
Text book/s*	ii. P ii. E o iii. U iv. E v. F vi. Ii F vi. Ii F vii. N	Principles of Plaublishing compan BahlArun, Bahl B. f Physical C. Co.,2000 University chemistr Engineering Chemi B. L. Tembe, Kama Physical Chemistry Introduction to na J. Owens, willeyi Vanotechnology, pportunity, LE fos	notechnology: C.P poole,Jr. nterscience 2003. science, innovation and ster, Pearson education 2007.					
Other			uid Crystals", Princeton					
References	U	University PressIS	SBN:9781439811450					
).P. Vermani, A.K hemistry", Galgot	. Narula, "Industrial ia Publications					

CO-PO MAPPING EC/EEE

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CHY 111. 1	3	1	1	2	1	1	1	1	1	1	1	1	1	1	-
CHY 111.2	3	1	1	1	1	1	1	1	1	1	1	1	1	1	-
CHY 111.3	3	1	1	1	1	1	1	1	1	1	1	1	1	1	-
CHY 111. 4	3	1	1	1	1	1	1	1	1	1	1	1	1	1	-
CHY 111. 5	3	1	2	1	2	1	1	1	1	1	1	1	1	1	-
CHY 111. 6	3	1	2	1	2	1	1	1	1	1	1	1	1	1	-
CHY 111	3.0	1.0	1.3	1.17	1.3	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	-



FEN104: Functional English Intermediate-2 First Year (Odd Semester) SYLLABUS

	T	T	JILLADOJ								
	Course										
1	number	FEN104									
2	Course Title	Functiona	al English Intermediate-2								
3	Credits	1									
	Contact										
4	Hours (L-T-P)	1-0-0 (-0-0 (However Contact hours : 2 hrs in a week)								
	Course	A skill-bas	skill-based course designed for undergraduate students with basic understanding of								
5	Pre-requisite	English la	nglish language								
		To guide	guide the students to hone the basic communication skills: listening, speaking,								
		reading a	ading and writing.								
			students to minimize the linguistic and soci	o-cultural barriers ei	merging in a						
	Course		environment.								
6	Objective	To help st	tudents to understand different accents and	d standardise their e	xisting English.						
			would be able to:								
		CO1: Utili	ize receptive language skills in order to cor	nprehend complex f	actual/literary						
		text									
		CO2: Und	lerstand long complex speeches and lectur	es							
		CO3: Com	npose clear and well-structured text to info	orm/express view po	pint						
		CO4: Exp	ress opinions about complex subjects by d	eveloping argument	s through						
		-	ve language skills								
		-	ically evaluate arguments in terms of the s	trength of evidence	and reasoning:						
			clusions through discussion	trength of evidence	and reasoning,						
			-								
			ognize and apply vocabulary and grammat	ical knowledge to ex	press thought						
		and actio	n;								
7	Course										
7	Outcomes		al Fuelish Internetists 2								
8	Outline syllad	ous: Function	nal English Intermediate-2 TOPICS	Def 9 Chanten	60-						
8.0				Ref. & Chapter	COs						
8.0 1	FEN104.A	UNIT A	LISTENING & DISCUSSION								
1 8.0	FEN104.A		Class discussion on Steven Spielberg's		CO1, CO2,						
8.0 2	FEN104.A1	Topic 1	Commencement Speech at Harvard	Ref 3, Ref 2	CO1, CO2, CO5, CO7						
2	TEN104.AI		Informative listening (Comprehension):								
8.0			Lecture by Johan Rockstrom: Let the								
3	FEN104.A2	Topic 2	Environment Guide our Development	Ref 4, Ref 2							
	1 21110 7.72		Expressing views on lessons learnt from		-						
8.0			the "Inspirational Speech for Students	Doff Dofa							
4	FEN104.A3	Topic 3	by Dr. APJ Abdul Kalam"	Ref 5, Ref 2							
8.0			READING TEXT & DISCUSSION	<u>I</u>	<u> </u>						
5	FEN104.B	UNIT B									
			Short Stories: "The Tiger in The Tunnel"	Ref 6, Ref 2							
8.0			by Ruskin Bond (Comprehension &		CO1, CO5,						
6	FEN104.B1	Topic 1	Critical Analysis)		CO7						
-			Poetry: "Where the Mind is Without	1							
8.0			<i>Fear</i> " by Rabindranath Tagore (Critical								
7	FEN104.B2	Topic 2	Appreciation and Discussion)								
			<i>"The Coffee House of Surat"</i> by Leo	1							
8.0			Tolstoy (Comprehension & Critical								
	1	1		1							
8	FEN104.B3	Topic 3	Analysis)								
8 8.0	FEN104.B3 FEN104.C	Topic 3 UNIT C	Analysis) CREATIVE WRITING & DISCUSSION								



9	1	I	I	🥿 🎾 Bey	ond Boundaries
9 8.1			Short Story Writing	Ref 2	CO3, CO4,
0	FEN104.C1	Topic 1		Net 2	CO5, CO7
8.1			Picture Interpretation		003,007
1	FEN104.C2	Topic 2			
8.1			Review Writing		
2	FEN104.C3	Topic 3			
8.1			TECHNICAL WRITING		1
3	FEN104.D	UNIT D			
		••••••	Emails & formal Letters		CO3, CO4,
8.1				Ref 1 (pages 478	CO8
4	FEN104.D1	Topic 1		to 593)	
8.1		Tania 2	Technical Reports (Informative &		
5 8.1	FEN104.D2	Topic 2	Routine based)		
8.1 6	FEN104.D3	Topic 3	Technical Proposal		
0	FEINI04.D5	TOPIC 5			
8.1			VOCABULARY BUILDING AND GRAM		
7	FEN104.E	UNIT E	LISTENING THE TEXTS)		
·			Phrasal Verbs; Idioms and Phrases;	Ref 2	CO3, CO6
			Proverbs; Functional Vocabulary;		000,000
8.1			Notional Concepts; Connectors and		
8	FEN104.E1	Topic 1	Linkers		
			Text based activities on: Non-finite		
			verbs; Reported Speech (Dialogue		
			Writing); Passives (Imperative		
8.1			sentences); Process description;		
9	FEN104.E2	Topic 2	Spotting error; Relative clauses.		
8.2			Spellings and Punctuations		
0	FEN104.E3	Topic 3			
9	Course Evalu	ation			
9.1	Course work:				
9.2	Attendance	None			
9.3	Homework		nents, no weight		
9.4	Quizzes		zzes (based on assignments); 20 marks		
9.5	Lab				
	Presentatio				
9.6	ns	None			
9.7	Any other	None			
		One,			
9.9	MTE	20%			
9.1					
0	End-term Exa				
10	Reference Boo				
		1. C	ommunication Skills by Sanjay Kumar and P	ushpLata, OUP Public	ations.
	Text book	2. Fi	unctional English Workbook (Intermediate)	2	
		3. St	even Spielberg's Commencemen	it Speech a	t Harvard
		(۲	https://www.youtube.com/watch?v=TYtoDu	<u>unfu00</u>)	
		4. Le		ide our	Development
			http://www.ted.com/talks/johan_rockstrom		•
		-	development)		nt_guide_our
	Videos and		spirational Speech for Students	,	vbdul Kalam
	Internet	(<u> </u>	<pre>https://www.youtube.com/watch?v=7E-cwo</pre>	dnsiow)	



6. Reading texts

Mapping of Outcomes vs. Topics FILENAME: Functional English Intermediate-2 (FEN104)

Outcome no. \rightarrow	CO1	CO2	CO3	CO4	CO5	CO6	C07	CO8
	001	02	005	04	005	000	07	008
Syllabus topic↓								
FEN104.A	Х	Х			Х		Х	
FEN104.A1	Х	Х			Х		Х	
FEN104.A2	х	х			х		Х	
FEN104.A3	Х	Х			Х		Х	
FEN104.B	Х				Х		Х	
FEN104.B1	Х				Х		Х	
FEN104.B2	Х				Х		Х	
FEN104.B3	Х				Х		Х	
FEN104.C			Х	Х	Х		Х	
FEN104.C1			Х	Х	Х		Х	
FEN104.C2			Х	Х	Х		Х	
FEN104.C3			Х	Х	Х		Х	
FEN104.D			Х	Х				х
FEN104.D1			Х	Х				Х
FEN104.D2			Х	Х				Х
FEN104.D3			Х	Х				Х
FEN104.E			Х			Х		
FEN104.E1			Х			Х		



Engineering Chemistry Lab (CHY-161)

Sch	ool: SET									
Pro	gram: B.Tech									
	nch: All	Semester: II								
1	Course Code	CHY-161 Course Name: Engineering Chemistry Lab)							
2	Course Title	Engineering Chemistry Lab								
3	Credits	1								
4	Contact	0-2								
	Hours									
	(L-T-P)									
	Course Status	Basic Engineering								
5	Course	1. To learn methods for preparation of solution of c	lifferent							
	Objective	concentration, their standardization								
		2. To learn quantitative estimation of different cher	nical species							
		by various volumetric methods.								
		3. To understand the practical concepts of reaction								
		4. To understand the procedure for testing of COD	of water							
		samples.								
6	Course	CO1 Propose solutions of different strength and standard	lize them							
0	Outcomes	CO1.Prepare solutions of different strength and standard								
	Outcomes	CO2.Estimate water alkalinity and hardness and hence water quality, the chloride ion/residual chlorine after disinfection								
		CO3.Understand the different order of reactions like Zer								
		Second order.	io, i list alla							
		CO4.Prepare simple thermosetting polymers at small sc	ale in							
		laboratory.								
		CO5.Understand the importance of microbial free water	by testing for							
		COD.								
		CO6.Understand the basics of analytical chemistry w	which may be							
		helpful to perform major engineering applications.								
7	Course	This course include various titration methods like acid-								
	Description	complexometric titration, precipitation titration etc. It								
		various calculations and units frequently used in analytic								
8	Outline syllabu	15	CO							
	TT	Desperation of standard solution	Mapping							
	Unit 1	Preparation of standard solution								
	A	To prepare N/10 normality solution of sodium carbonate and use it to standardize the given								
		hydrochloric acid solution.								
	BTo prepare N/30 normality solution of potassium dichromate and use it to standardize the given hypoCO1									
		solution. To determine the strength of given HCl solution by								
	С									
		titrating with standard NaOH solution by (a)Indicator								
		method (b) pH metrically								
L	1		ı]							



	-			Beyond Boundaries			
Unit 2	Analysis of w	ater					
А	To determine	the amount an	nd constituents of alkalinity				
	of given water						
В	To determine the hardness of water by EDTA method.						
С	To determine	CO2					
	Method.						
D	To determine						
	sample.						
Unit 3	Synthesis of						
А	Preparation of	f Bakelite and	Urea formaldehyde resin.	CO3			
Unit-4	Determinatio	Determination of kinetic parameters					
	To determine	e the rate co	onstant and order of the				
	reaction of hy	drolysis of an	ester catalyzed by an acid.				
	To determine	the rate cons	stant of hydrolysis of ethyl	CO4			
	acetate with	NaOH and sh	now that the reaction is of				
	second order.						
Unit-5	Determinatio	on of COD					
	To determine	the chemical	oxygen demand (COD) in	CO5,CO6			
	the given wate	er sample.		005,000			
Mode of	Practical						
examination							
Weightage	CA	MTE	ETE				
Distribution	60%	% None 40%					
Text book/s*	Text book, L	ab Manuals	·				
Other	Other Deferre						
References	Other Refere	nces					

CO and PO Mapping

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CHY161.1	2	3	1	-	2	1	2	-	3	3	2	2	-	-
CHY161.2	2	3	1	-	2	1	2	-	3	3	2	2	-	-
CHY161.3	2	3	1	-	2	1	2	-	3	3	2	2	-	-
CHY161.4	2	3	1	-	2	1	2	-	3	3	2	2	-	-
CHY161.5	2	2	2	-	2	1	1	-	3	3	1	2	-	-
CHY161.6	2	2	2	-	2	1	1	-	3	3	1	2	-	-
CHY161	2.0	2.7	1.3		2.0	1.0	1.7		3.0	3.0	1.7	2	-	-



	am: B.Tech h: ECE	
1	Course Code	ECP 120
2	Course Title	Mechanical Workshop
3	Credits	1.5
4	Contact Hours (L-T-P)	0-0-3
	Course Status	Compulsory
5	Course Objective	The objective of this course is to make the students, familiar with the modern day manufacturing processes, introduce them to various hand tools and equipment, acclimatize with the measuring devices, and perform basic machine tool operations in various machine tools.
6	Course Outcomes	On successful completion of this course, students will be able to CO1: Apply 5S (Seiri,Seiton, Seiso,Seiketsu and Shitsuke) methodology at workplace. CO2: Select the various hand tools used in the basic mechanical engineering workshop sections-smithy, carpentry, assembling, welding etc. CO3: Choose different measuring devices according to the job CO4: Differentiate between various machine tools and their operation CO5: Classify and select suitable tools for machining processes including turning, facing, thread cutting and tapping, milling, drilling and shaping. CO6: Apply the knowledge for advanced manufacturing experiments.
7	Course Description	 Black Smithy Shop: Simple exercises based on black smithy operations such as upsetting, practice of S -Hook from circular bar using hand forging operations. Carpentry Shop : Study of different types of wood , Carpentry Tools, Equipment and different joints, Practice of T joint, cross lap joint, Mortise and Tenon T joint, Bridle T joint Fitting Shop: Preparation of Square joint, V joint, half round joint, dovetail jointas per the given specifications, which contains: Sawing, Filing, Grinding, and Practice marking operations. Sheet Metal Shop: Study of galvanized Iron (G.I.) Sheet material properties, hand tools and sheet metal machines, and projective geometry, demonstration of different sheet metal operations and practice of development of Tray, cylinder, hopper, funnel etc. Welding Shop: Introduction, Study of Tools and welding Equipment (Gas and Arc welding), Selection of welding electrode and current, Bead practice and Practice of Butt Joint, Lap Joint.

				SH UNI Beyon	ARDA VERSITY	
		parts, different operations on I taper turning, k Shaper. Foundry Sho ingredients of	operations, stud Lathe machine, la cnurling and par p: Introduction moulding sand p of mould prep	nine tools in particular Lathe mach dy of cutting tools), Demonstration Practice of Facing, Plane Turning, rting and Study of Quick return n n to foundry, Patterns, pattern and melting furnaces. Foundry to paration and Practice – Preparation	n of different step turning, nechanism of allowances, ols and their	
8	Outline syllabus				CO Mapping	
	List of Experiments					
Unit 1	Experiment 1	To make a S-sl forging techniq		n a given circular rod using hand	CO1	
	Experiment 2		etail lap joint in (Carpentry shop.	CO1	
Unit 2	Experiment 3			n Carpentry shop.	CO2	
	Experiment 4	shop.		iven mild steel pieces in fitting	CO2	
Unit 3	Experiment 5	To prepare a v shop.	V-Fit from the	given mild steel pieces in fitting	СО3,	
	Experiment 6	To make a recta shop.	angular tray of s	pecified dimensions in sheet metal	CO3	
Unit 4	Experiment 7	To make a Lap welding.	joint, using the	given mild steel pieces using arc	CO4 , CO6	
	Experiment 8	To perform step work piece	turning and tap	er turning operations on the given	CO4, CO6	
Unit5	Experiment 9	To prepare a sa	nd mold, using t	he given single piece pattern	CO5, CO6	
	Experiment 10	To prepare a s	and mold, usin	g the given Split-piece pattern.	CO5, CO6	
	Mode of	Practical				
	examination					
	Weight- age	СА	MTE	ETE		
	Distribution	60%	0%	40%		
	Text book/s*	DhanpathRai 2. Kannaiah	& SonsISB P. and Naray	Workshop Technology Vol N:9788120340824 vana K.L., Workshop Manual 9788122419177,		



COs	P01	P02	P03	P04	PO5	P06	P07	P08	P09	PO10	P011	P012	PS01	PSO2	PSO3
MEP105.1	-	-	-	-	-	2	-	2	-	-	-	2	-	-	-
MEP105.2	1	-	-	-	1	2	-	-	-	-	-	1	1	1	-
MEP105.3	2	-	-	-	1	2	-	-	-	-	-	2	1	1	-
MEP105.4	2	-	1	-	2	2	-	-	-	-	-	2	1	1	-
MEP105.5	2	-	1	-	2	2	-	-	-	-	-	2	2	1	-
MEP105.6	2	-	1	-	2	2	-	-	-	-	-	2	2	-	1
MEP105	2	-	1	-	2	2	-	-	-	-	-	2	2	-	1



Tinkering Labs

Pr Br	hool: SET ogram: B.TEC anch: EEE mester:2	ĊH								
1	Course Code	ECP10)7							
2	Course Title									
3	Credits	1	ing Labs							
4	Contact Hours	_								
	(L-T-P)									
	Course Status	Compu	ulsory							
5	Course Objective	•	To be acqua	ainted with hardware's in Consumer E	lectronics goods					
6	Course Outcomes	ts.								
7	Course			e their Knowledge on consumer produ-						
	Description									
8	Outline syllab	us			CO Mapping					
	Unit 1	Inside Ce	ll phone Ch	arger						
	А	Unscrew	•		CO1					
	В	Identifyin	g parts		CO1					
	С	Working	01		CO1, CO6					
	Unit 2	Mobile pl	iones							
	А	Unscrew			CO2					
	В	Identifyin	g parts		CO2					
	С	Working			CO2, CO6					
	Unit 3	USB								
	А	Basics			CO3					
	В	Inside US	B cable/Port		CO3					
	С	Working			CO3, CO6					
	Unit 4	Speakers								
	А	Unscrew			CO4					
	В	Identifyin	g parts		CO4					
	С	Working			CO4, CO6					
	Unit 5	Compute	rs							
	А	Unscrew CO5								
	В	Identifyin	g parts ,Wor	king	CO5					
	С	Screw up			CO5, CO6					
	Mode of	Practical &	& Viva							
	examination									
	Weightage	CA	MTE	ETE						
	Distribution	60%	0%	40%						
	Text	Lab Manu	als	·						
		•								



book/s*		d Boundaries
Other	https://www.youtube.com/watch?v=WNRzU5DLA0I	
References	https://www.youtube.com/watch?v=jghFENiUsBI	

Cos	P01	P02	P03	P04	P05	P06	P07	P08	P09	P010	P011	P012	PS01	PSO2	PSO3
ECP107.1	3	1	1	-	1	2	1	-	2	1	-	1	1	1	2
ECP107.2	3	1	1	-	1	2	1	-	2	1	-	1	1	1	2
ECP107.3	3	1	1	-	1	2	1	-	2	1	-	1	1	1	2
ECP107.4	3	1	1	-	1	2	1	-	2	1	-	1	1	1	2
ECP107.5	3	1	1	-	1	2	1	-	2	1	-	1	1	1	2
ECP107.6	3	1	1	-	1	2	1	-	2	1	-	1	1	1	2
ECP107	3.0	1.0	1.0		1.0	2.0	1.0		2.0	1.0		1.0	1.0	1.0	2

*	SHARDA
	UNIVERSITY Beyond Boundaries

School Techno	l: School of Engineering and ology	Neyond Bou	
Progra	ım: B.Tech.		
Branch	1: Physics	Semester: I,II	
1	Course Code	PHY 161	
2	Course Title	Physics Lab 1	
3	Credits	1	
4	Contact Hours (L-T-P)	0-0-2	
	Course Status	Compulsory	
5	Course Objective	To gain practical knowledge by applying the experimental method with the Physics theory.	s to correlate
6	Course Outcomes	On successful completion of the course the students will have: CO1: Knowledge and study of basic physics experiments base harmonic motion CO2: Use the concept of stress, strain to calculate modulus of rigi modulus. CO3: Understand how to determine moment of inertia of different CO4: Understand how to draw characteristic curves of different CO4: Understand how to calculate frequency using Melde's Experin CO5: Understand how to calculate frequency using Melde's Experin CO6: Apply the mathematical concepts/equations to obtain quantia and ability to conduct, analyze and interpret experiments	dity, Young's bodies. nt electronic ment
7	Outline Syllabus		CO Mapping
	Unit 1		
	А	1. To verify the relation of time period using simple	CO1
	B C	pendulum.2. To determine the acceleration due to gravity and radius of Gyration of compound pendulum and compare with	
		theoretical value.	
	Unit 2	2. To measure the memory of inertia of a flow heal	
	A	 To measure the moment of inertia of a flywheel. To determine the Young's modulus of a beam using 	603
	B C	4. To determine the roung's modulus of a beam using cantilever beam experiment apparatus.5. To determine vertical distance between two points using sextant.	CO2
	Unit3		
	A B	6. To determine the modulus of rigidity of a material of a given wire with an inertia table (torsion pendulum) by	CO3
	С	dynamical method. 7. To calculate Moment of inertia of different irregular shapes.	CO4
	Unit 4		
	A	8. To determine the frequency of an electrically maintained	
	В	tuning fork using Melde's Apparatus. (i) Transverse mode of vibration (ii) Longitudinal mode of vibration.	CO4,CO6
	С	 To determine the coefficient of viscosity of water by Poiseuille's method. 	
	Unit 5		
	A	10. To draw the characteristic curve of a PN junction diode.	
	B C	11. To trace the circuit of a Half Wave Rectifier circuit and determine efficiencies and ripple factors with capacitor and inductor filters.	CO5,CO6



	1		Beyond Boundaries										
		12. To trace the circuit of a Full Wave Rectifier circuit and determine efficiencies and ripple factors with capacitor and inductor filters.											
Mode of Examination	Mode of Examination Practical/Viva												
Weightage Distribution	CA	ETE											
	60%	0%	40%										
Text books	1. B.Sc. Practical Physics-	Harnam Singh, S. Chanc	l Publishing.										
	2. B.Sc. Practical Physics-	C L Arora, S. Chand Pub	lishing.										
Other References	1. GeetaSanon, BSc Pract	ical Physics, 1st Edn. (20	07), R. Chand & Co.										
	2. B. L. Worsnop and H. T. Flint, Advanced Practical Physics, Asia												
	Publishing House, New												

Cos	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
PHY161.1	2	2	2	1	1	1	2	3	3	3	2	3	-	-	-
PHY161.2	2	2	2	1	1	1	2	3	3	3	2	3	-	-	-
PHY161.3	2	2	2	1	1	1	2	3	3	3	2	3	-	-	-
PHY161.4	2	2	2	1	1	1	2	3	3	3	2	3	-	-	-
PHY161.5	2	2	2	1	1	1	2	3	3	3	2	3	-	-	-
PHY161.6	2	2	2	1	1	1	2	3	3	3	2	3	-	-	-
PHY161	2.0	2.0	2.0	1.0	1.0	1.0	2.0	3.0	3.0	3.0	2.0	3.0	-	-	-



III TERM

SU/SET/B. Tech./EEE

Page 42



	1 000		Beyon
	ool: SET		
	gram: B. Tech.		
Bra		Semester: 03	
	E/EE/ECE	EEE220	
1	Course Code	EEE220	
2	Course Title	Network Analysis and Synthesis	
3	Credits	3	
4	Contact Hours (L-T-P)	3-0-0	
	Course Status	Compulsory	
5	Course Objective	To develop problem solving skills and understanding of cir through the application of techniques and principles of ele analysis to common circuit problems.	-
		After successful completion of the course, student will be a CO1 Obtain circuit matrices of linear graphs and analyze using graph theory CO2 Select appropriate and relevant technique for solving network in different conditions	networks
6	Course Outcomes	 CO3 Learn conditions for stability and realizability of net functions CO4 Solve two port network functions CO5 Synthesize driving point functions of RL, RC and R 	
		CO6 Apply mathematics in analyzing and synthesizing the time and frequency domain.	ne networks in
7	Course Description	This course deals with the fundamentals of electric components and the mathematical tools used to represent electrical circuits. It also deals with analysis of stability of transfer function and also to design circuit from transfer fur-	nt and analyze network using
8	Outline syllabus	S	CO Mapping
	Unit 1	GRAPH THEORY	
	А	Graph of a network, definitions, tree, co tree, link, basic loop and basic cut set	CO1, CO2
	В	Incidence matrix, cut set matrix, tie set matrix	CO1, CO2
	С	Duality, loop and node methods of analysis	CO1, CO2
	Unit 2	NETWORK THEOREMS (FOR AC NETWORKS)	
	А	Super-position theorem, Thevenin's theorem, Norton's theorem, Maximum power transfer theorem	CO1, CO2
	В	Reciprocity theorem, Millman's theorem	CO1, CO2
	С	Compensation theorem, Tellegen's theorem	CO1, CO2
	Unit 3	NETWORK FUNCTIONS	



_					Beyon
	A	-		ncy, Transform Impedances	CO3, CO6
			1	ort and two port networks,	
	В			properties of driving point and	CO3
		transfer funct			
	С	1		from pole zero plot	CO3
	Unit 4	TWO PORT	NETWORKS	5	
	А	Characterizat and h parame		port networks Z, Y, ABCD	CO2, CO6
	В	Reciprocity a	nd symmetry,	Inter-relationships between	CO2
		the parameter	'S	-	
	С	Inter-connect	ions of two poi	rt networks, Ladder and Lattice	CO2
		networks, T &	k П Representa	ation	
	Unit 5	NETWORK	SYNTHESIS		
	А	Positive real	function: definit	ition and properties, properties	CO4,CO5
		of LC, RC an	d RL driving p	oint functions	
	В	Synthesis of I	LC, RC and RI	driving point immittance	CO4, CO5
		functions usin	ng Foster and C	Cauer first and second forms	
	C			ctive filter fundamentals, low	CO4, CO5
		1 0 1	ss, band pass, b	and elimination filters.	
	Mode of	Theory			
	examination		1	1	
	Weightage	CA	MTE	ETE	
	Distribution	30%	20%	50%	
	Text book/s*	Franklin F. K	uo,"Network	Analysis and Synthesis", John	
		Wiley & Son	s ISBN:978812	26510016, 8126510013	
	Other	1. M.E. Van	Valkenburg,"	Network Analysis", Prentice	
	References	Hall of India	ISBN:9788131	701584, 8131701581	
		2. Donald E.	Scott: "An Intr	oduction to Circuit analysis: A	
		System App	oroach" McG	raw Hill Book Company.	
			0561274, 0070		
		•		emmerly, Engineering Circuit	
		-	ata McGraw	Hill. ISBN:9789814646345,	
		9814646342			

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SU/SET/B. Tech./EEE



COURSE ARTICULATION MATRIX:

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1			2						2		
CO2	3	3	1	2							2		3	3	
CO3	3	3	3	3	2		3				2		3	3	
CO4	3	2	2	2	1								2	1	
CO5	3	2	1	1	2		3				2		2	2	
CO6	3	2	2	2									2	1	
	3.00	2.33	1.67	1.83	1.67		2.67				2.00		2.33	2.00	

SU/SET/B. Tech./EEE



Sch	ool: SET		
Pro	gram: B.Tech		
	nch: EEE/EE	Semester: 3	
1	Course Code	EEE221	
2	Course Title	Electrical Machines-I	
3	Credits	3	
4	Contact Hours (L-T-P)	3-0-0	
	Course Status	Compulsory	
5	Course Objective	To provide students with: 1. knowledge of basic principles of electromechanical energy 2. the understanding of operation principles of electrical mac 3. ability to analyse different electrical machines	
6	Course Outcomes Course	 1: After completion of this course students will be able to: CO 1. Understand the concepts of magnetic circuits. CO 2. describe the basic energy conversion principles and di magnetic field systems CO 3. Understand the operation of dc machines CO 4. Analyse the differences in operation of different dc maconfigurations. CO 5. Analyse single phase and three phase transformers circuits CO 6 Combine an understanding of the established principle concepts and terminology relevant to electrical machines wit application. 	achine rcuits. les, theories,
,	Description	The course covers the basics of electromechanical energy co- electrical machines. The operating principles of DC machine transformers are thoroughly described as well as their testing control methods.	es and
8	Outline syllabu	15	CO Mapping
	Unit 1	Magnetic fields, Electromagnetic force and torque	
	A	Review of magnetic circuits - MMF, flux, reluctance, inductance; Visualization of magnetic fields produced by a bar magnet and a current carrying coil - through air and through a combination of iron and air	CO1,CO6
	В	Influence of highly permeable materials on the magnetic flux lines. B-H curve of magnetic materials, energy stored in the magnetic circuit	CO1
	С	force as a partial derivative of stored energy with respect to position of a moving element; torque as a partial derivative of stored energy with respect to angular position of a rotating	CO2



	element.						
Unit 2	DC machines						
А	Basic construction of a DC machine, visualization of magnetic	CO3, CO					
	field produced by the field winding excitation with armature						
	winding open, air gap flux density distribution, flux per pole ;						
	Armature winding and commutation - Elementary armature coil						
	and commutator, lap and wave windings, construction of						
	commutator						
В	DC generator: principle of operation, induced EMF in an	CO3					
	armature coil, commutation, methods of improving						
	commutation, parallel operation of DC generator						
С	DC Motor: principle of operation, Derivation of back EMF	CO3, CC					
	equation, derivation of torque equation						
Unit 3	DC machine – Speed Control and Testing						
A	Armature reaction, Cross magnetizing and de-magnetizing	CO3, CC					
	AT/pole, Types of field excitations - separately excited, shunt	, _ 0					
	and series. Characteristics of separately excited and self-excited						
	generators, build-up of EMF, critical field resistance and critical						
	speed						
В	Characteristics and torque-speed characteristics of separately						
D	excited, shunt and series motors. Speed control of DC Motors:						
	armature voltage and field flux control methods. Ward-Leonard	CO3, CC					
	system	005,00					
С	Losses of DC machines: constant and variable losses, calculation	CO4					
C	of efficiency, condition for maximum efficiency. DC machine	001					
	Testing: direct, indirect and regenerative testing: brake test,						
	Swinburne's test, Hopkinson's test, field's test,						
Unit 4	Transformers						
A	Principle, construction and operation of single-phase	CO5, CC					
	transformers, EMF equation, equivalent circuit, phasor	,					
	diagram, voltage regulation, losses and efficiency, condition for						
	maximum efficiency, All day efficiency, regulation and						
	condition for maximum voltage regulation						
В	Three-phase transformer - construction, types of connection	CO5					
	and their comparative features, Parallel operation of single-						
	phase and three-phase transformers,						
С	Autotransformers - construction, principle, applications and	CO5					
	comparison with two winding transformer						
Unit 5	Transformers Testing						
А	Testing - open circuit and short circuit tests, polarity test, back-	CO5, CO					
	to-back test, separation of hysteresis and eddy current losses						
В	Poly phase connections, third harmonics and their effect	CO5					
С	three winding transformers, tertiary winding, Scott connection	CO5					
Mode of	Theory/Jury/Practical/Viva						
examination	moory, sury, radioul, viva						
v.a.mation	CA MTE ETE	+					



Distribution	30%	20%	50%	
Text book/s*		chines by I.J. N ers. , ISBN 125	agrath & D.P. Kothari, Tata 9081532 2010	Mc Graw –
Other References	Ma 201 2. 2. <i>A</i> and	chinery", Nev 4. ISBN:978 A. E. Clayton design of DC	and C. Kingsley, "Electric v York, McGraw Hill Edu 0071326469, 0071326464 and N. N. Hancock, "Perf C machines", CBS Publish 0852268131, 0852268130	ucation, 4 formance ners,

COURSE ARTICULATION MATRIC

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	2	2				1				2	2	2
CO2	3	2	3	2	3				1				2	2	3
CO3	3	3	3	2	3				1				3	3	3
CO4	3	3	3	3	3				1				3	3	3
CO5	3	3	3	2	3				1				2	3	3
CO6	3	3	2	3	3				1				3	2	3
	3.00	2.67	2.67	2.33	2.83				1.00				2.50	2.50	2.83

SU/SET/B. Tech./EEE



Sch	ool: SET		
	gram: B.Tech		
	nch: EEE/EE	Semester: 3	
1	Course Code	EEP221	
2	Course Title	Electrical Machines-I Lab	
3	Credits	1	
4	Contact Hours	0-0-2	
	(L-T-P)		
	Course Status	Compulsory	
5	Course	The capability to analyze the operation of electric machine	s under
	Objective	different loading conditions	
	5	The ability to conduct testing and experimental procedures	on different
		types of electrical machines.	
6	Course	CO1: Experimentally obtain the load characteristics of var	ious dc motors
	Outcomes	and generators.	
		CO2: Determination of various performance curves of DO	C Motor
		CO3: Experimentally perform speed control of DC motor	
		CO4: Understand the concept of efficiency and the short ci	
		impedance of a single-phase transformer from no-load test	, winding
		resistance, short circuit test, and load test	<i>c</i>
		CO5: Understand the concept of parallel operation of trans	
		CO6 Combine an understanding of the established princ.	• · · · · ·
		concepts and terminology relevant to electrical machines v application.	vitii practical
7	Course		
,	Description		
	Description	The course covers practical experiment on transformers an	d
		DC machines. It includes load test on various dc machines	
		transformer and also speed control of DC motor.	
		I I I I I I I I I I I I I I I I I I I	
8	Outline syllabus		CO Mapping
	Unit 1	Practical based on Load Test of DC Generator	
		Load test on DC shunt generator and determination of	CO1,CO6
		characteristics.	
		Load test on DC series generator and determination of	CO1
		characteristics.	CO1
		Load test on DC compound generator and determination of	CO1
	Unit 2	characteristics. Practical related to Characteristic of DC Generator	
			CO1
		Magnetization characteristics of DC shunt generator and determination of critical field resistance and critical speed.	
		determination of entical neithresistance and entical speed.	+
			<u> </u>



Unit 3	Practical rel	ated to DC	² Motor	
	Swinburne's	test of DC M	achine	CO2, CO6
	Brake test on	DC compou	nd motor and determination	of CO2
	performance	curves.		
	Hopkinson te	st on two id	entical DC machine.	CO2
	Brake test on	DC shunt mo	otor and determination of	CO2
	performance of	curves.		
	speed control efficiency.	of DC shunt	motor and predetermination	of CO3
Unit 4	Practical rel	ated to Tes	sting of Transformer	
	OC and SC test	CO4, CO6		
	Sumpner's tes	CO4		
	To perform loa	CO4		
Unit 5	Practical rel			
	Parallel operat	CO5, CO6		
	Polarity test o			
	Study of Scott			
Mode of examination	Jury/Practica			
Weightage	CA	MTE	ETE	
Distribution	60%	0%	40%	
Text book/s*	Electric Machi – Hill Publishe	c Graw		
Other	1. A.E.	Fitzgerald	and C. Kingsley, "Electric	
References	Mach	inery", Nev	v York, McGraw Hill Educ	ation,
	2014.	ISBN:978	0071326469, 0071326464	
	2. A.			
		CBS		
			d design of DC machines",	
			. ISBN:9780852268131,	
	08522	268130		

COURSE ARTICULATION MATRIX:



	1	1													
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	1	3								3	3	3
CO2	3	2	2	2	3								2	2	3
CO3	3	3	2	2	2								3	3	2
CO4	3	2	3		3								2	3	3
CO5	3	2	2		3								2	2	3
CO6	3	3	2	2	3								3	2	2
	3.00	2.33	2.17	1.75	2.83								2.50	2.50	2.67



IV TERM

SU/SET/B. Tech./EEE



	ool: SET		
	gram: B.Tech		
	nch: EEE/EE	Semester: 4	
1	Course Code	EEE224	
2	Course Title	Electrical Machines-II	
3	Credits	3	
4	Contact	3-0-0	
	Hours		
	(L-T-P) Course Status	Compulsory	
5	Course Status Course	Compulsory To provide students with:	
5	Objective	To provide students with: 1. fundamentals of AC machine construction	
	Objective	2. the understanding of operation principles of AC electrical	machines
		3. ability to analyse performance characteristics of ac machin	
6	Course	After completion of this course students will be able to:	
0	Outcomes	CO 1. Understand the concepts of rotating magnetic field.	
	0	CO 2. demonstrate the operation of Synchronous generator a	nd motor
		CO 3. define, analyse and solve problem based on Three-pha	
		machine	
		CO 4. identify the problem in three-phase Induction motor starting	ng and analyse
		different type of starters	
		CO 5. analyse the principle of operation of special electrical	
		CO6 Combine an understanding of the established principl	
		concepts and terminology relevant to electrical machines wit	h practical
		application.	
7	Course		
	Description	This course provides a basic understanding of AC maching	•
		fundamentals, constructional features, operational analysis phasor diagrams, equivalent circuits, determination of perfe	
		parameters, testing and applications	ormance
		parameters, testing and appreations	
8	Outline syllabu	18	CO Mapping
	Unit 1	Fundamentals of AC machine windings	
	А	Physical arrangement of windings in stator and cylindrical rotor;	CO1,CO6
		slots for windings; single turn coil - active portion and overhang;	
	В	full-pitch coils, concentrated winding, distributed winding,	CO1
		winding axis, 3D visualization of the above winding types	
	C	Air-gap MMF distribution with fixed current through winding -	CO1
		concentrated and distributed, Sinusoidally	
		distributed winding, winding distribution factor	
	Unit 2	Synchronous machines	
	А	Principle of rotating magnetic field, Constructional features,	CO2, CO6
		cylindrical rotor synchronous machine, Salient pole, generated	
		EMF, equivalent circuit and phasor diagram, armature reaction,	
		voltage regulation: EMF, MMF, ZPF and ASA methods.	



В	Synchronous	motor: Prin	ciple of operation,	Starting methods.	CO2		
	Operating cha	aracteristics	of synchronous r	nachines, V-			
	curves. Salier	<u>t pole mac</u> ł	ine – two reactio	on theory,			
С	Analysis of ph	asor diagra	m, power angle c	haracteristics.	CO2		
	Parallel opera	tion of alte	rnators - synchroi	nization and			
	load division						
Unit 3	3- Phase Induc	tion Machin	es		1		
A	Principle of op	eration, cons	tructional details,	types of rotors,	CO3,CO6		
			ue characteristics.	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	,		
В	Condition for r	power, losses					
	and efficiency,	rotor tests,					
	cogging and cr	on of no load	CO3				
	losses.						
С	Double cage ro	otor, inductio	n generator.		CO3		
Unit 4	Starting and S	peed Contro	of 3-Phase Induct	ion Motor			
А	Requirements	for starters,	types of starters: st	ator resistance	CO4,CO6		
	and reactance,	ner and star-delta					
	starters.						
В	Speed control:	change of vo	oltage, torque, num	nber of poles and	CO4		
	slip.				CO4		
С	V/f control method, cascaded connection, slip power recovery						
	scheme.						
Unit 5	Special Electrical Machines						
А	Single phase induction motor, double revolving field theory and						
	operation and its type						
В	Principle of operation and constructional features of universal						
~	and stepper motors						
C	Principle of operation and constructional features of brushless						
	DC motor and servomotor						
Mode of	Theory/Jury/I	Practical/Vi	Va				
examination	<u></u>		DED		+		
Weightage	CA	MTE	ETE				
Distribution	30%	20%	50%		<u> </u>		
Text book/s*	Electric Machi Hill Publishers		grath & D.P. Kotha	ri, Tata Mic Graw –			
Other				Floatria			
References		e	nd C. Kingsley, "				
References			York, McGraw H				
	2014.	ISBN:9780	071326469, 0071	326464			
	2. A. I	E. Clayton a	nd N. N. Hancocl	k, "Performance			
	and de	esign of DC	machines", CBS	Publishers,			
		0	852268131, 0852		1		



Course Articulation Matrix:

Cos	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
EEE213.1	3	2	2	1	2	1		1					2	2	2
EEE213.2	3	3	2	2	2	2		2	1	1			3	2	3
EEE213.3	3	3	3	2	3	3		2	1	1			3	3	3
EEE213.4	3	3	3	3	3	3		2					3	3	3
EEE213.5	3	3	3	3	3	2		3		1			3	3	2
EEE213.6	3	3	3	3	3	2		3		1			3	2	3
	3.00	2.83	2.67	2.33	2.67	2.17		2.17	1.00	1.00			2.83	2.50	2.67

SU/SET/B. Tech./EEE



School: SET Program: B. Tech Program: B. Tech Semester: 4 1 Course Code EEP224 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours 0-0-2 (L-T-P) Course Status Compulsory 5 Course Status Compulsory 6 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The capability to conduct testing and experimental procedures on different types of electrical machines. 6 Course CO1: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. C02: Understand the encept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. C06 <th></th> <th></th> <th>Γ</th> <th></th>			Γ							
Branch: EEE/ZE Semester: 4 1 Course Code EIP224 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours 0-0-2 (L-T-P) Course Status Compulsory 5 Course • The capability to analyze the operation of electric machines under different loading conditions 6 Course • The capability to conduct testing and experimental procedures on different types of electrical machines. 6 Course CO1: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. C04: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. CO Mapping 8 Outline syllabus CO Mapping CO1: CO2 9 Practical based on three-phase induction motor. CO1 10										
1 Course Code Course Title EEP224 2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours Objective 0-0-2 5 Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. C04: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. C05: Understand the concept of parallel operation of alternator. C06 Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. CO1	· · · ·	0								
2 Course Title Electrical Machines-II Lab 3 Credits 1 4 Contact Hours 0-0-2 (L-T-P) Course Status Compulsory 5 Cospicative • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The capability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes CO1: Experimentally obtain the load characteristics of induction motor. CO3: Experimentally perform speed control of induction motor CO3: Experimentally perform speed control of field current on armature current and power factor of a synchronous motor. CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. CO6 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor . CO1. CO2 generator. 7 To perform load test on three-phase induction motor. CO1. CO2 induction motor 7 To perform load test on three-phase induction motor. CO1. CO2 induction motor.										
3 Credits 1 4 Contact Hours (L-T-P) 0-0-2 5 Course Objective Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes CO1: Experimentally obtain the load characteristics of induction motor. C02: Determination of variation of field current on armature current and power factor of a synchronous motor. CO3: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. CO1, CO2 ignerator. 7 To perform no-load and blocked rotor tests on three-phase induction motor CO1, CO2 ignerator. 8 Outline syllabus CO Apping 10 To perform load test on three-phase induction motor. CO1 10 To perform no-load and blocked rotor tests on three-phase induction motor. CO1 11 Practical related to										
4 Contact Hours (L-T-P) 0-0-2 Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally perform speed control of induction motor. C02: Determination of various performance characteristic of induction motor C03: Experimentally perform speed control of induction motor. C05: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. C05: Understand the concept of parallel operation of alternator. C06 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping 10 To perform no-load and blocked rotor tests on three-phase induction motor C01. C01. C02 11 Practical based on three-phase induction motor. To perform load test on three-phase induction motor. To perform no-load and blocked rotor tests on three-phase induction motor. C01. C01. C02 11 Practical related to single phase induction motor. To perform no-load and blocked rotor tests on single-phase induction motor. C01. C02 11 Practical related to single phase induction motor. To perform no-load and										
(L-T-P) Course Status Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. 7 Course Description The course covers practical experiment on three phase induction motor, sinduction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. CO1 7 To perform no-load and blocked rotor tests on three-phase induction motor CO1,CO6 1 To perform load test on three-phase induction motor. CO1,CO2 2 To obtain the characteristic of three-phase induction generator. CO1,CO2 4 To obtain the characteristic of rotation and capacitor and to reverse its direction of rotation To perform load test on single-phase induction motor CO1, CO2 induction motor. 4			-							
Course Status Compulsory 5 Course Objective • The capability to analyze the operation of electric machines under different loading conditions 6 Course Outcomes • The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. C02: Determination of various performance characteristic of induction motor C03: Experimentally perform speed control of field current on armature current and power factor of a synchronous motor. C05: Understand the concept of parallel operation of alternator. C06 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. To perform load test on three-phase induction motor. C01 7 To perform load test on three-phase induction motor. C01, C02 induction motor C01, C02 8 Outline syllabus CO1, C02 C01, C02 9 To perform load test on three-phase induction motor. C01, C02 9 To perform no-load and blocked rotor tests on three-phase induction motor. C01, C02 9 Practical related to single phase	4		0-0-2							
5 Course Objective The capability to analyze the operation of electric machines under different loading conditions The ability to conduct testing and experimental procedures on different types of electrical machines. 6 Course Outcomes C01: Experimentally obtain the load characteristics of induction motor. CO2: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor. CO3: Experimentally perform speed control of induction motor. CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. CO6 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor. To perform load test on three-phase induction motor. To obtain the characteristic of three-phase induction generator. CO1, CO2 generator. 1 Practical related to single phase induction motor. To perform load test on single-phase induction motor. To perform load test on single-		· · · · ·	Commulación							
Objective different loading conditions number interview of the second of the seco	5									
6 Course Outcomes CO1: Experimentally obtain the load characteristics of induction motor. CO2: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. CO6: Understand the concept of parallel operation of alternator. CO6: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor CO1, CO6 induction motor 7 To perform no-load and blocked rotor tests on three-phase induction motor CO1, CO2 8 Outline syllabus CO1, CO2 9 To perform load test on three-phase induction motor. CO1 10 To perform load test on three-phase induction motor. CO1, CO2 11 Practical related to single phase induction motor CO1, CO2 12 Practical related to single phase induction motor. CO1, CO2 13 Practical related to single phase induction motor. CO1, CO2 14 To perform load test on single-phase induction motor. CO1	3									
Outcomes CO2: Determination of various performance characteristic of induction motor CO3: Experimentally perform speed control of induction motor CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on armature current and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternator. 7 Course Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping 1 Practical based on three phase induction motor. CO1 7 To perform no-load and blocked rotor tests on three-phase induction motor. CO1 1 To perform load test on three-phase induction motor. CO1 1 To perform load test on three-phase induction motor. CO1, CO2 generator. 1 To start single-phase induction motor CO1, CO2 inductand the concept is direction of rotation 1 To perform no-load and blocked rotor tests on single-phase induction motor. CO1 1 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 induction motor. 2 To start single-phase induction motor. CO1, CO2 induction motor. CO1, CO2 induction motor. 2<				procedures on						
Description The course covers practical experiment on three phase induction motor, single phase induction motor and synchronous machines. 8 Outline syllabus CO Mapping Unit 1 Practical based on three phase induction motor CO1 1 Operform no-load and blocked rotor tests on three-phase induction motor. CO1 1 To perform load test on three-phase induction motor. CO1 1 Operform load test on three-phase induction motor. CO1 1 Operform load test on three-phase induction motor. CO1 1 Practical related to single phase induction motor CO1, CO2 1 Operform no-load and blocked rotor tests on single-phase induction motor CO1, CO2 1 Operform load test on single phase induction motor CO1, CO2 1 Operform no-load and blocked rotor tests on single-phase CO1, CO2 1 Operform no-load and blocked rotor tests on single-phase CO1, CO2 1 Operform load test on single-phase induction motor. CO1, CO2 1 Operform load test on single-phase induction motor. CO1, CO2 1 Operform load test on single-phase induction motor CO1, CO2 1 Operform speed control of induction motor <td>6</td> <td></td> <td>CO2: Determination of various performance characteristic of i CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on arm and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternato</td> <td>nduction motor ature current r.</td>	6		CO2: Determination of various performance characteristic of i CO3: Experimentally perform speed control of induction motor CO4: Understand the effect of variation of field current on arm and power factor of a synchronous motor. CO5: Understand the concept of parallel operation of alternato	nduction motor ature current r.						
Unit 1 Practical based on three phase induction motor CO1,CO6 To perform no-load and blocked rotor tests on three-phase induction motor CO1,CO6 To perform load test on three-phase induction motor. CO1 To obtain the characteristic of three-phase induction motor. CO1,CO2 generator. CO1,CO2 Unit 2 Practical related to single phase induction motor To start single-phase induction motor CO1,CO2 and capacitor and to reverse its direction of rotation CO1,CO2 To perform load test on single-phase induction motor. CO1,CO2 To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1,CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1,CO2 To perform load test on single-phase induction motor. CO1,CO2 Unit 3 Practical related to speed control of induction motor using v/f method. CO3,CO6 To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3		Description	phase induction motor and synchronous machines.	-						
To perform no-load and blocked rotor tests on three-phase induction motorCO1,CO6To perform load test on three-phase induction motor.CO1To obtain the characteristic of three-phase induction generator.CO1, CO2 generator.Unit 2Practical related to single phase induction motorCO1, CO2To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotationCO1, CO2To perform no-load and blocked rotor tests on single-phase induction motor.CO1, CO2To perform no-load and blocked rotor tests on single-phase induction motor.CO1, CO2To perform load test on single-phase induction motor.CO1, CO2To perform load test on single-phase induction motor.CO1, CO2To perform speed control of induction motorCO3,CO6Unit 3Practical related to speed control of induction motor using v/f method.CO3,CO6To perform speed control of three-phase slip-ring induction motor by varying rotor resistanceCO3	8	· · · · · ·		CO Mapping						
induction motor CO1 To perform load test on three-phase induction motor. CO1 To obtain the characteristic of three-phase induction CO1, CO2 generator. CO1 Unit 2 Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 To perform speed control of induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 using v/f method. To perform speed control of three-phase slip-ring induction motor CO3 To perform speed control of three-phase slip-ring induction		Unit 1	· · · · · · · · · · · · · · · · · · ·							
To perform load test on three-phase induction motor. CO1 To obtain the characteristic of three-phase induction generator. CO1, CO2 Unit 2 Practical related to single phase induction motor CO1, CO2 To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 To perform speed control of induction motor. CO1, CO3, CO6 Unit 3 Practical related to speed control of induction motor To perform speed control of three-phase induction motor CO3, CO6 Unit 3 Practical control of three-phase slip-ring induction motor CO3 CO3				CO1,CO6						
To obtain the characteristic of three-phase induction generator. CO1, CO2 Unit 2 Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Unit 3 Practical related to speed control of three-phase slip-ring induction motor CO3,CO6 To perform speed control of three-phase slip-ring induction				CO1						
generator. Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Using v/f method. To perform speed control of three-phase slip-ring induction motor CO3 CO3										
Unit 2 Practical related to single phase induction motor To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor using v/f method. CO3,CO6 To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3				01,002						
To start single-phase induction motor using auxiliary winding and capacitor and to reverse its direction of rotation CO1, CO2 To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Unit 3 To perform speed control of three-phase induction motor To perform speed control of three-phase slip-ring induction CO3		Unit 2								
and capacitor and to reverse its direction of rotation To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 To perform speed control of three-phase slip-ring induction motor CO3 To perform speed control of three-phase slip-ring induction CO3				CO1. CO2						
To perform no-load and blocked rotor tests on single-phase induction motor. CO1, CO2 To perform load test on single-phase induction motor. CO1, CO2 Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor CO3,CO6 Unit 3 To perform speed control of three-phase slip-ring induction motor CO3,CO6 To perform speed control of three-phase slip-ring induction CO3 CO3										
Unit 3 Practical related to speed control of induction motor CO1, CO2 Unit 3 Practical related to speed control of induction motor CO3,CO6 Unit 3 To perform speed control of single-phase induction motor CO3,CO6 Unit 3 To perform speed control of three-phase slip-ring induction CO3,CO6 Unit 5 To perform speed control of three-phase slip-ring induction CO3				CO1, CO2						
Unit 3 Practical related to speed control of induction motor To perform speed control of single-phase induction motor using v/f method. CO3,CO6 To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3			induction motor.							
To perform speed control of single-phase induction motor using v/f method.CO3,CO6To perform speed control of three-phase slip-ring induction motor by varying rotor resistanceCO3			To perform load test on single-phase induction motor.	CO1, CO2						
using v/f method. To perform speed control of three-phase slip-ring induction motor by varying rotor resistance CO3		Unit 3								
motor by varying rotor resistance										
				CO3						
		Unit 4	Practical related to Synchronous machine							



					Beyon					
				n of field current on armature synchronous motor.	CO4					
		To perform op generator	en-circuit and sh	ort-circuit tests on synchronous	CO4					
U	nit 5	Practical rela generator	ated to paralle	l operation of synchronous						
		To carry-out pagenerators	To carry-out parallel operation of three-phase synchronous generators							
	Iode of xamination	Jury/Practical								
W	Veightage	CA	MTE	ETE						
D	istribution	60%	0%	40%						
Te	ext book/s*		nes by I.J. Nagrat rs ISBN 1259081	th & D.P. Kothari, Tata Mc Graw 532 2010						
0	ther	3. A.E.	Fitzgerald and	C. Kingsley, "Electric						
R	eferences	Machi	inery", New Yo	ork, McGraw Hill Education,						
		2014.	ISBN:9780071	326469, 0071326464						
		2. A. I								
		"Perfo								
		Publis	hers, 2004. ISE	3N:9780852268131,						
			68130							

Course Articulation Matrix:

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	3	3	2	3			2			3	3	3
CO2	3	2	2	2	3	2	3			2			2	2	3
CO3	3	3	2	2	2	2	2			2			3	3	2
CO4	3	2	3	2	3	2	2			2			2	3	3
CO5	3	2	2	2	3	2	2			2			2	2	3
CO6	3	3	2	2	3	2	2			2			3	2	2
	3.00	2.33	2.17	2.17	2.83	2.00	2.33			2.00			2.50	2.50	2.67



Sak	ool: SET		Beyon							
	gram: B.Tech nch: EEE	Semester: IV								
	Course Code	EEE225								
1										
2	Course Title	ELECTRICAL AND ELECTRONICS MEASUREMENTS								
3	Credits	3								
4	Contact	3-0-0								
	Hours									
	(L-T-P)	Demontració								
5	Course Status									
5	Course	• To discuss about basic instrument and measurement system	n							
	Objective	• To identify basic structure of electrical meters								
		• To study techniques of RLC measurement								
		• To explain different principle of special instruments								
		• To get knowledge and discuss on basic industry sensors ar	nd transducers							
6	Course	After completion of this course students will be able to:								
	Outcomes	CO1: Getting knowledge of basic instrument and measureme	ent systems							
		CO2: Applying knowledge and concept on construction of d	•							
		electrical meters								
		CO3: Analyzing concepts of RLC measurements								
		CO4: Understanding knowledge of construction of CRO wor	rking and							
		other special instruments								
		CO5: identifying principles and applications of different industry sensors								
		CO6: Studying applications of instruments in industry Instrumentation field is very important in industry field. Internal details of								
7	Course									
	Description	different types of analog and digital instruments will be discussed								
		find the suitable instrument for a particular application can be do								
		student after going through this subject. Some of special instrume								
		and workbench instrument details will be discussed. Basics of ser	isors and their							
8	Outline syllabu	applications are explained	CO Mapping							
0	Unit 1	Philosophy Of Measurement	CO Mapping							
	A	Methods of Measurement, Measurement System, Classification	C01,C06							
	A	of instrument system	01,000							
	В	Characteristics of instruments & measurement system	CO1							
	C	Errors in measurement & its analysis, Standards.	C01							
	Unit 2	Analog Measurement of Electrical Quantities	001							
	A A	Electrodynamic ,Thermocouple, Electrostatic & Rectifier type								
		Ammeters & Voltmeters								
	В	Different types of wattmeters, measurement of power in single CO2,CO6								
		phase and three phase								
	С	Different types of energy meters, measurement of energy in	CO2							
		single phase and three phase	_							



TL 14 0				🥆 🥟 Ве					
Unit 3			and Instrument transformers						
А	Measurement I megger	resistance (low,	, medium & high) using bridge and	CO3,CO6					
В	Measurement of	of inductance 8	capacitance using AC bridges	CO3					
С	Instrument trar	nsformers: CT 8	k PT	CO3					
Unit 4	CRO, DSO & Sp	CRO, DSO & Special Instruments							
А	CRO, DSO block	CRO, DSO block diagram, working principle, basic							
	measurements	, testing of com	ponents using CRO;						
В	Electronic mult	imeter, digital ı	multimeter; Digital tachometer;	CO4					
	Digital frequent	Digital frequency meter							
С	Harmonic analy	Harmonic analyzer; wave analyzer; distortion analyzer Sensors and Transducers							
Unit 5	Sensors and Tra								
А	Sensors and tra	insducers classi	fication; Temperature sensors	CO5, CO6					
	types and work	ing principle;							
В	Pressure senso	rs types and w	orking principle; Flow sensors	CO5					
	types and work	ing principle;							
С	Displacement s	ensors types ar	nd working principle; Calibration	CO5					
	of sensors								
Mode of	Theory								
examination	-								
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*	Ŭ	rument", A.W. 14311, 818561 nd Transdu	acers by <u>D. Patranabi</u>						
References	W.D.Cooper," I Fechnique "Pre ISBN:9798129 A.K. Sawhney,"El nstrument", Dha								



Course Articulation Matrix

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2	2	1	1		-	-	2	3	3	3
CO2	3	3	3	3	3	3	-	2	2			2	3	3	3
CO3	3	3	2	3	3	3	-	2	2	-	1	2	3	3	3
CO4	3	3	3	2	3	1	-	2	2	1	-	3	3	3	3
CO5	3	3	3	2	3	-	1	1	1	-	1	3	3	2	3
CO6	3	2	2	2	2							1	2	2	3
	3.00	2.83	2.50	2.33	2.67	2.25	1.00	1.60	1.75	1.00	1.00	2.17	2.83	2.67	3.00

SU/SET/B. Tech./EEE



Sch	lool:								
	gram:								
Bra	unch:	Semester:4							
1	Course Code	EEP225							
2	Course Title	Electrical & Electronics Measurements Lab							
3	Credits	1							
4	Contact Hours	0-0-2							
	(L-T-P)								
	Course Status	Compulsory/Elective							
5	Course Objective	 To know calibration and diagnosing problem instruments To measure and read unknown electrical compone meters and bridges To measure electrical parameters like voltage, free CROs 	nts value using						
		 To know characteristics of sensors and transducers 							
		 To know constructions of analog and digital insturn 	nents						
6	Course	CO1: Getting knowledge of basic instrument and measurer							
0	Outcomes	CO2: Applying knowledge and concept on construction of electrical meters CO3: Analyzing concepts of RLC measurements CO4: Able to select proper sensors to sense a parameter CO5: Understanding knowledge of construction of CRO w other special instruments	different						
		CO6: Finding applications of instruments							
7	Course Description	This course gives idea about how to use different types of r measurements. Some experiments give practice of RLC me using AC & DC bridges. One section gives practice of mea using CRO. The last two sections about sensors and case st	easurement surement						
8	Outline syllabus		CO Mapping						
	Unit 1	Calibration							
	А	Calibration of voltmeter and ammeter	CO1,CO6						
	В	Measurement of RMS, average and form factor using rectifier and meters	CO1						
	С	Calibration of wattmeter and energy meter	CO1						
	Unit 2	RLC Bridges							
	A	DC Bridge for R measurement	CO2,CO6						
	B	AC Bridge for L measurement	CO2						
	C	AC Bridge for C measurement	CO2						
	Unit 3	CRO and DSO							
	A	Identifying of controls and functions switches on CRO & DSO	CO3,CO6						
	В	Measurements using CRO	CO3						
	Ē	Measurements using DSO	CO3						
	SETTER Tech./EEE	Sensors Characteristics	+						

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														yond Bou	ndaries
	А		C	haracte	ristics	of temp	peratur	e senso	or			CO4	,CO6		
	В		C	haracte	ristics	of force	e senso	or				CO4	-		
	С		C	haracte	ristics	of disp	laceme	ent or fl	low ser	isor		CO4	-	<u>C</u>	<u>OUR</u>
	Unit 5	5	C	ase stu	dy of]	Instrur	nents							SE	E
	А	A Digital Energy Meter										CO5	,CO6		RTI
	B Digital Temperature Meter									CO5	i		ULA		
			D	igital N	Iultim	eter									ION
	Mode	of	P	ractical	& Viv	'a									
	exami	nation												$-\frac{\mathbf{M}}{\mathbf{IC}}$	<u>ATR</u>
	Weigh	ntage	C	A	l	MTE		ETE							<u></u>
	Distri	bution	6)%	()%		40%							
	Text b	ook/s*	R	efer lab	manu	als									
	Other														
	Refere	ences													
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	2	2	2	2	1	1		-	-	2	3	2	2
CO2	3	3	3	3	3	3	-	2	2			2	3	3	2
CO3	3	3	2	3	3	3	-	2	2	-	1	2	3	3	1
CO4	3	3	3	2	3	1	-	2	2	1	-	3	3	3	2
CO5	3	3	3	2	3	-	1	1	1	-	1	3	3	2	2
CO6	3	2	2	2	2							1	2	2	1
	3.00	2.83	2.50	2.33	2.67	2.25	1.00	1.60	1.75	1.00	1.00	2.17	2.83	2.50	1.67



V TERM

SU/SET/B. Tech./EEE



C -l	l. CET										
	ool: SET										
	gram: B.Tech nch: EEE	Semester:V									
1	Course Code	EEE330									
2	Course Title	Control Systems									
3	Credits	3									
4	Contact Hours	3-0-0									
	(L-T-P)										
	Course Status	Compulsory									
5	Course	Control Systems is the study of the analysis and regulation	of the output								
5	Objective	behaviors of dynamical systems subject to input signals. Th									
	Objective	tools discussed in this course can be used in a wide									
		engineering disciplines. The emphasis of this course will and feedback controller design methods for linear									
		-	time-invariant								
6	Course	systems. CO1:Apply transfer function models, signal flow graphs and	t block								
0	Outcomes	diagram algebra to obtain the transfer function of a give									
	Outcomes	CO2: Obtain system response in time domain	ven system								
		CO3: Design a closed-loop control system to satisfy dynam	ic performance								
		specifications using frequency response									
		CO4:Analyze closed-loop control systems for stability and steady-state									
		performance									
		CO5: Design simple feedback controllers and compensators to meet									
		desired performance specifications CO6: Apply different types of analysis and explain the nature of stability									
		of any given linear system									
7	Course	This course shall introduce the fundamentals of modeling	and control of								
	Description	linear time invariant systems. The course will be useful for students from									
		major streams of engineering to build foundations of									
		analysis of systems as well as the feedback control of such s	ystems.								
8	Outline syllabu		CO Mapping								
	Unit 1	Introduction to Control Problem									
	А	Feedback Control: open-loop and closed-loop systems,	CO1,CO6								
	benefits of feedback,block diagram algebra										
	В	Mathematical models of physical systems, signal flow	CO1								
		graph									
	C Unit 2	Transfer function models of linear time-invariant systems	CO1								
	Unit 2 A	Time Response Analysis Standard tast signals, time response of first order systems CO2									
	A	Standard test signals, time response of first order systems CO2 for standard test inputs									
	В	Time response of second order systems for standard test CO2									
	U U	inputs CO2									
	С	Design specifications for second-order systems based on	CO2								
L		Design specifications for second order systems based on	0.02								

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~~	<u>Beyon</u> d Boundaries

	the time-response					
Unit 3	Frequency Resp	oonse Ana	alysis			
Α	Introduction and	frequency	y domain specifications	CO3		
В	Correlation betw	een frequ	ency domain and time domain.	CO3		
С	Polar plot and B	ode plot		CO3,CO6		
Unit 4	Stability of Con					
А	Concept of stabil	lity		CO4		
В	Characteristic ec stability, Routh H	CO4				
С	Root-locus techr	CO4				
Unit 5	Modern Contro					
А	Lag, lead, lag-lea criteria	CO5,CO6				
В	Concepts of state variables and state space model.					
С	Solution of state observability.	CO5				
Mode of examination	Theory					
Weightage	CA N	ITE	ETE			
Distribution	30% 2	0%	50%			
Text book/s*	1991. ISBN:9 2. M. Gopal, "C	78013589 ontrol Sys	ntrol Engineering", Prentice Hall, 91285, 0135891280 stems: Principles and Design", n, 1997. ISBN:9780070482890,			
Other References	Engineering" ISBN:978812 2. B. C. Kuo, "A	, New Ag 22417753, Automatic	opal, "Control Systems e International, 2009 , 8122417752 Control System", Prentice Hall, 34763, 0471134767			



COURSE ARTICULATION MATRIX:

	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	2	-	-	-	1	1	-	-	2	3	3
CO2	3	3	3	2	3	-	-	-	1	1	-	-	3	3	3
CO3	3	3	3	2	3	-	-	-	1	1	-	-	2	3	2
CO4	3	3	3	2	3	-	-	-	1	1	-	-	2	3	3
CO5	3	3	3	2	3		-	-	1	1	-	-	2	3	3
CO6	3	3	3	2	3	-	-	-	1	1	-	-	3	3	3
	3.00	3.00	3.00	2.00	2.83				1.00	1.00			2.33	3.00	2.83

SU/SET/B. Tech./EEE

		* SH	ARDA
			d Boundaries
_	chool: SET rogram: B.		
	ech.		
	ranch: EEE	Semester: 05	
1	Course	EEE331	
	Code		
2	Course	Power System-I	
-	Title		
3	Credits	3	
4	Contact Hours	3-0-0	
	(L-T-P)		
	Course	Compulsory	
	Status		
		To provide students with the ability of:	
		 understanding of the basic components of Power System and then analyze 	
		the system using the technique of per unit system. Also introducing the	
5	Course	students to cables, insulators and the corono phenomena which occurs in	
0	Objective	transmission system	
		 representing the transmission system with the help of their equivalent 	
		circuits	
		 calculating various design parameters of transmission lines 	
		On successful completion of this course students will be able to	
		CO1: assimilate necessary fundamental knowledge of different power system elements	
		CO2: Apply concepts from basic electromagnetics to determine the inductance,	
		capacitance, and resistance of three-phase transmission lines, including lines	
6	Course	with conductor bundling .	
0	Outcomes	CO3: Derive the model for short, medium and long transmission lines	
		CO4: Analyse the mechanical and electrical design aspects of transmission system	
		CO5: Analyse different types of distribution systems and its design.	
		CO6: Examine the various design features of overhead transmission lines	
7	Course	This course will cover major topics of power engineering and intended to deliver basic knowledge of fundamentals of power systems including	
/	Description	transmission, and distribution of electrical power. Course will guide students to	
		design transmission line having perfect sag and insulator design and minimum	
L		o month and the manual states of the month of the manual states of the manual states of the manual states of the manual states of the states o	l

	corona loss.	
Outline	syllabus	CO Mapping
Unit 1	Fundamentals of Power System	
А	Single phase transmission, three phase transmission, basic	CO1,CO6
	components of a power system.	
В	Need of EHV Transmission	CO2
С	Types of Distribution System	CO1, CO2
Unit 2	Transmission Line Constants and Performance	,
A	Inductance of solid, stranded and bundled conductors, symmetrical and unsymmetrical spacing and transposition,	CO1, CO3, CO6
	application of self and mutual GMD	
В	Capacitance of solid, stranded and bundled conductors, Symmetrical and unsymmetrical spacing and transposition,	CO1, CO3
	application of self and mutual GMD	
С		CO4
	Characteristics and performance of lines - short line, medium line and long line; equivalent circuits, ABCD constants, Ferranti effect.	
Unit 3	Corona, Interference and Insulated Cables	
A	Critical disruptive voltage and visible disruptive voltage, corona loss, line design based on corona, advantages and disadvantages of corona.	CO1, CO2, CO5
В	Skin and proximity Effects, Interference with neighbouring communication circuits and Radio Interference.	CO1, CO2, CO5
С	Insulation, Shielding and Armouring of cables, types of cables, EHV cables, insulation resistance, capacitance and loss angle, capacitance grading, heating of cables, current rating	CO1, CO2, CO5
Unit 4	Mechanical Design of Transmission Lines	
A	Catenary curve, sag-tension calculations, supports at different levels	CO1, CO2, CO5
В	Stringing chart, sag template, equivalent span, vibration and vibration dampers.	CO1, CO2, CO5
С	Types, voltage distribution in insulator string and grading, methods of equalizing potentials.	CO1, CO2, CO5
Unit 5	HVDC Transmission	
А	Components of HVDC transmission system, Comparison of AC and DC transmission.	CO5,CO6
В	Application of DC Transmission	CO5
C	Types of HVDC links	CO5
Mode	Theory	
of		

)A



				Beyon						
examin ation										
 Weight	СА	MTE	ETE							
age Distrib ution	30%	20%	50%							
Text book*	•	J.Nagrath and D.P.Kothari, "Power System Engineering", Tata McGraw- Hill Publishers. ISBN:9789353165123, 1353165121								
Other Referen ces		a, "Electrical Powe ISBN:97881224177	r Systems", New Age International 739, 8122417736							

COURSE ARTICULATION MATRIX:

	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	2	1	-	-	-	1	1	-	-	3	3	2
CO2	2	2	1	2	1	-	-	-	1	1	-	-	3	2	2
CO3	3	3	1	2	2	-	-	-	1	1	-	-	3	2	2
CO4	2	2	1	1	2	-	-	-	1	1	-	-	3	3	2
CO5	2	2	1	1	2	-	-	-	1	1	-	-	3	3	1
CO6	3	2	1	2	2	-	-	-	1	1	-	-	3	2	2
	2.50	2.33	1.00	1.67	1.67				1.00	1.00			3.00	2.50	1.83



	ool: SET											
	gram: B. Tech.											
	nch: EEE	Semester: 05										
1	Course Code	EEP331										
2	Course Title	Power System-1 Lab										
3	Credits	1 0-0-2										
4	Contact Hours (L-T-P)											
	Course Status	Compulsory										
5	Course Objective	 To provide students with the ability of: understanding of the basic components of Power System analyze the system using the technique of per unit syste introducing the students to cables, insulators and the comphenomena which occurs in transmission system representing the transmission system with the help of the circuits calculating various design parameters of transmission li 	m. Also rono eir equivalent									
6	Course Outcomes	On successful completion of this course students will bCO1:design three-phase power system model in PSCAD softwCO2:design of transmission lines of specified parametersCO3:analyse Ferranti Effect in transmission lineCO4:derive the model for short, medium and long transmissiCO5:examine the various design features of overhead transmissionCO6:do fault analysis in transmission and distribution sys	e able to vare on lines nission lines									
7	Course Description	This course will cover major topics of power engineering a deliver basic knowledge of fundamentals of power syst transmission, and distribution of electrical power. Cour students to design transmission line having perfect sag design and minimum corona loss.	ems including rse will guide									
8	Outline syllabus											
	Unit 1	Practical based on fundamentals of Power System										
	A	To design single-phase power system model consisting of generator, transformer, transmission line and motors in PSCAD	CO1,CO6									
	В	To design three-phase power system model consisting of generator, transformer, transmission line and motors in PSCAD	CO2									



C	To design diff	ferent types	of distribution systems and to	CO1, CO2
	measure volta PSCAD	ages and curr	rents at different feeder point in	n
Unit 2		ed on trans	mission line constants and	
	performance		mission mic constants and	
A	-		f transmission line using line	CO1,
	data in MATI			CO3,CO6
В			of transmission line using line	CO1, CO3
	data in MATI		C	,
С	To determine	ABCD para	meters in transmission line kit	CO4
Unit 3			ona, Interference and	
	Insulated Ca		<i>,</i>	
А	To plot a grap	oh between c	ritical disruptive voltage,	CO1, CO2
			r radius vs corona loass in	CO5
	MATLAB			
В	To examine F	Ferranti effec	t in transmission line kit.	CO1, CO2
				CO5
С				CO1, CO2
	To determine	e the location	n of fault in a cable using cable	e CO5
	fault locator.	•		
Unit 4			hanical Design of	
	Transmission			
A		sag taking re	quired inputs from user in	CO1, CO2
	MATLAB			CO5
В	To plot string	ing chart and	d sag template in MATLAB	CO1, CO2
		8	B I III	CO5
С	To determine	the string ef	ficiency of insulating disc	CO1, CO2
-		8		CO5
Unit 5	Practical rela	ated to HVI	OC Transmission	
Α	To design a re			CO5,CO6
В	To design an			CO5
С	0		DC system in PSCAD	CO5
Mode of	Practical	1	•	
examination				
Weightage	CA	MTE	ETE	
Distribution	60%	0%	40%	
Text book/s*	I.J.Nagrath ar	nd D.P.Kotha	ari, "Power System	
			aw- Hill Publishers.	
	ISBN:978935			
Other References	2. C.L.Wad	ge		
itereneus	Internatio	39,		
	8122417	736		
	0122 117	,		



COURSE ARTICULATION MATRIX:

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	2	-	-	1	1	-	-	-	3	3	3
CO2	2	3	3	2	2	-	-	1	1	-	-	-	3	3	3
CO3	3	2	2	2	2	-	-	1	1	-	-	-	3	3	3
CO4	2	1	2	2	2	-	-	1	1	-	-	-	3	3	3
CO5	2	2	1	2	3	-	-	1	1	-	-	-	3	3	3
CO6	3	2	1	2	3	-	-	1	1	-	-	-	3	3	3
	2.50			2.00	2.33			1.00	1.00				3.00	3.00	3.00

SU/SET/B. Tech./EEE



~ -			Beyon							
	ool: SET									
	gram: B.Tech									
	nch: EEE/EE	Semester: V								
1	Course Code Course Title	EEE332								
23	Course Thie Credits	Power Electronics 3								
4	Contact	3-0-0								
-	Hours	5-0-0								
	(L-T-P)									
	Course Status	Compulsory								
5	Course	1. Analysis of modern power semiconductor devices, their	strengths, and							
	Objective	their switching and protection techniques								
		2. Ability to analyze various important topologies of power	converter							
		circuits for specific types of applications including contro	lled and							
		uncontrolled rectifiers, DC-DC converters and inverters								
		3. Ability to understand and analyze the qualities of wavefo	rms at input							
		and output ends of these converters								
6	Course	On successful completion of this course students will be able	e to							
	Outcomes									
		CO1: summerise the characteristics and principle of operation	of different							
		types of semiconductor switches								
		CO2: "analyse the principles of operation of silicon controlled rectifiers.								
		CO3: Analyse controlled rectifier circuits								
		CO4: Analyse the operation of DC-DC choppers								
		CO5: Analyse the operation of voltage source inverters.								
		CO6: Classification of different type of controller								
7	Course									
	Description	Power electronics is the application of solid-state elect	ronics for the							
	_	control and conversion of electrical power. During the cou	rse it is taught							
		that how in modern system the conversion is pe								
		semiconductor switching device such as SCR, MOSFET, IG	BT, and GTO.							
8	Outline syllabu	IS	CO Mapping							
	Unit 1	Power Semiconductor Devices								
	A	Thyristors : Silicon Controlled Rectifiers (SCR's) , BJT, power	CO1							
		MOSFET, power IGBT, TRIAC and their characteristics								
	B	Gate characteristics of SCR, turn on and turn off methods.	CO1							
	C	Series and parallel operation of SCRs, line commutation and	CO1							
	Unit 2	forced commutation circuits. Phase Controlled Converters								
	Unit 2 A	Phase Controlled Converters Principle of phase control, circuit, waveform and analysis of	CO2 CO6							
L	A SET/D Toch /EEE		CO2, CO6							



	single phase ha	If wave and ful	l wave line commutated						
	converters with	n R, RL, RLE load	1.						
В			s of three pulse and six pulse	CO2					
	converters with								
С	Operation of d	ual converter.		CO2					
Unit 3	Choppers								
А	Principle of ope	Principle of operation, time ratio control and current limit							
	control strateg	ies							
В	Circuit, operati	on and analysis	of Step down and step up	CO3					
	choppers.								
C	Types of chopp	Types of choppers: A, B, C, D and E choppers.							
Unit 4	Inverters								
А	Principle of ope	eration of single	e phase inverter, basic series	CO4					
	inverter bridge								
В	Three phase In	verter: 120 ⁰ and	d 180 ⁰ mode, circuit, operation	CO4					
	and analysis.								
С	Voltage contro	l techniques for	inverters, VSI & CSI and their	CO4					
	comparison.								
Unit 5	Other Applic	ations of Pow	er Electronics						
А	AC voltage con	trollers with R a	and RL loads.	CO5,CO6					
В	Cycloconverter	S		CO5					
С	UPS,SMPS, Ind	uction heating,	HVDC	CO5					
Mode of	Theory	0.							
examination	5								
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*			ics", Pearson Education; Fourth						
			7658, 0080467652						
Other									
References	1. Bose B								
	-		780310841, 0780310845						
	2. Sen P.C	C., "Power Elect	ronics", Mc.Graw Hill,2016.						
	3. Singh N	Л.D., Kanchand	ani K.B., "Power Electronics",						
	McGra	w-Hill, 2017. ISI	BN:9788126511013, 812651101X						
		,							



COURSE ARTICULATION MATRIX

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	3	-	-	-	1	1	-	-	3	3	3
CO2	2	2	3	2	3	-	-	-	1	1	-	-	3	3	2
CO3	3	3	3	2	2	-	-	-	1	1	-	-	3	3	3
CO4	2	2	3	3	2	-	-	-	1	1	-	-	3	3	2
CO5	2	2	3	3	2	-	-	-	1	1	-	-	3	3	1
CO6	3	2	3	2	2	-	-	-	1	1	-	-	3	2	2
	2.50	2.33	3.00	2.33	2.33				1.00	1.00			3.00	2.83	2.17

SU/SET/B. Tech./EEE



Sch	ool: SET											
Program: B.Tech												
Bra	nch:EEE/EE	Semester: V										
1	Course Code	EEP332										
2	Course Title	Power electronics lab										
3	Credits	1										
4	Contact Hours (L-T-P)	0-0-2										
	Course Status	Compulsory										
5	Course Objective	Ability to analyze various important topologies of power converter circlypes of applications including controlled and uncontrolled rectifiers, I and inverters	•									
6	Course Outcomes	On successful completion of this course students will be able to										
		CO1: Analysis of different power electronic devices.										
		CO2: study of characteristics of SCR, BJT, MOSFET and IGBT										
		CO3: eperimental verification of the design and control of rectifiers, inverters.										
		CO4: Experimental study of different communication methods										
		CO5: Experimental verification the DC-DC chopper circuit										
		CO6: Design and Experiment of AC voltage controller and Cyclo Converter										
7	Course											
	Description	Electronic power conversion is vital in modern electrical energy systems and device The primary goal of the course is to give students an in-depth laboratory experience the design, operation, characterization, and application of electronic circuits for conversion and control of electrical energy.										
8	Outline syllabus	 }	CO Mapping									
	Unit 1	Power Semiconductor Devices										
	А	To obtain VI Characteristics of SCR.	CO1									
	В	To control the thyristor using different gate firing circuits.	CO1									
	Unit 2	Phase Controlled Converters										
	A	To observe the output voltage waveforms and to find the average and rms output voltages of a single phase half controlled converter with R load.										
	В	To observe the output voltage waveforms and to find the average and rms output voltages of a three-phase half controlled bridge converter with R-load.	CO2									

					* SHARD			
С	To observe the of and rms output converter with f	CO2						
Unit 3	Choppers							
А		To observe the output voltage waveforms and to find the average voltage of a voltage commutated chopper.						
В	Simulation of st							
Unit 4	Inverters							
A	To observe the overlapped to observe the overlapped to observe the other strength to observe the	CO4						
В	Simulation of th		CO4					
Unit 5	AC voltage cont							
А	To observe the overlapped to t	• •	•	CO5,C06				
В	Simulation of A	C voltage contr	ollers with R and R	loads	CO5,CO6			
Mode of examination	Viva-voce							
Weightage	СА	MTE	ETE					
Distribution	60%	00%	40%					
Text book/s*	Rashid M.D., " P							
Other References	1. Bose B.I ISBN:97							
	2. Sen P.C.							
	3. Singh M McGraw							

COURSE ARTICULATION MATRIX

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	1	1	1	2	1			1			1	1	2
CO2	3	2	1	1	2	1	2			1			1	1	2
CO3	2	3	3	2	2	2	2			1			3	3	3
CO4	3	3	3	3	2	1				1			3	3	2
CO5	3	3	3	3	2	2	2			1			3	3	3
CO6	3	3	3	2	2	2	2			1			3	3	3
	2.83	2.67	2.33	2.00	1.83	1.67	1.80			1.00			2.33	2.33	2.50



VI TERM

SU/SET/B. Tech./EEE



Bra	anch:EEE	Semester:VI	
1	Course Code	EEE334	
2	Course Title	Switchgear and Protection	
3	Credits	3	
4	Contact Hours (L-T-P)	3-0-0	
	Course Status	Compulsory	
5	Course Objective	The objective of the course is to expose students to the tech protecting the various subsystems of a power system during operation and also under fault condition. The students will a acquainted with the techniques to coordinate these protectin systems	g their normal also be
6	Course Outcomes	 CO1:Understand the basic terminologies related to power system faults for balanced and conditions. CO2: compare the protection techniques used for protection power system components CO3:Identify, apply, and calculate settings for transformers and transmission line protection schemes. CO4: discuss the theory of circuit interruption and physical phe CO5: Identify the challenges and solutions to industrial por protection problems. CO6 An ability to develop protection schemes/algorithms components of power system. 	d unbalanced n of different , generators nomena of arc wer system s for all
7	Course Description	Reliability of electrical energy systems to a large extent is of the reliability of its protection system. Basic building protection system are fuses, over current and distar differential protection schemes. In this course, we will principles and applications to apparatus and system protection	g blocks of the nee relays and introduce their
8	Outline syllabu	15	CO Mapping
	Unit 1	Introduction to Power System Protection	
	A	Nature and causes of faults on power system elements need of protection.	CO1,CO6
	В	Zones of protection, essential qualities of protection, primary and backup protection	CO1
	С	CTs and VTs and their applications in protection.	CO1
	Unit 2	Operating Principles and Construction of Relays	
	A	Principle of various Electromagnetic relays and their constructions.	CO2
	В	over-current, directional, differential and distance relays and their operating characteristics	CO2
	С	Introduction to digital/numerical relays and Intelligent	CO2



	Electronic Dev	vice (IED) rela	lys			
Unit 3	Protection of		-			
A	Faults on trar againstextern protection ag	asformers and a al faults, prote a a faults, prote	its protection: protection ection against internal faults, inrush, concept of lightning	CO3,CO6		
В	Faults on Ger Stator protect stator-overhe protection,los	nerator and its tion, protection ating, Rotor pr as of excitation	against inter-turn faults, rotection, field ground-fault protection, overvoltage	CO3		
С	protection, overspeed protection.CFaults on transmission lines and its protection: wire pilot protection, carrier current protection					
Unit 4	Theory of Circu	it Interruption				
А	Physics of arc	phenomena ar	nd arc interruption.	CO4		
В	Restriking vol recovery volta	-	ry voltage, rate of rise of	CO4		
С	Resistance swi capacitive curr	•	t chopping, interruption of	CO4		
Unit 5	Circuit Break	xers				
А	Types of circu	it breakers,		CO5,CO6		
В		and vacuum c	onstruction of air-break, air ircuit breakers, their merits and	CO5		
С	Concept of HV		eaker.	CO5		
Mode of examination	Theory					
Weightage	CA	MTE	ETE			
Distribution	30%	20%	50%			
Text book/s*	 Badri Ran Protection publishin ISBN:978 C.L Wadl 	n & Switchgea g company ltd 30071077743, hwa, 'Electrica nal (p) limited				
Other References	Bhavesh Bhalj "Protection an ISBN:9780199	d Switchgear"				



Course Articulation Matrix:

	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	1			3			3			1	1	1
CO2	3	3	3	2			2			3			1	2	1
CO3	3	3	3	2						3			3	3	2
CO4	3	3	3				3			3			2	2	1
CO5	3	3	3							3			2	3	2
CO6	3	3	2	2			3			3			1	1	2
	3.00	3.00	2.83	1.75			2.75			3.00			1.67	2.00	1.50

SU/SET/B. Tech./EEE



Sch	nool: SET									
Pro	ogram: B.Tech									
Bra	anch: EEE	Semester: VI:								
1	Course Code	EEP335								
2	Course Title	Power System-II Lab								
3	Credits	1								
4	Contact Hours (L-T-P)	0-0-2								
	Course Status	Compulsory								
5	5 Course Objective The objective of the course is to expose students to the techniques of protecting the various subsystems of a power system during their norm operation and also under fault condition. The students will also be acquainted with the techniques to coordinate these protecting devices a systems									
6	Course Outcomes	 CO1: Exposure to the modeling of individual power system contransmission lines and generators CO2: Formulate the load flow problems using various methods CO3: Perform the numerical and phasor analysis of fault occur power system and calculate current and voltages in faulted power CO4: Perform stability analysis using various methods CO5: Identify and employ the methods to control real and real 	ds irrences in ver system.							
		and frequency and voltage of power system CO6: Analyse of stability, security and control of power system	m							
7	Course Description	Reliability of electrical energy systems to a large extent is of the reliability of its protection system. Basic building protection system are fuses, over current and distant differential protection schemes. In this course, we will is principles and applications to apparatus and system protection	a consequence blocks of the ce relays and introduce their							
8	Outline syllabus	3	CO Mapping							
	Unit 1	Practical based on Power System Protection								
		To analyse the single-phase fault on a power system network using MATLAB/PSCAD	CO1							
		To analyse the Line-Line fault on a power system network using MATLAB/PSCAD	CO1							
		To analyse the three-phase fault on a power system network using MATLAB/PSCAD	CO1							
	Unit 1I	Practical based on Relays								
		To determine the operating characteristics of over-current relay.	CO2							
		To determine the operating characteristics of over-voltage relay.	CO2							



Unit III	Practical bas	sed on Pow	er Apparatus					
			ng characteristics of	inverse	CO2			
	definite mean	-	0					
			ng characteristics of	bimetallic	CO2			
	Thermal relay	-	0					
UniT IV	Practical bas	sed on Circ	uit Interruption					
	To obtain the characteristics of a circuit breaker during							
	circuit interru	circuit interruption in a power system using						
	MATLAB/PS	SCAD						
UNIT V	Practical bas							
	To study the working and application of ac circuit breaker							
	and dc circuit breaker							
Mode of	Practical							
examination								
Weightage	CA	MTE	ETE					
Distribution	60%	0%	40%					
Text book/s*	 Badri Ram, D.N.Vishwakarma, 'Power System Protection & Switchgear', TataMcGraw –hill publishing company ltd, New Delhi. ISBN:9780071077743, 007107774X C.L Wadhwa, 'Electrical Power Systems', New Age International (p) limited. ISBN:9788122417739, 8122417736 							
Other References	Bhavesh Bha "Protection a ISBN:978019	nd Switchg		G. Chothani,				

	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1								3			3	3	3
CO2	3	3	1	3						3			2	3	3
CO3	2	3	1	2						3			2	3	3
CO4	2	3	1	2						3			2	3	3
CO5	2	2	3		3					3			2	3	3
CO6	3	3	3	3	3					3			3	3	3
	2.50	2.50	1.80	2.50	3.00					3.00			2.33	3.00	3.00



	ool: SET									
	gram: B. Tech.									
Bra	nch: EEE	Semester: VI								
1	Course Code	EEE335								
2	Course Title	Power System-II								
3	Credits	3								
4	Contact Hours	3-0-0								
	(L-T-P)									
	Course Status	Compulsory								
	Course	To acquaint the students with the tools for performing p	ower flow							
5	Course	and fault analysis in power system and modern method	for control of							
	Objective	power flow through existing lines.								
		On successful completion of this course students will be able	e to							
		CO1: Exposure to the modeling of individual power system cor								
		transmission lines and generators								
		CO2: Formulate the load flow problems using various methods								
		CO3: Perform the numerical and phasor analysis of fault occur								
6	Course	power system and calculate current and voltages in faulted power	er system.							
U	Outcomes	CO4: Perform stability analysis using various methods								
		CO5: Identify and employ the methods to control real and reactive power								
		and frequency and voltage of power system								
		CO6: Analyse of stability, security and control of power system	1							
7	Course Description	This course will introduce and explain the fundamental of field of electrical power system engineering. The basic co- unit system will be introduced along with their application applications. Basic load flow algorithms will be cover in with short circuit analysis and the method of symmetrica Unbalanced fault analysis and basic power system stability also be covered in these lecture series. By the end of the students should be able to gather high quality knowledge power system components, its operation strategies, and stability	oncepts of per ons in circuit details along l components y analysis will ne course, the e of electrica							
8	Outline syllabus		CO Mapping							
	Unit 1	Review of Basic Concept								
	A	Representation of synchronous machine and transformer in	CO3, CO4							
		power system	<i>,</i>							
	В	Single line diagram, Impedance and Reactance Diagram	CO3, CO4							
	С	Per-unit system and its significance, change of base	CO3, CO4							
	Unit 2	Power Flow Analysis								
	А	Formation of bus admittance matrix (YBUS) using	CO1							
		inspection method and singular transformation method								
	В	Bus classifications, Solution of non-linear algebraic	CO1, CO2							
		equations	, -							
CI1 /0	ET/B. Tech./EEE	Gauss Seidel method, Newton Raphson method and Fast-	CO1, CO2							
30/3	EI/D. IECH./EEE	decoupled method (Algorithms and flow-charts),	,							

*	SHARDA
	UNIVEDCITY
	Beyond Boundaries

	comparison o	f the three me	hods	
Unit 3	Fault Analys	sis		
А	Types of faul	ts, Short circui	t capacity	CO1, CO3
В	Symmetrical	components of	f unsymmetrical phasor,	CO1, CO3
	Sequence imp	pedances, Sequ	ence networks	
С	Fault analysis	s of L-G, L-L	and L-L-G faults	CO1, CO3
Unit 4	Power System	m Stability		
A	rotor angle st	ability and vol	ons, Classification of stability, tage stability, Comparison of nic stability and transient	CO1, CO4
В			g equation, Equal area criteria, by step by step method	CO1, CO4
С	Factors influe		t stability, Techniques for	CO1, CO4
Unit 5		m Control and		
A	Concept of lo	ad frequency of	control	CO5
В	Methods of v	oltage control		CO5
С	Introduction t			CO5
Mode of examination	Theory			
Weightage	CA	MTE	ETE	
Distribution	30%	20%	50%	
Text book/s*			J., 'Modern Power System l Publishing Company Limited	
Other	1. Grainer J.J.	and Stevenso	n W.D., 'Power System	
References	Analysis' McC		-	
			n Analysis' McGraw Hill.	



COs	PO	PO	PO3	PO	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO
	1	2		4												
CO335. 1	3	1											3			3
CO335. 2	3	3	1	3									2			3
CO335. 3	2	3	1	2									2			2
CO335. 4	2	3	1	2									2			2
CO335. 5	2	2	3		3								2	3	2	2
CO335. 6	3	3	3	3	3								3	3		3
	2.5	2.5		2.5												
	0	0	1.80	0	3.00								2.33	3.00	2.00	2.50

SU/SET/B. Tech./EEE





PROGRAM ELECTIVES

SU/SET/B. Tech./EEE



SE	Т								
Pro	gram: B.Tech								
	nch: EEE/EE	Semester:							
1	Course Code	EEE444							
2	Course Title	HVDC and FACTS							
3	Credits	3							
4	Contact Hours	3-0-0							
	(L-T-P)								
	Course Status	Department Elective							
5	Course	To provide students with the ability of:							
	Objective	1. Comprehend the concept behind planning of HVDC transmis	ssion and						
		comparison with AC power transmission.							
		 Implementing control strategies for the power flow control Systems. 	in AC-DC						
		3. An thoughtful on the fundamentals of power flow control							
		4. An indulgent on the fundamentals of FACTS controllers							
6	Course	On successful completion of this course students will be able t	:0						
	Outcomes		_						
		CO1: Explain the objective and functions of different components of	•						
		CO2: Differentiate between different controls schemes for the control of DC link.							
		CO3: Analyzed the process of commutation failure and also understand the							
		techniques to protect the HVDC system against over-voltage and o	ver-currents.						
		CO4: Summarized the benefits of FACTS devices.							
		CO5: Describe principle of operation and configuration of FACTS de	vices						
		Acquire the knowledge of FACTS and HVDC system concept and general							
		CO6 Acquire the knowledge of FACTS and HVDC system concep system considerations	80.00						
		system considerations							
7	Course	This subject deals with the importance of HVDC transmission, analy	sis of HVDC						
	Description	Converters, Harmonics and Filters, Reactive power control and Pov	ver factor						
	1	improvements of the system. It also deals with basic FACTS concep	ts, static shunt						
		and series compensation and combined compensation techniques							
8									
	Unit 1	HVDC System Configuration and Components							
A Classification of HVDC links, components of HVDC transmission CO1 system.									
	В	Comparison of AC and DC Transmission, application of DC	C01,C06						
	U	Transmission.							
	С	Graetz Bridge, Choice of converter configuration, characteristics	CO1						
		of a twelve pulse converter.							
	Unit 2	HVDC System Control							



-	-			K Bey				
Α			trol implementation.	CO2,CO6				
В	-		nk, firing angle control, current and	CO2				
	extinction angle							
С	Harmonics and			CO2				
Unit 3	Converter Fault	onverter Faults and Protection						
А	Types of conver	pes of converter faults, commutation failure.						
В	DC line fault, AC	C system fault		CO3				
С	-		kers, surge arresters.	CO3				
Unit 4	Introduction to	introduction to FACTS						
А	Introduction to	power flow co	ontrol, loading capability.	CO4,CO6				
В	Steady state an	d dynamic lim	its of power transmission.	CO4				
С	Applications of	FACTS and it	s benefits.	CO4				
Unit 5	Types of FACTS							
А		Shunt controllers: Principle of operation, configuration and control of SVC and STATCOM						
В		rs : Principle o	f operation, configuration and	CO5				
С	Hybrid controlle	•	f operation, configuration and	CO5				
Mode of examination	Theory							
Weightage	СА	MTE	ETE					
Distribution	30%	20%	50%					
Text book/s*	International, 2 2G. Hingorar and technology	1. Padiyar K.R., HVDC Transmission Systems, New Age International, 2011 ISBN:9781906574772, 1906574774 2G. Hingorani and L. Gyugi, "Understanding FACTS: concepts and technology of Flexible AC Transmission systems", 1999, Wiley-IEEE Press ISBN:9780780334557, 0780334558						
Other References	-	EEE Power Ser						

	PO	РО													
	1	2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	2	2	3	3	1			1	2			2	3	2
CO2	3	2	2	2	3	2			1	2			2	3	3
CO3	3	3	3	2	3	1			1	2			3	3	3
CO4	3	3	2	3	3	3			1	2			3	3	3
CO5	3	3	2	2	2	2			1	2			2	2	2
CO6	3	3	2	2	2	2			1	2			2	2	3
	3.	2.6	2.17	2.33	2.67	1.83			1.00	2.00			2.33	2.67	2.67

SU/SET/B. Tech./EEE

		*	SHARDA
	00 7		Beyond Boundaries
Scho	ool: SET		
	gram: B.Tech		
	nch:EEE/EE/ECE	Semester:	
1	Course Code	EEE448	
2	Course Title	PLC and SCADA	
3	Credits	3	
4	Contact Hours	3-0-0	
	(L-T-P) Course Status	Commulsomy /Elective/Open Elective	
5	Course Status Course Objective	Compulsory /Elective/Open Elective To provide students with:	
5	Course Objective	1. The conceptual as well as practical knowledge of the Industrial	Automation &
		latest technologies being used to achieve Industrial Automation.	
6	Course Outcomes	CO1: inerpret basic components and their symbols used in convent	tional control
		boards	
		CO2: apply the concept of electrical ladder logic in programming of	PLC instruction
		CO3: indentify various input output components and design wiring	circuit for a PLC
		CO4: implement the input-output and programming techniques for	· interfacing PLC
			-
		CO5: design monitoring and control schemes for industrial applicati	ions
	Course Description	CO6: apply PLC based automation in indusrial applications	
7	Course Description	This course is aimed at equipping students with appropriate knowledg	and skills
		required in configuring, programming and operating Industrial automa	-
		with the use of Industrial Field Instruments, PLCs, SCADA/ HMI and DC	-
8	Outline syllabus		CO Mapping
0	Unit 1	Computer Based Industrial Control	
	A	Microprocessor/microcontroller based industrial controller: concept	CO1
		and configuration	
	B	Computer based industrial controller: concept and configuration	CO1
	С	Introduction to direct digital control (DDC), distributed control system (DCS) and supervisory control and data acquisition (SCADA)	CO1
	Unit 2	PLC Basics	+
	A	Introduction to PLC, PLC versus	CO2
		microprocessor/microcontroller/computer; Advantages and	
		disadvantages of PLC	



				Beyond Boundaries					
В			re and physical forms of PLC; Digital	CO3					
		its; Analog inputs							
C	PLC program	nming: ladder pr	ogramming, function blocks, Instruction	n CO2					
			t, mnemonic programming						
Unit 3	PLC Function								
А			output registers; Timers and timer	CO4					
		ounters and count							
В		g functions; Bit f		CO4					
С	Advanced fu	inctions; PLC pro	gramming using various functions	CO4					
Unit 4	SCADA Basic	s, Layout and Fu	nctions						
А	Introduction:	; Definition and p	ourpose; Controlled / uncontrolled	CO5					
	variables and	a remotely / local	ly controlled objects in controlled plant						
В	•		system; Detailed block schematic of	CO5					
	SCADA syst								
C			data acquisition and transmission,	CO5					
			ection and storage, data processing and						
		report generation							
	SCADA Hard	dware and Softw	are						
Unit 5									
А			: functions, single processor and	CO5					
	*	or MTU, single a	and dual computer configurations of						
P	MTU		for the product of the start of	005					
В			: functions, architecture / layout; RTU	CO5					
С	programming		nd RTU-field device communication	CO5					
				005					
Mode of	Theory/Jury	y/Practical/Viva							
examination									
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*			Programmable Logic Controllers,						
	Prentice-Hall								
			ory Control and Data Acquisition						
			onal Society of Automation, 2010.						
Other References			worth, Programmable Logic						
		Controllers, Pearson Edition							
	2. W. Boston	2. W. Boston, Programmable Logic Controllers, Newnes, (Elsevier)							
	3. H.K. Verm	a, SCADA, e-mon	ograph at www.profhkverma.info,						
			Chapter 2: Functions of SCADA System,						
	Chapter 3: H	ardware of SCAD	PA System.						



														🚺 веу		DII I ndaries
COs	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO1	PO1	PO1	PSO	PSO	PSO	PSO
	1	2	3	4	5	6	7	8	9	0	1	2	1	2	3	4
CO448 .1	3	2	1	-	1	2	-	-	-	-	-	2	2	2	2	3
CO448 .2	3	3	3	1	3	1	-	-	-	-	-	2	2	2	2	3
CO448 .3	3	3	3	3	3	2	-	-	-	-	-	2	2	2	2	3
CO448 .4	3	2	1	1	3	1	-	-	-	-	-	2	2	2	2	3
CO448 .5	3	3	3	3	3	2	-	-	-	-	-	2	2	2	2	3
CO448 .6	3	1	1	1	1	1	-	-	-	-	-	1	2	2	2	3
	3.0 0	2.3 3	2.0 0	1.8 0	2.3 3	1.5 0						1.83	2.00	2.00	2.00	3.00



Sch	ool: SET	
Pro	gram:	
Bra	nch: EEE	Semester:
1	Course Code	MOO402
2	Course Title	Introduction to smart grid
3	Credits	2
4	Contact Hours (L-T-P)	2-0-0
	Course Status	
5	Course Objective	• To introduce the concept of demand-side management for residential, commercial and industrial energy users.
		 To give an overview of the different types of demand-side measures. To describe energy auditing and routine data collection and monitoring, andto indicate their benefits.
		 To outline information dissemination on demand-side management. To provide an overview of the major implementation challenges for DSM programmes
6	Course Outcomes	 CO1 : To be able to define demand-side management. CO2: To understand the different types of demand-side management measures and their suitability to various energy users. CO3: To be aware of the benefits of good reliable data collection for regular performance analysis, and as an essential part of energy auditing CO4: To appreciate the need for effective information dissemination. CO5: To understand the challenges facing the implementation of demand-side management CO 6: To be able to design housekeeping and preventative maintenance in commerce and industry can be used to reduce energy demand.
7	Course Description	Demand-side management (DSM) has been traditionally seen as a means of reducing peak electricity demand so that utilities can delay building further capacity. In fact, by reducing the overall load on an electricity network, DSM has various beneficial effects, including mitigating electrical system emergencies, reducing the number of blackouts and increasing system reliability. Possible benefits can also include reducing dependency on expensive imports of fuel, reducing energy prices, and reducing harmful emissions to the environment. Finally, DSM has a major role to play in deferring high investments in generation, transmission and distribution networks. Thus DSM applied to electricity



	7 1	ies significant	economic, reliability and environmenta						
\$ Outline syllab				CO Mappin					
Unit 1	Energy Scenario			CO1					
Α			udit, Energy Scenarios,	CO1					
В	Energy Consum		•	CO1					
C	Energy Strategy	, Clean Develop	oment Mechanism	CO1					
Unit 2	Energy Audit								
А	Definition of En	ergy Audit, Plac	ce of Audit,	CO2					
В	Energy – Audit M Project Financin		inancial Analysis, Sensitivity Analysis,	CO2					
С	Energy Monitor	ing and Training	g Solar power plant	CO2					
Unit 3	Electrical-Load	Management		CO3					
А	Electrical Basics	, Electrical Load	Management,	CO3					
В	Variable- Freque	ency Drives, Ha	rmonics and its Effects,	CO3					
С			Transmission and Distribution Losses	CO3					
Unit 4	Demand side M	anagement		CO4, CO6					
А	Scope of DSM, E Implementation		M concept, DSM planning and	CO4, CO6					
В	Load manageme	CO4, CO6							
С	Tariff options fo	CO4, CO6							
Unit 5	Energy Conserv	CO5,CO6							
А		Motivation of energy conservation, Principles of Energy conservation, Energy conservation planning,							
В	Energy conserva	CO5, CO6							
С		and commerci	al sectors, EC in transport, EC in	CO5, CO6					
Mode of examination	Theory								
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*	1. Renewa		wer for a sustainable future, third edition, le, Oxford University Press, 2013.						
Other References	1. Microgr Chowdł Technol								



COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	_	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	-	-

SU/SET/B. Tech./EEE



<mark>Sch</mark>	ool: SET		
Pro	<mark>gram: B.Tech</mark>		
Bra	nch: EEE		
1	Course Code		
2	Course Title	Advanced Control Engineering and Controllers	
<mark>3</mark>	Credits	3	
<mark>4</mark>	Contact Hours (L-T-P)	3-0-0	
	Course Status		
<mark>5</mark>	Course Objective	To provide students with: 1. some advanced concepts in Control Systems Engineering and their a 2. A theoretical understanding of advanced linear control systems and s including the principles of digital control. 3 understanding of performing stability analysis of digital control system 4. knowledge of Analog controller, computer based controller and inte	strategies, ns.
<mark>6</mark>	Course Outcomes	After completion of this course students will be able to: CO1: Understand advanced concepts and approaches to control system CO2: Understand industrial controllers of continuous and discontinuou advanced control concepts of cascaded and feed forward controls. CO 3design, develop and operate analog controllers, both electronic an types. CO4: Design develop and operate computer based control systems. CO5Understand simulate and design artificial intelligence based control CO 6: Industrial experiences in control engineering	n designs s types and d pneumatic
7	Course Description	This course introduces systematic approaches to the design and analysic control systems for industrial applications.	is of advance
8	Outline syllabus		CO Mapping
<u>,</u>	Unit 1	Overview of Control System	
	A	Elements of control systems; Concept of open loop and closed loop systems; Examples and application of open loop and closed loop systems	CO1
	B	Brief idea of multivariable control systems; Concept of stability and necessary conditions, Routh-Hurwitz criteria and limitations. Correlation between time and frequency responses	CO1
	C	State variable modelling of linear discrete systems, controllability and observability; Nonlinear control systems; Fundamentals- common nonlinearities (saturation, dead-zone, relay, on-off nonlinearity, backlash, hysteresis	CO1
	Unit 2	Controller Principles	



				Beyond Bounda					
A	Process Ch	naracteristics; Cor	trol system parameters: error, v	ariable CO2					
	range, con	trol parameter rai	nge, control lag, dead time, cyclir	ng					
<mark>B</mark>	Discontinu	ious controller mo	odes: two-position mode, multi-	CO2					
	<mark>position m</mark>	ode; Continuous o	controller modes						
C	proportion	al, integral and de	erivative control modes; Compos	ite CO2					
	Control mo	odes: proportiona	l-integral (PI), proportional-deriv	<mark>ative</mark>					
	<mark>(PD) and th</mark>	n <mark>ree mode contro</mark>	<pre>ller (PID); Cascaded and feed-for</pre>	ward					
	<mark>controls</mark>								
<mark>Unit 3</mark>	Analog Col								
A		on; General featur		CO3					
<mark>B</mark>			r detector, single mode and com	posite CO3					
	<mark>mode cont</mark>	<u> </u>							
C			ortional, proportional-integral (P	<mark>I),</mark> CO3					
			and PID controller.						
<mark>Unit 4</mark>		Based Control							
A	Introduction (1977)	on; Digital applicat	tions: alarms, two-position contro						
<mark>B</mark>	Computer	<mark>based controller</mark>		CO4,CO6					
C			<mark>ftware requirements</mark>	CO4,CO6					
<mark>Unit 5</mark>	Intelligent	Control Systems							
A	Fuzzy-logic	control system: F	uzzy set theory, basic fuzzy set	CO5,CO6					
			uzzy logic controller, methods of						
_		tion of membersh	· · · · · · · · · · · · · · · · · · ·	ogic CO5,CO6					
B		Methods of defuzzification, fuzzy rule base, design of fuzzy logic control system.							
<u>a</u>									
C			em :Artificial neural networks,	CO5,CO6					
			I neuron, network architecture,						
	learning in	neural networks,	back-propagation, Neurofuzzy co	ontrol					
Mada af		D							
Mode of examination	Theory/Ju	ry/Practical/Viva							
Weightage	CA	MTE	ETE						
Distribution	<u>CA</u> 30%	20%	50%						
Text book/s*	<u>30%</u>	20%	<mark>30%</mark>						
ICAL DOOK/S	1 Curtic D	Johnson "Proces	s Control Instrumentation						
		y,"8th Edition Pear							
			"Control Systems Engineering,"	1+h					
		w Age Internatio		4					
Other References									
Suler References		nandam and S.N.	Deepa, "Principles of soft compu	iting "					
		Pvt. Limited.		<u>·····δ</u>					
	,								
			'ijayalakshmi Pai, " Neural	had					
	NWTWORKS	FUZZY LOGIC, and (-	enetic Algorithms," PHI Pvt. Limi	led.					

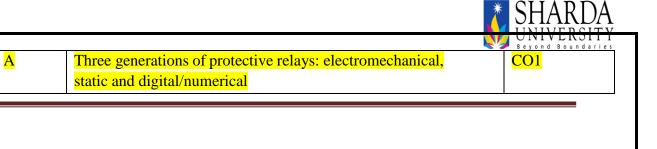


COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	<mark>3</mark>	2	2	<mark>1</mark>	-	-	-	-	-	-	-	-	2	<mark>1</mark>	2
CO.2	<mark>3</mark>	<mark>1</mark>	2	<mark>2</mark>	-	-	-	-	-	-	-	-	-	-	2
CO.3	<mark>3</mark>	2	<mark>2</mark>	2	-	-	-	-	-	-	-	-	2	<mark>3</mark>	2
CO.4	<mark>3</mark>	1	<mark>2</mark>	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	<mark>2</mark>	<mark>2</mark>	1	-	-	-	-	-		-	-	<mark>3</mark>	2	2
CO.6	<mark>3</mark>	<mark>3</mark>	<mark>3</mark>	<mark>2</mark>	-	-	-	-	-	-	-	-	<mark>2</mark>	-	-

SU/SET/B. Tech./EEE



	ool: SET	
	gram: B.Tech	Current Academic Year:
_	nch: EEE	Semester:
1	Course Code	
<mark>2</mark>	Course Title	Digital Relaying for Power Systems
<mark>3</mark>	Credits	<mark>3</mark>
<mark>4</mark>	Contact	3-0-0
	Hours	
	<mark>(L-T-P)</mark>	
	Course Status	Compulsory
<mark>5</mark>	Course	1. to understand the concept of digital protection and computer relaying forpower
	Objective	system.
		2. to acquire an in-depth knowledge on different generations of protectiverelays
		3. to identify different components of a numerical relay
		4. to apply discrete Fourier transform technique in Power System
		Protection
		5. to design and develop relay algorithms for protection of power system
		apparatus
<mark>6</mark>	Course	CO1: to compare, analyse the advantages and disadvantages of all the three
	Outcomes	generations of protective relay and also identify the different components of a
		numerical relay
		CO2: to develop relay algorithms based on relaying signals
		CO3: to develop algorithm for digital protection of generator
		CO4: to develop algorithm for digital protection of transformer
		CO5: to apply ANN for protection of transmission line and power
		transformer
		CO6: to design and evaluate protection algorithms for protection of anypower
_		system component
<mark>7</mark>	Course	The first and foremost driving force for advances in relaying systems is the need
	Description	improve reliability. In turn, this implies increase in dependability as well a
		security. This need to improve reliability propelled the development of digit
		relaying. In this course, the students will have an exposure to the three generation
		of protective relays.
		Throughout the course, students will have an opportunity to be exposed to
		different numerical techniques for protection of generators, transformers and
		transmission lines.
<mark>8</mark>	Outline syllabus	CO Mapping
<mark>v</mark>	Unit 1	Introduction and Architecture of Digital Relay
		indoduction and Architecture of Digital Actay





B	architecture and elements of a digital relay	CO1
C	Multifunctional relays, management relays and IED Relays	CO1
Unit 2	Relay Algorithms and Mathematical Basis	
A	Relay Algorithms based on pure sinusoidal relaying	CO2 & CO6
	signals, distorted relaying signals and differential equation	
	representation of system;	
B	Z transform, sine and cosine Fourier series, Fourier	CO2 & CO6
	Transform and DFT	
C	Walsh functions, digital filters, windows and windowing.	CO2 & CO6
Unit 3	Digital Relaying for Generator	
A	Various protection functions: differential, stator earth fault,	CO3 & CO6
	loss of excitation and reverse power protection	
B	Abnormal frequency and voltage protection: over and under	CO3 & CO6
	frequency protection, over and under voltage	
C	protection	
	Numerical differential protection of generator	CO3 & CO6
Unit 4	Digital Relaying for Transformer	
A	Types of faults encountered in transformer, basic	CO4
	considerations for transformer differential protection,	
B	stabilizing of differential protection during magnetizing inrush current	CO4
C	Numerical protection of transformer	CO4
Unit 5	Artificial Intelligence Based Numerical Protection	CO5
A	Types of Neural Network Models, Artificial Neural	CO5
_	Network, Design Procedure and Consideration	
<mark>B</mark>	Application of ANN to transmission line protection	CO5
C	ANN based power transformer protection	
Mode of	Theory	
examination		
Weightage	CA MTE ETE	
Distribution	30% 20% 50%	
Text book/s*	1. Arun G Phadke and James S. Thorp, "Computer Relaying	
	for Power Systems", John Wiley and SonsInc, New York.	
	2. Badri ram, D.N. Vishwakarma, 'Power System	
	Protection & Switchgear', Tata McGraw –hill	
	publishing company ltd, New Delhi.	
Other	1. Bhavesh Bhalja, R.P. Maheswari and Nilesh G.	
References	Chothani, "Protection and Switchgear", Oxford.	
IXCICICITUES	Chomani, Trotection and Switchgear, Oxford.	1

														UNIV Beyond	LILL
<mark>COs</mark>	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSC
<mark>CO.1</mark>	<mark>3</mark>	<mark>2</mark>	<mark>2</mark>	<mark>1</mark>	-	-	-	-	-	-	-	-	<mark>2</mark>	<mark>1</mark>	2
<mark>CO.2</mark>	<mark>3</mark>	1	<mark>2</mark>	<mark>2</mark>	-	-	-	-	-	-	-	-	-	-	2
<mark>CO.3</mark>	<mark>3</mark>	<mark>2</mark>	<mark>2</mark>	<mark>2</mark>		-	-	-	-	-	-	-	2	<mark>3</mark>	2
<mark>CO.4</mark>	<mark>3</mark>	1	<mark>2</mark>	<mark>2</mark>		-	-	-	-	-	-	-	2	-	2
CO.5	1	2	<mark>2</mark>	<mark>1</mark>		-	-	-	-		-	-	<mark>3</mark>	2	2
CO.6	<mark>3</mark>	3	<mark>3</mark>	2	_	_	_	_	_	_	_	_	2	_	-



	lool: SET		
	ogram: M.Tech		
	nch: EEE	Somoston	
<u>БГа</u>		Semester:	
1	Course Code	Distributed Conception Technologie	
2	Course Title	Distributed Generation Technology	
3	Credits	3	
4	Contact Hours	3-0-0	
	(L-T-P)		
	Course Status		
5	Course	To introduce the concept of distributed generation, microgrids, electric ve	ehicles and
	Objective	energy storage.	
		To familiarize the students with renewable generation system modelling,	and their grid
		integration issues.	
		To impart an understanding of economics, policies and technical regulation	ons for DG
6	Course	integration CO1 : Analyse the concept and importance of distributed generation.	
0	Outcomes	CO2: Understand different renewable energy sources, micro-grid and sto	r200
	Outcomes	Devices.	age
		CO3: Evaluate the technical impact of DG in power system	
		CO4: Analyze the operation and control strategies for grid connected and	l off-grid
		System.	
		•	
		1 CO5. Evaluate the effect of DG placement in the existing system	
		CO5: Evaluate the effect of DG placement in the existing system	
7	Course	CO 6: Industrial experiences in renewable energy integration	ovoltaic systems
7	Course	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot	•
7	Course Description	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi	ples of control of
7		CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution system	ples of control of ms, installation,
7		CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi	ples of control of ms, installation,
7		CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distributed	ples of control of ms, installation, puted generation,
7 8	Description Outline syllabu	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards.	ples of control of ms, installation, puted generation, CO Mapping
	Description	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation	ples of control of ms, installation, outed generation, CO Mapping CO1
	Description Outline syllabu	CO 6: Industrial experiences in renewable energy integrationThis syllabus gives an overview of distributed energy resources, photsmall hydro, fuel cells, energy storage technologies; wind turbines, Princidistributed generation systems; Electric power distribution systeinterconnection and integration; Economic and financial aspects of distributethe regulatory environment and standards.Introduction to Distributed GenerationConcept of DG and, its definition, Current scenario in distributed	ples of control of ms, installation, outed generation, CO Mapping CO1
	Description Outline syllabu Unit 1	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distributed the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation	ples of control of ms, installation, outed generation, CO Mapping CO1
	Description Outline syllabu Unit 1 A B	CO 6: Industrial experiences in renewable energy integrationThis syllabus gives an overview of distributed energy resources, photsmall hydro, fuel cells, energy storage technologies; wind turbines, Princidistributed generation systems; Electric power distribution systeinterconnection and integration; Economic and financial aspects of distributethe regulatory environment and standards.Introduction to Distributed GenerationConcept of DG and, its definition, Current scenario in distributed	ples of control of ms, installation, outed generation, CO Mapping CO1
	Description Outline syllabu Unit 1 A	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distributed the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation	ples of control of ms, installation, outed generation, CO Mapping CO1 CO1
	Description Outline syllabu Unit 1 A B C	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distribute the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG	ples of control of ms, installation, outed generation, CO Mapping CO1 CO1 CO1
	Description Outline syllabu Unit 1 A B C Unit 2	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distribute the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation	ples of control of ms, installation, outed generation, CO Mapping CO1 CO1 CO1 CO1
	Description Outline syllabu Unit 1 A B C Unit 2 A	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant	iples of control of ms, installation, outed generation, CO1 CO1 CO1 CO1 CO1 CO1 CO1 CO1
	Description Description Outline syllabu Unit 1 A B C Unit 2 A B	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distribute the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant	CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO2 CO2
	Description Outline syllabut Unit 1 A B C Unit 2 A B C	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG	CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2
	Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG	CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3
	Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 A	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG Transmission systems, Distribution systems	CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 CO3
	Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 A B	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG Impact of DGs upon protective relaying	CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 CO3 CO3
	Description Outline syllabut Unit 1 A B C Unit 2 A B C Unit 3 A	CO 6: Industrial experiences in renewable energy integration This syllabus gives an overview of distributed energy resources, phot small hydro, fuel cells, energy storage technologies; wind turbines, Princi distributed generation systems; Electric power distribution syste interconnection and integration; Economic and financial aspects of distrib the regulatory environment and standards. Is Introduction to Distributed Generation Concept of DG and, its definition, Current scenario in distributed generation Need for distributed generation Advantage and limitation of DG Renewable based Distributed generation Wind power plant Solar power plant Small hydro other alternate DG Technical impacts of DG Transmission systems, Distribution systems	CO Mapping CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2 CO2 CO2 CO3 CO3



Unit 4	Onoration and	- Feanami	c aspects of DGs	CO4, CO6			
			*	/			
A	De-regulation	1 /	es, Reactive power control, Harmonics,	CO4, CO6			
В	Ū.	CO4, CO6					
	· · ·		ability of DG based systems				
С	Economic imp	oacts: Mark	tet facts, issues and challenges	CO4, CO6			
Unit 5	Grid integrati	on of DGs		CO5,CO6			
A	Optimal placer	nent of DG	sources in distribution systems	CO5, CO6			
В	• 1		ces , Inverter based DGs and rotating , Aggregation of multiple DG units	CO5, CO6			
С	Energy storage	CO5, CO6					
Mode of examination	Theory						
Weightage	CA	MTE	ETE				
Distribution	30%	20%	50%				
Text book/s*	2. Renewa	ble Energy-	Power for a sustainable future, third edition,				
		0,	Boyle, Oxford University Press, 2013.				
Other References	Chowdh		ve Distribution Networks, S. Chowdhury, S.P. Crossley, The Institution of Engineering and n, U.K, 2009				

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	-	-



-	nool: SET								
	ogram: B.Tech	Current Academic Year:							
Bra	anch: EEE	Semester :							
1	Course Code								
2	Course Title	Intelligent Actuators and Mechatronics							
3	Credits	3							
4	Contact	3-0-0							
	Hours								
	(L-T-P)								
	Course Status								
5	Course	• Discussing of basic components of actuators and mechatr	onics						
	Objective	• Discussing of electronics and digital circuits concepts of t	he subject						
		 Explaining concept of intelligent and smart system Discussing of interfacing concepts of mask stranges systems 							
		• Discussing of interfacing concepts of mechatronics system							
		• Giving case studies and exploring knowledge on designing	g						
6	Course	CO 1. Cotting browledge on basis services of the t	and						
6	Course	CO 1: Getting knowledge on basic components of actuators	and						
	Outcomes	mechatronics							
		CO 2: Exploring knowledge and getting design concepts of a							
		CO 3: Identifying concepts smart and intelligent on mechatronics systems $CO(4)$. Able to design of interfacing circuits for the subject							
		CO 4: Able to design of interfacing circuits for the subject							
		CO 5: Able to design of tailor-made systems							
7	Comme	CO 6: Industrial experiences in mechatronics systems	1.4 1 6 1 4						
7	Course	The field of mechatronics has braddened the scope of the tra							
7	Course Description	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre	ends on						
7		The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand	ends on						
-	Description	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems.	ends on l alone						
-	Description Outline syllabutic	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems.	ends on l alone						
-	Description Outline syllabu Unit 1	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems.	ends on l alone CO Mappin						
-	Description Outline syllabutic	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems.	ends on l alone						
-	Description Outline syllabu Unit 1 A	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding	ends on l alone CO Mappin CO1						
-	Description Outline syllabu Unit 1 A B	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators	CO Mappin CO Mappin CO1 CO1						
-	Description Outline syllabu Unit 1 A	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of	ends on l alone CO Mappin CO1						
-	Description Outline syllabu Unit 1 A B C	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course	CO Mappin CO Mappin CO1 CO1 CO1 CO1						
7 8	Description Outline syllabu Unit 1 A B C Unit 2	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics	CO Mappin CO Mappin CO1 CO1						
-	Description Outline syllabu Unit 1 A B C	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation	CO Mappin CO Mappin CO1 CO1 CO1 CO1						
-	Description Outline syllabu Unit 1 A B C Unit 2 A	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers	 co Mappin CO Mappin CO1 CO1 CO1 CO1 CO2 						
-	Description Outline syllabu Unit 1 A B C Unit 2 A B	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration	 cnds on alone CO Mappin CO1 CO1 CO1 CO1 CO2 CO2 						
-	Description Outline syllabu Unit 1 A B C Unit 2 A	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their	 cnds on l alone CO Mappin CO1 CO1 CO1 CO1 CO2 						
-	Description Outline syllabu Unit 1 A B C Unit 2 A B C C	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts	 cnds on alone CO Mappin CO1 CO1 CO1 CO1 CO2 CO2 						
-	Description Outline syllabu Unit 1 A B C Unit 2 A B C Unit 2 Unit 3	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. INTRODUCTION Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts Smart and Intelligent Actuators	ends on l alone CO Mappin CO1 CO1 CO1 CO2 CO2 CO2 CO2						
-	Description Outline syllabu Unit 1 A B C Unit 2 A B C C	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. IS Introduction Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts Smart and Intelligent Actuators Definitions: Smart and intelligent actuators; Architecture and	 cnds on alone CO Mappin CO1 CO1 CO1 CO1 CO2 CO2 						
-	Description Outline syllabu Unit 1 A B C Unit 2 A B C Unit 2 Unit 3	The field of mechatronics has braddened the scope of the tra of elctromechanics. The subject is made to know modern tre mechatronics system, hybrid of different engineerings, stand mechatronics systems. INTRODUCTION Definitions: Mechatronics & actuator; Overview of sensors, current & voltage sources; Grounding Solenoids, relays, electrical motors for actuators Basics of open loop and closed loop systems , block diagram of mechatronics system ; Scope of the course Overview of Analog and Digital Electronics Active electronic devices for mechatroics, basics of operation amplifiers and instrumentation amplifiers Display systems, measurement systems, testing and calibration Combination logic and logic classes; Flip-flops and their applications; Microcontroller concepts Smart and Intelligent Actuators	ends on l alone CO Mappin CO1 CO1 CO1 CO2 CO2 CO2 CO2						



				👟 🌽 Beyond Boun					
Unit 4	Mechanical-Ele	ectronic Interfac	ing						
А	Concept of three	ee-state (tri-stat	e) outputs; Interfacing of	CO4,CO6					
	pushbutton, ke	ushbutton, keyboard and sensors							
В	Interfacing of r	nterfacing of relays, solenoids, DC, AC motors and special							
	motors to micr	Interfacing of relays, solenoids, DC, AC motors and special motors to microcontroller Selecting of motor for actuators Case studies & Design Exercise Case study 1: Mechatronic design of a coin counter; Case study							
С	Selecting of mo								
Unit 5	Case studies &								
А	Case study 1: N								
В	Case study 2: N	Case study 2: Mechatronics for conveyor based material							
	handling syster	n							
С	Design exercise	on mechatroni	c system	CO5,CO6					
Mode of	Theory								
examination									
Weightage	СА	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*	David G, Alcia	tore et al., "In	troduction to Mechatronics and						
		Measurement Systems", Tata McGraw Hill, 2003							
Other									
References	2. Godfre	v C. Onwubolu.	"Mechatronics", Elsevier, 2005						
		,	······································						

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	-	-



Sch	ool: SET		Beyond Boundaries
	gram: B.Tech	Current Academic Year:	
	nch:EEE	Semester:	
1	Course Code		
2	Course Title	Operation and Control of smart grid	
3	Credits	3	
4	Contact Hours	3-0-0	
	(L-T-P)		
	Course Status		
5	Course Objective	The objective of the subject on smart grid technologies is to interest optimize distributed energy resources to achieve a more efficient grid, enable active participation of consumers with more environ constraints	and reliable
6 7	Course Outcomes Course Description	 The students should be able to CO1: Identify different tools and approaches to modelling a Smat CO2: Apply Optimal Power Flow (OPF) solutions to evaluate the of a power system with renewable energy sources. CO3: Analyze power system dynamics (frequency stability) to achieve balance. CO3: To familiarize the students with modelling of smart grids compered CO5. Identify control-room technologies for system-wide remote management of smart grid cyber security CO 6: Able to design, implementation, evaluation and management electricity infrastructure. 	ne performance ve active power onents. onitoring, c of smart pics in the field of
		storage, vehicle-to-grid systems, wide area measurement, smart gretc	id cyber security,
8	Outline syllabus		CO Mapping
_	Unit 1	Modeling of Smart Grids	
	А	Operating principles and models of smart gird components,;.	CO1
	В	Key technologies for generation, networks, loads and their control capabilities decision-making tools	CO1
	С	Hardware, Software, Communication. Approaches to estimation,	CO1
		scheduling, management and control of next generation smart grid	
	Unit 2	Smart Grid Communications	
	А	Two-way Digital Communications Paradigm, Network Architectures	CO2
	В	IP-based Systems, Power Line Communications	CO3
	С	Advanced Metering Infrastructure,	CO2
	Unit 3	Security and Privacy	
	А	Cyber Security Challenges in Smart Grid,Load Altering Attacks	CO4
	В	False Data Injection Attacks, Defense Mechanisms	CO4



				Beyond Boundaries			
C	Privacy Challen	ges Data hand	lling functions; Bit functions	CO4			
Unit 4	IoT for power sy	ystems					
Α	Internet of thing management.	gs for electrici	ty infrastructure and energy	CO5,CO6			
В	SCADA, Demand	l response, Al	∕II, IoT aided smart grid,	CO5,CO6			
С	Big data for pow	ver system an	d introduction to data analytic	cs. CO5,CO6			
Unit 5	Flexible AC tran						
А	Congestion man power compens	-	loadability enhancement, rea	ctive CO5,CO6			
В	concept of serie working principl	•	on, shunt compensation, FACT	-s: CO5,CO6			
C	Classification, se	Classification, series controllers, shunt controllers, series-series controllers, series-series					
Mode of examination	Theory/Jury/Pt						
Weightage	CA	MTE	ETE				
Distribution	30%	20%	50%				
Text book/s*	Wu, Akihiko Yo Applications", 2 James Mom	okoyama, "Sr John Wiley & oh, "Smart Gr	Jenkins, Kithsiri Liyanage, Jia nart Grid: Technology and a sons inc, 2015. id: Fundamentals of design an nc, IEEE press 2012				
Other References	1.Fereidoon P. Distributed & I 2.Clark W.Gelli and demand re	Sioshansi, " Efficient Ene Ings, "The sn esponse", Fa	Smart Grid: Integrating Renergy", Academic Press, 2012. art grid: Enabling energy ef irmont Press Inc, 2009. ograph at ww.profhkverma.in	ficiency			

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	-	-



Sch	ool: SET		
Pro	gram: B. Tech.		
	nch: EEE		
1	Course Code		
2	Course Title	Operation and Control of smart grid Lab	
3	Credits	2	
4	Contact Hours (L-T-P)	0-0-4	
	Course Status		
5	Course Objective	Learn modern numerical techniques and analytical method with and solving operation and protection related probled power systems	-
6	Course Outcomes	 After the completion of course student will be able to CO1: explore the concept of automatic generation control. CO2: apply the modes of excitation systems and exercises control. CO3: employ incremental cost curve and penalty factor for operation. CO4: plan unit commitment for optimal operation. CO5: evaluate power system security and methods of impri CO6: compare the protection techniques used for protection power system components 	voltage or economic rovement.
7	Course Description	This course aims to convince the student that constancy of voltage are the primary health indicator of the power maintaining the real and reactive power balance in systems of economic load dispatch and unit commitment are also course. The concept of close coordination between there power plant to meet the load demand has been included in t	er system for 5. The concepts 50 given in the mal and hydro
8			
	Unit 1	Practical related to economic load dispatch and Unit Commitment	
	А	To perform economic load dispatch without considering losses using MATLAB	CO3
	В	To perform economic load dispatch with considering losses using MATLAB	CO3
	С	To solve unit commitment method using priority list scheme in MATLAB	CO4
	Unit 2	Practical related to load frequency control and voltage	





	control			
А	To design load	frequency co	ntrol model in MATLAB	CO1
В			n most optimal location and	CO2
			tage profile using	
	MATLAB/PS			
C			n most optimal location and	CO2
			ver transfer capability using	
II:4 2	MATLAB/PS		system security and	
Unit 3	excitation cor			
A			control model in PSCAD.	CO2
B	-		ontrol model in PSCAD.	CO2 CO2
C	0		f a system using contingency	CO2
C	analysis in MA	005		
Unit 4	Practical rela			
А	To simulate si	CO6		
	measure volta			
В	To simulate li	CO6		
	and current at			
C	To simulate de	CO6		
	measure voltag			
Unit 5	Practical rela			
А	Principle of va constructions.	CO6		
В			ferential and distance relays	CO6
	and their operation			000
C	•	s: introduction	to static and essor based) relays and	CO6
	Intelligent Ele	· •	, .	
Mode of	Practical		(ILD) Iciayo	
examination	- raction			
Weightage	CA	MTE	ETE	
Distribution	60%	1		
Text book/s*	Allen. J. Woo	Wollenberg, "Power		
			ontrol", John Wiley & Sons,	
	Inc., 2003.		-	

	SHARDA	
Other References	 P.Kundur, "Power System Stability and Control"MC Craw Hill Publisher, USA, 1994. Olle.I.Elgerd, "Electric Energy Systems Theory An Introduction" Tata McGraw Hill Publishing Company Ltd. New Delhi, Second Edition 2003 	

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	_	-	-	2	-	-

SU/SET/B. Tech./EEE



Sch	nool: SET							
Pro	gram: B.Tech							
	anch: EEE	Semester:						
1	Course Code	EEE448						
2	Course Title	PLC and SCADA						
3	Credits	3						
4	Contact Hours (L-T-P)	3-0-0						
	Course Status							
5	Course Objective	To provide students with: 1. The conceptual as well as practical knowledge of the Industrial Automation & latest technologies being used to achieve Industrial Automation.						
6	Course Outcomes	 The students should be able to CO1: understand the concepts of computer based Industrial Control, including PLC, DCS and SCADA. CO2: understand hardware of PLC and ladder programming for PLC CO3: use various PLC functions and develop PLC programs for 						
		 industrial control and automation applications. CO4: understand the purpose, layout, components and functions of SCADA systems and use the knowledge for the operation of SCADA systems in Industry CO5.design SCADA system including layout, communication system and software. CO 6: Industrial experiences in PLC and SCADA. 						
7	Course Description	This course is aimed at equipping students with appropriate knowledge skills required in configuring, programming and operating Industrial automation systems with the use of Industrial Field Instruments, PLC and SCADA systems.						
8	Outline syllabus		CO Mapping					
	Unit 1	Computer Based Industrial Control						
	A	Microprocessor/microcontroller based industrial controller: concept and configuration	CO1					
	В	Computer based industrial controller: concept and configuration	CO1					
	С	Introduction to direct digital control (DDC), distributed control system (DCS) and supervisory control and data acquisition (SCADA)	CO1					
	Unit 2	PLC Basics						
	A	Introduction to PLC, PLC versus microprocessor/microcontroller/computer; Advantages and disadvantages of PLC	CO2					
	В	Hardware, internal architecture and physical forms of PLC; Digital inputs/ outputs; Analog inputs/ outputs	CO3					



				Beyond		
С		ists, Sequential	programming, function blocks, function chart, mnemonic	CO2		
Unit 3	PLC Function					
А	Registers: holding, input and output registers; Timers and timer functions; Counters and counter functionsData handling functions; Bit functions;					
В						
С	Advanced fu functions	CO4				
Unit 4	SCADA Basic	s, Layout and	Functions			
A	A Introduction; Definition and purpose; Controlled / uncontrolled variables and remotely / locally controlled objects in controlled plant B Layout and parts of SCADA system; Detailed block schematic of SCADA system C Functions of SCADA system: data acquisition and transmission, monitoring, control, data collection and storage, data processing and calculation, report generation					
В						
С						
Unit 5	SCADA Desi					
A	Master Terminal Unit (MTU): functions, single processor and multiprocessor MTU, single and dual computer configurations of MTU; Remote Terminal Unit (RTU): functions, architecture / layout; RTU programming					
В	MTU-RTU o communicat	CO5,CO6				
С	Design of SC Software.	CO5,CO6				
Mode of examination	Theory/Jury					
Weightage	CA	MTE	ETE			
Distribution	30%	20%	50%			
Text book/s*	1. J.W. Web Prentice-Hal 2 Stuart A. (SCADA), 4th 2010.					
Other References	Dther ReferencesJ.R. Hackworth and F.D. Hackworth, Programmable Logic Controllers, Pearson Edition 2. W. Boston, Programmable Logic Controllers, Newnes,(Elsevier). 3. H.K. Verma, SCADA, e-monograph at www.profhkverma.info, Chapter 1: Basics of SCADA, Chapter 2: Functions of SCADA System, Chapter 3: Hardware of SCADA System.					



COs	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	2	2

SU/SET/B. Tech./EEE

Page 115



Sch	ool:											
Pro	gram: B.Tech											
	nch: EEE	Semester: II										
1	Course Code											
2	Course Title	PLC and SCADA Lab										
3	Credits	2										
4	Contact Hours	0-0-4										
-	(L-T-P)											
	Course Status	Compulsory										
5	Course	To equip students with the working knowledge abo	ut the PLC based process									
	Objective	control and SCADA functions.	×.									
	5											
6	Course	CO1: To study and perform basic experiments on PLC	•									
	Outcomes	CO2: To perform process control using PLC.										
1		CO3: To perform motor control using PLC.										
		CO4: To implement basic SCADA functions.										
		CO5: To implement advanced SCADA functions										
		CO6: Industrial experiences in PLC and SCADA.										
7	Course	The contents of this course covers the implementation of	of basic and advanced									
	Description	functions of PLC and SCADA and their applications in										
8	Outline syllabus		CO Mapping									
	Unit 1	PLC based basic experiments										
	А	1.To study and use of NO and NC bit	CO1									
		2.To study and use of S (Set) and R (Reset) bit										
	В	1.To study and use of Timer instruction	CO1									
		2. To study and use of Cumulative timer instruction										
	С	1.To study and use of Counter instruction	CO1									
		2. To study logic gates in PLC.										
	Unit 2	PLC based process control										
	А	Water Level Control using PLC	CO2									
	В	Conveyor Belt Control Module using PLC	CO2									
	С	Traffic control using PLC										
	Unit 3	PLC based Motor Control										
	A-B	Ac motor speed control module using PLC.	CO3									
	С	Dc motor speed control module using PLC	CO3									
	Unit 4	Basic SCADA functions										
	А	Parameter reading of PLC in SCADA.	CO4									
	B-C	Alarm annunciation using SCADA.	CO4									
	Unit 5	Advanced SCADA functions										
	А	SCADA communication with PLC	CO5, CO6									
	В	Trend Monitoring on SCADA	CO4, CO6									
	C	Reporting on SCADA	CO6									
	Mode of	Practical & Viva										
	examination											
1	Weightage	CA MTE ETE										



		_			👟 🎾 Beyond Bound
Distribution	60%	0%	40%		
Text book/s*	Controlle 2 Stuar	rs, Prentice-H t A. Boyer, Sup on (SCADA), 4t	Reis, Programmabl all India pervisory Control ar hEdition, Internatio	nd Data	
Other	Refer lab	manuals			
References					

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	2	2

SU/SET/B. Tech./EEE

Page 117



	School: SET									
Prog	gram: B.Tech									
Brai	nch:EEE	Semester:								
1	Course Code									
2	Course Title	Robotics and Industrial Robots								
3	Credits	3								
4	Contact Hours	3-0-0								
	(L-T-P)									
	Course Status									
5	Course	1.To understand the construction industrial robotics								
	Objective	2.To explore knowledge on selection of end-effectors of robotics								
		3.To get knowledge of electrical drive systems of industrial robot								
		4.To know types of sensors of industrial robotics								
		5. To understand of electrical and electronics interfacings								
6	Carrier	6.To study about applications of industrial robots								
6	Course Outcomes	CO1: Basic construction of robot and robotics components								
	Outcomes	CO2: Understanding interfacing & building techniques of robots CO3: Knowing different types of actuators of robotics								
		CO4: Getting knowledge of robotics sensors and transducers								
		CO5: Developing interfacing circuits for robotics applications								
		CO 6: Industrial experiences in Robotics								
		co o. muusunai experiences in Kobolies								
7	0									
	Course	This course gives coverage of robotics components, architecture.	and electronics							
/	Course Description	This course gives coverage of robotics components, architecture, interfacing circuits knowledge. Students can also practice program								
,	Description	interfacing circuits knowledge. Students can also practice program	mming of robotics							
,		interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the statement of the statement o	mming of robotics his subject. Finally							
	Description	interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering	mming of robotics his subject. Finally							
		interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering.	mming of robotics his subject. Finally ng							
	Description Outline syllabus Unit 1	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis 	mming of robotics his subject. Finally ng CO Mapping							
	Description Outline syllabus	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; 	mming of robotics his subject. Finally ng							
8	Description Outline syllabus Unit 1 A	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis 	mming of robotics his subject. Finally ng CO Mapping CO1							
	Description Outline syllabus Unit 1 A	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic 	mming of robotics his subject. Finally ng CO Mapping CO1							
	Description Outline syllabus Unit 1 A B	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B C Unit 2	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B C	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B C Unit 2 A	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B C Unit 2	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B C Unit 2 A B B	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3							
	Description Outline syllabus Unit 1 A B C Unit 2 A	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO1 CO1							
	Description Outline syllabus Unit 1 A B C Unit 2 A B B	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3							
	Description Outline syllabus Unit 1 A B C Unit 2 A B C Unit 2 A C C C C C C	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and harmonic drive. 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3							
8	Description Outline syllabus Unit 1 A B C Unit 2 A B C Unit 2 A B C Unit 2 A B C Unit 3 A	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and harmonic drive. Sensors of Robotic System 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO2 CO2 CO2,CO3 CO2							
8	Description Outline syllabus Unit 1 A B C Unit 2 A B C Unit 3	 interfacing circuits knowledge. Students can also practice programusing embedded C on open source software after going through the students are able to do tailor-made projects on robotics engineering. Introduction to Robotics and Motion Analysis Historical background; Laws of robotics and robot definitions; Robotics systems and robot anatomy: Basic diagram, basic components and their uses; Specifications of robots. Position representation; Forward and reverse transformation: 2 & 3 DOF Robot End-Effectors, Robot Drives and Actuators Classification of end-effectors; Mechanical grippers, Magnetic grippers and vaccum grippers; Gripper force analysis. Functions of drive systems; Electrical drives: DC, BLDC motors, AC motors, stepper motor, piezoelectric actuators; Drive Mechanisms: rack and pinion, ball screws, gear trains and harmonic drive. Sensors of Robotic System Uses of sensors in robotics; Shaft Encoders (linear and rotational); 	mming of robotics his subject. Finally ng CO Mapping CO1 CO1 CO1 CO1 CO2 CO2,CO3 CO2 CO2 CO2							



				Beyond Boundaries					
A	Basics of PC inter	facings		CO5					
В	Microcontroller i	nterfacings		CO5					
С	Robot languages	Robot languages and classification; Robot software.							
Unit 5	Industrial Robot	Applications							
А	Material handling	g robots		CO6					
В	Welding Robots			CO6					
С	Assembling robo	ts		CO6					
Mode of	Theory								
examination									
Weightage	CA	MTE	ETE						
Distribution	30%	20%	50%						
Text book/s*	1.S.R. Deb and S.	Deb. "Robotics T	echnology and Flexible						
	Automation", Se								
Other	2. Mikell P Groo	. Mikell P Groover et al., "Industrial Robotics", fifth print, McGraw							
References	Hill, Special India	n Edition, 2013							

Course Articulation Matrix

COs	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	-	-	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	_	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	-	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	2	2



	ool: SET										
	gram: B.Tech										
Bra	nch: EEE	Semester:									
1	Course Code										
2	Course Title	Smart Power Grid and Micro-Grid									
3	Credits	3									
4	Contact Hours	3-0-0									
	(L-T-P)										
	Course Status										
5	Course	1. To understand the concepts of smart power grid and micro grid									
-	Objective	2. To acquire in depth knowledge of smart distribution, distribution									
	- J	automation, smart transmission and substation automation									
		3. To identify various components of smart grid and micro grid									
		4. To apply principles of automation to transmission and distribution									
		5. To design smart micro grid for a given application									
6	Course	CO1: To understand concept, motivation and benefits of Smart Power Grid									
	Outcomes	CO2: To develop knowledge of demand-side management as a tool of									
		smart distribution									
		CO3: to design advanced metering infrastructure for Distribu	tion								
		Automation									
		CO4: To design AC, DC and hybrid micro grids									
		CO5: To design phasor measurement and develop wide area	monitoring								
		system using PMU									
		CO6: Industrial experiences in renewable energy integration in distribution									
		system									
7	Course	The course deals with the concept of smart power grid an	d includes inv								
	Description	depth study of its its various components, namely smar									
	1	distribution automation and management, advanced metering									
		, smart micro grid, smart transmission and substation automa									
8	Outline syllabu		CO Mapping								
	Unit 1	Introduction to Smart Power Grid (4 hours)									
	А	Traditional power grid, Smart power grid (or smart grid) concept and objectives	CO1								
	В	Benefits of smart power grid, traditional-grid and smart-	CO1								
		grid comparison									
	С	Stake-holders in smart-grid development, Smart grid solutions.	CO1								
	Unit 2	Smart Distribution									
	A	Demand-side management: Energy efficiency, time of use and spinning reserve	CO2								
	В	Demand response: Market driven DR and operation-driven DR, incentive-based DR and TOU-based rates DR	CO2								





С	Distributed ge	neration, Ener	gy storage, Use of plugged	CO2				
		brid electric ve						
Unit 3	Distribution	Automation ar	nd Management					
A	customer autor	mation, feeder	eem, Components of DA: automation and substation trol centre (DCC)	CO3				
В	Distribution management system (DMS), Outage management system (OMS)- unplanned and planned outages, Asset management system (AMS), Customer information system (CIS)							
С	C Meaning and benefits of advanced metering, Structure and components of AMI, AMI integration with DA, DMS and OMS.							
Unit 4	Smart Micros							
А	Definition, con	CO4,CO6						
В			and hybrid, Modes of disland modes	CO4,CO6				
С	Meaning of sn control	nart micro grid	, Micro grid operation and	CO4,CO6				
Unit 5	Smart Transı	nission and Su	ubstation Automation					
А	Meaning and o	challenges of si	nart transmission	CO5,CO6				
В		Vide area moni	ncept, layout, components and toring system: concept and	CO5,CO6				
С		ation automatio	n (SA), Technical issues of ction.	CO5,CO6				
Mode of examination	Theory							
Weightage	CA							
Distribution	30%	20%	50%					
Text book/s*		1. Mini S. Thomas and John D. McDonald, Power System SCADA and Smart Grids, CRC Press,						



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Other	1. Janak Eknayake at el., Smart Grid: Technology and	
References	Applications, John Wiley and Sons, 2012	
	2. H. K. Verma, e-Monograph on "Smart – Grid",	
	www.profhkverma.info	

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO.1	3	2	2	1	-	-	_	_	-	-	-	-	2	1	2
CO.2	3	1	2	2	-	-	-	-	-	-	-	-	-	-	2
CO.3	3	2	2	2	-	-	-	-	-	-	-	-	2	3	2
CO.4	3	1	2	2	-	-	-	-	-	_	-	-	2	-	2
CO.5	1	2	2	1	-	-	-	-	-		-	-	3	2	2
CO.6	3	3	3	2	-	-	-	-	-	-	-	-	2	-	-



	ool:	School of Engineering and Technology
Pro	gram:	
Bra	unch: EEE	
1	Course Code	
2	Course Title	Virtual Instrumentation
3	Credits	3
4	Contact	3-0-0
	Hours	
	(L-T-P)	
	Course	
	Status	
5	Course Objective	 Introduction to the various models of Virtual Instruments, their comparison with traditional instruments and major application areas of VI. Introduction to basics of LabVIEW VI Programming techniques like loops, arrays, clusters, plotting and Strings and files. Basics of signal conditioning techniques along with DAQ hardware and software and various signal processing techniques available in LABVIEW. Advanced concepts in LabVIEW with main concepts of real time applications in Image acquisition and Motion control. Building of Virtual Instruments with various types of controls and indicators. Configuring DAQ card and acquisition of real time signals from sources and sensors. Simulate a signal in LabVIEW and generate a virtual source using DAQ cards.
6	Course Outcomes	 CO1: Understand various models and areas of application of Virtual Instrumentation. CO2: Understand various components of LabVIEW required for the development of VI. CO3: Understand and apply various programming functions of LabVIEW like loops, arrays, clusters and file I/Os for building of simple Virtual instruments. CO4: Understand the concepts of Data acquisition hardware and software and to apply basic signal processing techniques available in LabVIEW. CO5: Understand the real time applications of LabVIEW in motion control and Image acquisition.
7	Course	CO6: Able to build VI for simulated and real time applications.
1	Description	The course content of this subject includes an introduction to graphical



			Beyond Bounda						
		to LabVIEW g language .In ttc. have been n this course. ques are also on control and orated in this							
8	Outline syllabus								
	Unit 1	Introduction	Mapping CO1						
	A	Graphical system design model - design model, prototype model, deployment model							
	В	Building blocks of VI; Virtual instrument versus traditional instrument, Hardware and software in VI							
	С	Graphical system Design using LabVIEW; Graphical programming and Textual programming							
	Unit 2	Graphical system Design using LabVIEW	CO2,CO6						
	A	Advantages of LabVIEW; Components of VI Software - Front panel windows, Block diagram windows, Icon /connector pane							
	В	Creating and saving a VI; Toolbars, Palettes, Front panel controls and indicators, Block diagram – terminals, nodes, functions							
	С	Sub VIs, Express VIs and VIs, wires; Data types, Data flow program							
	Unit 3	Programming Techniques	CO3,CO6						
	А	Modular Programming in Lab View; Building VI front panel and block diagram							
	В	Loops – for and while loops, Local and Global variables in LabVIEW, Arrays in LabVIEW,							
	C	Clusters in LabVIEW; Conversion between arrays and clusters, Plotting data in LabVIEW, Strings and File I/O in LabVIEW							
	Unit 4	Data Acquisition and Signal Processing in LabVIEW	CO4,CO6						
	А	Transducers and Signal conditioning ,sampling and aliasing							
	В	Basics of DAQ hardware and software, DAQ modules and drivers for building virtual instruments							
	C	Fourier transforms; Power spectrum, Correlation methods; Windowing & filtering							
	Unit 5	Advanced concepts in LabVIEW	CO5, CO6						
	Α	Data Socket, TCP/IP VI's synchronization							
	В	Serial interface buses - RS 232, RS485,USB							
	С	Concepts of real time systems; Image acquisition; Motion control							
	Mode of examination	Theory/Jury/Practical/Viva							



				🥆 🥟 Beyond Bounda							
Weightage	CA	MTE	ETE								
Distribution	30%	20%	50%								
Text book/s*		1. Jovitha Jerome, "Virtual Instrumentation and LABVIEW", PHI Learning									
Other References	1. C.L. Clar TMH Publishir	ıg",									
	2. Techn and Na	ntech									
	3. <u>www.p</u> Protoce	gies/									
	4. NI USI http://v										
	5. www.n										

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO 008.1	1	2	2	2	2	1	1	2	1	2	-	2	2	2	1
CO008.2	3	2	1	2	3	1	2	2	1	1	-	2	2	2	2
CO008.3	3	2	3	2	3	2	2	2	1	2	-	2	2	2	2
CO008.4	2	2	2	2	1	2	2	2	2	2	-	3	3	2	2
CO008.5	2	3	3	2	2	2	2	2	2	2	-	3	3	2	2
CO008.6	2	3	3	2	3	2	2	2	2	3	2	3	3	2	3



Sch	ool: SET		🥟 Beyond Boundari
Pro	gram: B.Tech		
	nch:EEE	Semester:	
1	Course Code		
2	Course Title	Virtual Instrumentation Lab	
3	Credits	2	
4	Contact Hours	0-0-4	
	(L-T-P)		
	Course Status	Compulsory/Elective	
5	Course	• To understand the basic concepts of Lab VIEW.	
	Objective	• To build VI using Lab VIEW.	
		• To acquire data using data acquisition card.	
		• To build real time applications using Lab VIEW.	
6	Course	CO1: To implement simple arithmetic and Boolean systems	s using Lab
	Outcomes	VIEW.	-
		CO2: To create VI using arrays.	
		CO3: To build VI using clusters operations of LabVIEW.	
		CO4: To acquire and generate a signal using DAQ cards.	
		CO5: To develop real time application of a VI.	
7	Course	CO6: Able to build VI for simulated and real time application	ons.
		the Lab VIEW platform for the designing of VI. This cours the use of loops, arrays, clusters and various programming Lab VIEW for building the Virtual instruments.	
8	Outline syllabus		CO Mapping
0	Unit 2	Practical related to	CO1
		1. To study various types of Boolean controls and	
		Indicators. Also study various Boolean programming	
		functions available in function palate.	
		2. Create a VI to compute the Boolean expression (A*B)	
		+(C*D*E).	
		3. Create a front panel and block diagram to implement	
		half ladder and full adder.	
		4. To study various types of numeric controls and	
		indicators and numeric programming functions available	
		in function palate.	
		5. Create the front panel and block diagram of VI to show	
		the trigonometric values Of sine and cosine of a given	
	Unit 3	angle in degrees. Practical related to	CO2
		6. Create a VI to create 2D numeric arrays & add them.	
		7. Create a VI consisting of two clusters of LEDs Perform	
		the AND operation between the clusters and display the	
	1	and raise operation between the elusions and display the	

	· · ·	<i>(</i> 1 1 <i>i</i>		k.	Beyond			
		'I using clus e, age, statu	s of LEDs. ster to display in is, marks. Use B					
Unit 4	Practical rel	lated to			CO4			
	volts in steps using a DAQ 10. Create a using USB60	s of 0.5 volt card. VI to acqui: 008. Also ex	e voltage output s. View the sam re an analog sign stract the inform meters and frequ	e on the CRO nal from a source ation related to				
Unit 5	Practical rel		CO5					
	temperature 12. Design a 13. Design a	 Create a VI to acquire an analog signal of LM35 temperature sensor on a DAQ signal accessory Design a Virtual Resistance Meter. Design a Virtual Sinusoidal Voltage Source. Design a Virtual CRO. 						
Mode of examination	Jury/Practica							
Weightage	СА	MTE	ETE					
Distribution	60%	0%	40%					
Text book/s*	1.Jovitha Jerome, "Virtual Instrumentation and LABVIEW", PHI Learning							
Other References	2. Technical Manuals for DAQ Modules, Advantech and National Instruments							
		ER MANUAL	m/pdf/manuals/3	76445b.pdf				

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO 008.1	1	2	2	2	2	1	1	2	1	2	-	2	2	2	1
CO008.2	3	2	1	2	3	1	2	2	1	1	-	2	2	2	2
CO008.3	3	2	3	2	3	2	2	2	1	2	-	2	2	2	2
CO008.4	2	2	2	2	1	2	2	2	2	2	-	3	3	2	2
CO008.5	2	3	3	2	2	2	2	2	2	2	-	3	3	2	2
CO008.6	2	3	3	2	3	2	2	2	2	3	2	3	3	2	3